

# Apogee Air & Land Series

## ULTIMATE ACCURACY MEMS Inertial Navigation System



ITAR  
Free

0.005°  
RMS

INS  
MRU  
AHRS



Motion Sensing  
& Georeferencing



**APOGEE SERIES** makes high accuracy affordable for all surveying companies. On the fields of hydrography, mobile mapping, or remote sensing, the Apogee joins robustness, simplicity to high performance.



# HIGH QUALITY HIGH ACCURACY

SBG SYSTEMS manufactures high quality, high accuracy inertial navigation systems from the design to the production. The Apogee benefits from our high level of expertise in integrated design, IMU calibration, testing, and filtering.



## Highly Accurate



### ATTITUDE AND POSITION - AEROSPACE APPLICATIONS

	GNSS L1/L2/L5	RTK*	PPK**
Roll/Pitch	0.01°	0.008°	0.005°
Heading - Dual antenna (2m baseline)	0.03°	0.03°	0.015°
Heading - Dual antenna (4m baseline)	0.015°	0.015°	0.015°
Position (X/Y)	1.0 m	0.01 m	< 0.01 m
Altitude (Z)	1.0 m	0.03 m	< 0.02 m

### ATTITUDE AND POSITION - LAND APPLICATIONS\*\*\*

	GNSS L1/L2/L5	RTK*	PPK**	RTK 60 sec outage	PPK 60 sec outage
Roll/Pitch	0.01°	0.008°	0.005°	0.012°	0.008°
Heading - Single antenna	0.03°	0.03°	0.02°	0.06°	0.025°
Position (X/Y)	1.0 m	0.01 m	< 0.01 m	0.5 m	0.3 m
Altitude (Z)	1.0 m	0.03 m	< 0.02 m	0.1 m	0.05 m

\*Real Time Kinematic

\*\* Post-processing Kinematic

\*\*\*With odometer aiding

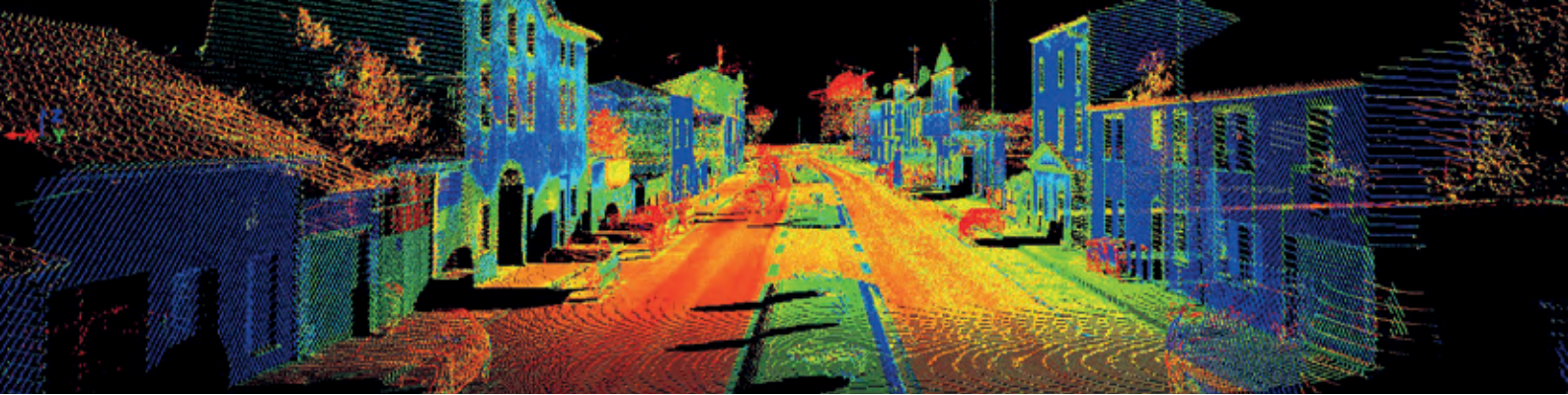
RMS values for typical survey trajectories

Performance may be affected by atmospheric conditions, signal multipath, and satellite geometry.

All specifications subject to change without notice.







## Precise Trajectory & Direct Georeferencing

ACCURATE TRAJECTORY  
DURING GNSS OUTAGES

VERY LOW NOISE GYROSCOPES

LATEST GENERATION OF  
TRI-FREQUENCY GNSS RECEIVER

INTERNAL 8 GB DATA RECORDER

### LAND MOBILE MAPPING

Robust position in urban canyons, forest, tunnels thanks to:

- » Continuous fusion with Inertial and odometer data
- » Real time and off-line RTK corrections
- » Post-processing software
- » Tight GNSS integration for optimal position in multipath environments

### AERIAL SURVEY

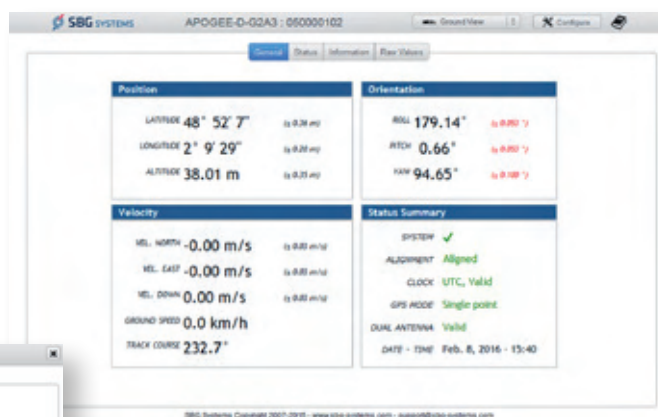
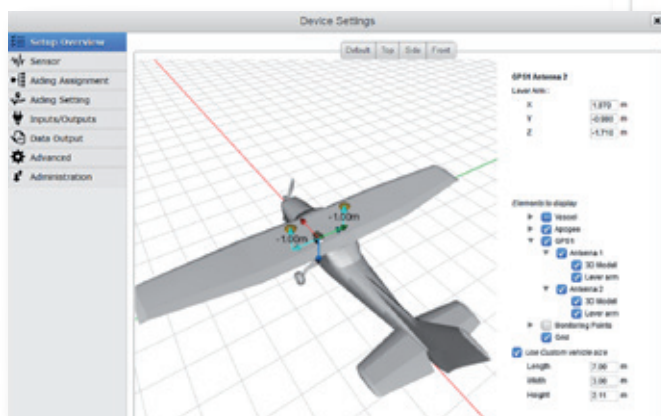
High accuracy real-time external orientation and direct georeferencing thanks to:

- » RTK or OmniSTAR corrections
- » Low latency (3 ms)
- » High resistance to vibrations (can be used on helicopter)
- » Post-processing software

## Modern and Easy-to-use Inertial Sensors

### WEB INTERFACE

Connect your sensor and configure it throughout the intuitive web interface.

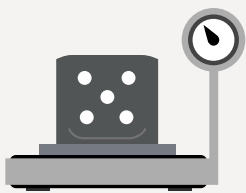


### 3D VIEW

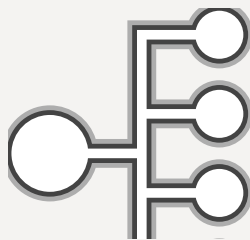
The new 3D View helps you to check your mechanical installation, especially your sensor position, your alignments, and lever arms.



## Easy Integration, Precise Synchronization



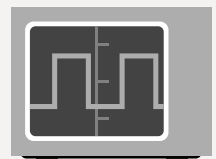
COMPACT,  
LIGHTWEIGHT &  
LOW POWER



ETHERNET,  
RS-232, RS-422, CAN  
PROTOCOLS



ACCURATE UTC TIME  
STAMPING (1  $\mu$ s)



UP TO 5 EVENT  
INPUT MARKERS

### WHY MEMS TECHNOLOGY?

- » Low-power consumption
- » Cost-effective

- » Highly Robust
- » Compact and Light-weight

## Versatile Product Line



Model	Apogee-E Externally-aided INS	Apogee-D INS/GNSS
Roll, Pitch, Heading	●	●
Navigation	●	●
GNSS receiver	Connect to any external survey-grade GNSS receiver	Single or Dual Antenna L1/L2/L5 GPS + GLONASS, GALILEO, BEIDOU
Omnistar		○
RTK		●
Post-processing (raw data)**		●
External Aiding	Up to two external GNSS receivers, Odometer (DMI)	

\*Subscription available from third party PPP service provider

\*\*Raw data are compatible with Qinetia post-processing software

All trademarks are property of their respective owners.  
All specifications subject to change without notice.

● Standard ○ Option





### CONTINUOUS POSITION

Continuous fusion of inertial data with GNSS information stabilizes the position output, effectively eliminating the impact of multipath and signal outages, when the vehicle is passing in dense urban areas for example.

## Specifications

All parameters apply to -20 to 60°C temperature range, unless otherwise stated. Full specifications can be found in the Apogee Hardware Manual available upon request.

### PHYSICAL CHARACTERISTICS

Model	Apogee-E	Apogee-D
Weight	< 690 grams 1.52 pounds	< 900 grams 1.98 pounds
Dimensions (L x W x H)	130 x 100 x 58 mm 5.12 x 3.94 x 2.28 "	130 x 100 x 75 mm 5.12 x 3.94 x 2.95 "
Consumption	< 3 W	< 5 W Single antenna < 7 W Dual antenna
Supply	9 to 36 VDC	9 to 36 VDC

### ENVIRONMENTAL

IP rating Apogee- A/D/E	IP68 (Aluminium)
Specified temperature	-20 to 60 °C / -4 to 140 °F
Operating temperature	-40 to 71 °C / -40 to 160 °F
MTBF (computed)	50,000 hours
Operating vibrations	20 Hz to 2 kHz as per MIL-STD-810G Accelerometer 10 g: 8 g RMS

All specifications subject to change without notice.

### INTERFACE

Aiding (input)	2x GNSS, RTCM, Odometer
Protocols	Output: NMEA, ASCII, Binary, TSS, Simrad Input: NMEA, Trimble, Novatel, Septentrio, Hemisphere, veripos, Fugro, PDO, PD6
Output rate	0.1 to 200 Hz
Logging Capacity	8 GB or 48 h @ 200 Hz
Serial RS-232/422	Model D - 2 outputs / 4 inputs Model A/E - 3 outputs / 5 inputs
Ethernet	Full Duplex (10/100 base-T)
CAN	1 CAN 2.0 A/B bus up to 1 Mbit/s
Pulses	Inputs: PPS, Event marker up to 1 kHz Outputs: SyncOut, Trigger, PPS 5 inputs / 2 outputs

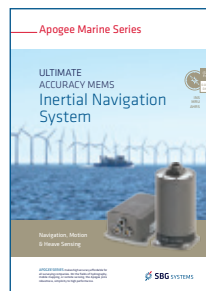
### SENSOR PERFORMANCE

	Accelerometers	Cyroscopes
Measurement range	10 g	200 °/s
Bias in-run instability	< 15 µg	< 0.08 °/hr
Random walk	< 75 µg/√Hz	< 0.012 °/√hr



SBG Systems is a leading supplier of MEMS-based inertial motion sensing solutions. The company provides a wide range of inertial solutions from miniature to high accuracy. Combined with cutting-edge calibration techniques and advanced embedded algorithms, SBG Systems products are ideal solutions for industrial & research projects such as unmanned vehicle control, surveying applications, antenna tracking, and camera stabilization.

## PRODUCTS



Apogee Marine



Ekinox Series



Qinertia

## VIDEO



Apogee Series

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[www.sbg-systems.com](http://www.sbg-systems.com)

# Ellipse Series

## MINIATURE HIGH PERFORMANCE Inertial Sensors



3<sup>rd</sup>  
GENERATION

0.05°  
RMS

ITAR  
Free

IMU  
AHRS  
MRU  
INS  
VG



Navigation, Motion  
& Heave Sensing



ELLIPSE SERIES sets up new standard for miniature and cost-effective inertial systems with an extremely rugged design, cutting-edge sensors, enhanced capabilities, and advanced algorithms.





# Ellipse Series - High-end Technology in the Smallest Package

**Robust L1/L2 RTK**  
with no extra charge

**New 64bit processor**  
for maximum performance

**Best performance and SWaP** of its category

**OEM version** when size and cost matters

**Easy integration**

Get more out of your Ellipse with Qinertia Post-processing software (INS)



Ellipse Series is a successful line of industrial-grade inertial sensors known for their high level of robustness. This 3<sup>rd</sup> generation embeds a 64Bit microprocessor running latest generation algorithms. All the INS/ GNSS are now provided with multi-band RTK receiver for centimetric position and more accurate orientation.

## Product Line

Robust Heading within seconds  
Immune to magnetic disturbances  
Very short baseline down to 50 cm



Ellipse-A



Ellipse-E



Ellipse-N



Ellipse-D

	Ellipse-A	Ellipse-E	Ellipse-N	Ellipse-D
Application	Motion Sensor	INS with your own GNSS receiver	INS for dynamic and automotive applications	INS for low dynamics and robust heading
Heading	Magnetic	Magnetic or GNSS	Magnetic or Mono-antenna GNSS	Dual antenna GNSS
Heave: 5 cm or 5%	●	●	●	●
Odometer aiding		Pulse / CAN OBD-II	Pulse / CAN OBD-II	Pulse / CAN OBD-II
Navigation		Navigation with external GNSS receiver	L1/L2 GNSS receiver 1 cm RTK GNSS Accuracy	L1/L2 GNSS receiver 1 cm RTK GNSS Accuracy
Post-Processing		●	●	●

Motion & Heave Monitoring



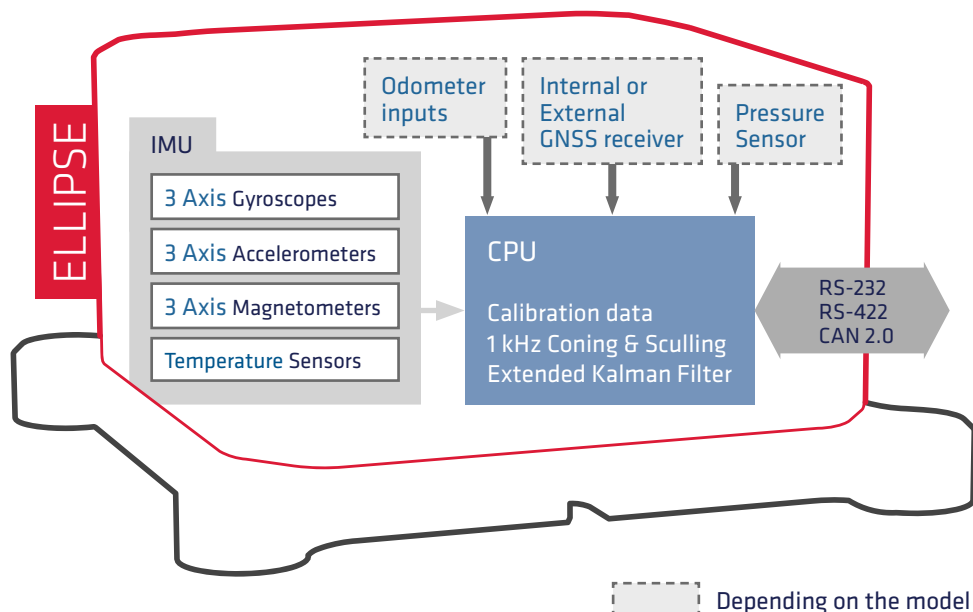
Data Georeferencing



Payload Orientation & Positioning



## Features Inherited from High End INS/GNSS



2-year  
Warranty



No Export  
Restriction



Drivers for:

ROS

PX4  
autopilot

### Best-in-class IMU

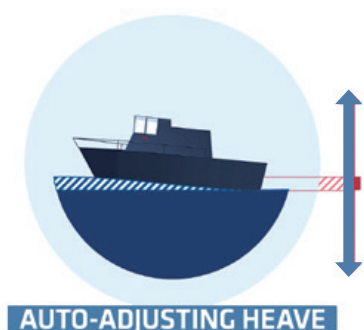
- » Industrial grade MEMS, superior vibration rejection
- » Extensive test and calibration from -40 to 85°C with individual calibration report
- » Integrated hard & soft magnetic disturbances calibration tools

### Advanced Algorithms

- » Real-time fusion of inertial with aiding sensors (GNSS, RTK, DMI, DVL, etc.)
- » Robust position with invalid GNSS measurements detection and RAIM

### Easy Integration

- » Select your motion profile to automatically adjust Kalman filter and dynamic constraints for optimal performance
- » Automatic lever arm estimation (Enter rough lever arms, Ellipse will refine them automatically)



### High Accuracy Heave

Ellipse Marine version delivers a 5-cm accurate heave which automatically adjusts to the wave period.

Ellipse is a cost-effective alternative solution for instrumented buoys, helideck, or boat motion monitoring applications.

Autonomous Navigation



Orientation



Pointing & Stabilization



# All you need to quickly get started



## Development Kit

The Development kit comes with your first Ellipse. It contains:

- » Your Ellipse sensor calibration report
- » A Quick start guide
- » All required accessories depending on the chosen model (USB cable, Antenna(s), Development boards)

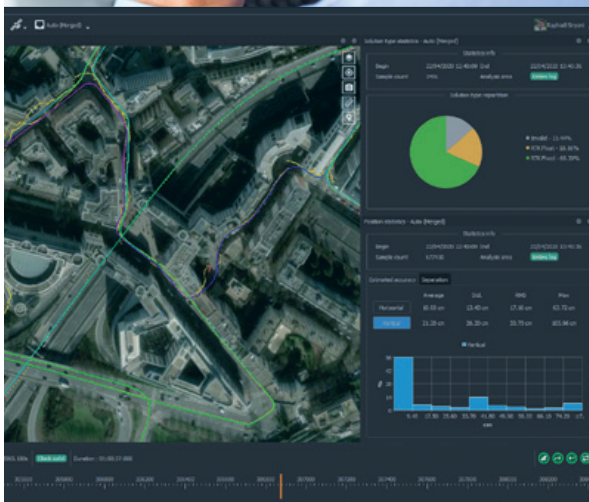
The SDK contains the sbgcenter which allows visualization, configuration, analysis, and export to Excel, Matlab, Google Earth formats as well as code examples for easy integration.



## Services

As expert of inertial navigation, we are at your side, helping you to get the most of your sensor:

- » Free technical support by phone and email
- » Unlimited firmware updates
- » Dedicated support platform (Knowledge center, documentation, etc.)
- » Custom remote initiation or on-site training on demand



## Qinertia

Get more with your Ellipse INS using Qinertia (in option):

- » Detailed analysis after the mission
- » Replay the sensor data with different configuration
- » Refine the mechanical installation (GNSS lever arm) to the centimeter level for improved real time behavior
- » Reach ultimate sensors performance using Forward/Backward/Merge processing

### Dynamics Analysis



### Navigation



### Autonomous Industrial Vehicles





**ACCURACY (RMS)** 360° sensing in all axes, no mounting limitation

Model	A	E <sup>(1)</sup> / N / D
Roll / Pitch	0.1°	0.1° SP 0.05° RTK 0.03° PPK <sup>(4)</sup>
Heading	0.8° Magnetic <sup>(2)</sup>	0.2° Dual antenna 2m 0.2° Single antenna with dynamics 0.1° PPK <sup>(4)</sup>
Velocity <sup>(3)</sup>	-	0.03 m/s
Navigation <sup>(3)</sup>	-	1.2 m Single Point 1 m SBAS 1 cm RTK / PPK <sup>(3)</sup> + 1 ppm
Heave accuracy	5 cm or 5% - Valid for Marine version	
Heave period	Up to 15 s - Automatically adjusts to the wave period	









<sup>(1)</sup> With Supported GNSS receiver<sup>(3)</sup> Under good GNSS availability<sup>(2)</sup> Under homogenous magnetic field<sup>(4)</sup> Optional PPK = Post-processing Kinematic**INTERFACES**

Available data	Euler angles, quaternion, velocity, position, heave, calibrated sensor data, delta angles & velocity, barometric data, status, GPS data, UTC time, GNSS raw data (Post-processing), etc.
Aiding sensors	GNSS, Odometer, RTCM
Output rate	200 Hz, 1,000 Hz (IMU data)
Main Serial Interface	RS-232, RS-422, USB - up to 921,600 bps
Serial protocols	Binary eCom, NMEA, ASCII, TSS
CAN interface	CAN 2.0A/B - up to 1 Mbit/s
Pulses	Inputs: Events, PPS, DMI (Direction or quadrature) Outputs: Synchronization (PPS) Model A/N/D: 2 inputs / 1 output Model E: 4 inputs / 2 outputs

**SENSORS**

	Accelerometers	Gyroscopes	Magnetometers
Gain stability	1000 ppm	500 ppm	< 0.5 %
Non-linearity	1500 ppm	50 ppm	< 0.1 % FS
Bias stability	± 5 mg	± 0.2 °/s	± 1 mGauss
Random walk Noise density	57 µg/√Hz	0.15 °/√hr	3 mGauss
Bias in-run instability <sup>(1)</sup>	14 µg	7 °/h	1.5 mGauss
VRE	50 µg/g <sup>2</sup> RMS	1 °/h/g <sup>2</sup> RMS	-
Alignment error	< 0.05 °	< 0.05 °	< 0.1 °
Bandwidth	390 Hz	133 Hz	22 Hz

<sup>(1)</sup> Allan Variance, @ 25 °C**MECHANICAL**Box version are IP68, resistant to dust and water.  
OEM version are PCB mounted for tight integration.

Model	A	E	N	D
Box				
Size	46 x 45 x 24 mm	46 x 45 x 24 mm	46 x 45 x 24 mm	46 x 45 x 32 mm
Weight	45 g	47 g	49 g	65 g
OEM				
Size	29.5 x 25.5 x 11 mm	29.5 x 25.5 x 11 mm	29.5 x 25.5 x 16 mm	29.5 x 25.5 x 16 mm
Weight	8 g	8 g	17 g	17 g

All parameters apply to full specified temperature range, unless otherwise stated. Full specifications can be found in the Ellipse Hardware Manual available upon request.

**ORDERING INFORMATION**

Pick one of each category

**MODEL**

A: AHR5

E: Externally Aided INS

N: INS with integrated RTK GNSS

D: INS with dual antenna RTK GNSS

**VERSION**

Marine: 8 g – 450°/s

Land Air: 20 g – 450°/s

High Dynamics: 40 g – 1000°/s

**PACKAGE**

BOX RS-232 / 422

BOX RS-232 / CAN

OEM TTL

**INTERNAL GNSS (N & D MODELS)**

Features	SBAS, RTK, RAW
Signals	GPS: L1C/A, L2C GLONASS: L10F, L20F GALILEO: E1, E5b, BEIDOU: B1/B2
Update rate	5 Hz
Cold start / Hot start	< 24 s / < 2 s

**PRESSURE SENSOR (models E/N/D)**

Resolution	1.2 Pa / 10 cm / 0.3 ft
Pressure accuracy	± 50 Pa / ± 200 Pa Relative / Absolute

**ELECTRICAL & ENVIRONMENTAL**

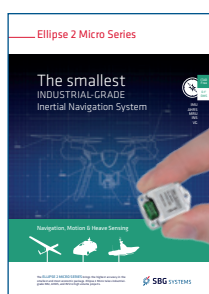
Input voltage	5 - 36 V
Power consumption	A/E: < 300 mW N <sup>(1)</sup> : < 600 mW D <sup>(1)</sup> : < 900 mW
Specified temperature	-40 to 85 °C
Shock limit	2,000 g
Operating vibration	8 g RMS (20 Hz to 2 k Hz per MIL-STD 810G)
MTBF	50,000 hours

<sup>(1)</sup> Without GNSS antenna

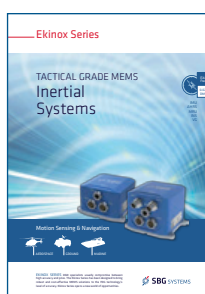


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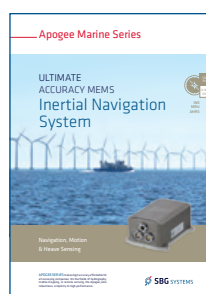
## PRODUCT LINES



Ellipse Micro



Ekinox Series



Apogee Series

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# Navsight Land & Air Solution

## Motion & Navigation Solution FOR SURVEYING APPLICATIONS



Motion, Navigation, and Geo-referencing

NAVSIGHT LAND/AIR SOLUTION is a full high performance inertial navigation solution designed to make surveyors' mobile data collection easier, whether it is terrestrial or aerial.





# Reliable Trajectory IN EVERY CONDITION

Navsight Land/Air Solution is an extremely versatile solution. It consists in an Inertial Measurement Unit available at three different performance levels, and connected to Navsight, a rugged equipment embedding the fusion intelligence, the GNSS receiver, and all connections to external equipment such as LiDAR, cameras, computer, etc.

## Navsight Processing Unit - Data Fusion and GNSS



Navsight Processing Unit with embedded GPS/GNSS

- » Tri-frequency receiver
- » Multi-constellations
- » RTK
- » PPP ready
- » Internal logger for Post-processing
- » One or two antennas

Navsight can also be used with your own GNSS receiver

## Inertial Measurement Unit (IMU) - Several Levels of Accuracy



**Ekinox IMU**  
Compact & Economical



**Apogee IMU**  
Good Perf/Price Ratio



**Horizon IMU**  
High Accuracy FOG IMU

	Ekinox IMU Compact & Economical	Apogee IMU Good Perf/Price Ratio	Horizon IMU High Accuracy FOG IMU
Roll/Pitch	0.015°	0.005°	0.004°
Heading Land	0.03°	0.02°	0.008°
Heading Air	0.03°*	0.015°*	0.008°
Position Horizontal	1cm+1ppm	1cm+1ppm	1cm+1ppm

Post-processing Accuracy

\* Dual antenna heading, 2m baseline.



**Continuous Position** Continuous fusion of inertial data with GNSS information stabilizes the position output, effectively eliminating the impact of multipath and signal outages, when the vehicle is passing in dense urban areas for example.



### ROBUST AND SMOOTH TRAJECTORY

Navsight fuses inertial and GNSS data to offer a robust and smooth trajectory at a high frequency (200 Hz).



### MAXIMIZED SIGNAL AVAILABILITY

Four constellations can be used simultaneously to benefit from more satellites and so, more signal availability.



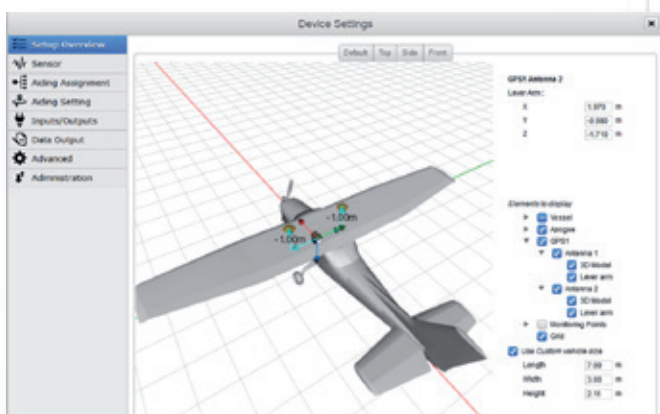
### ODOMETER AIDING

Navsight fuses inertial, gnss, and odometer data for an even better performance in harsh conditions.

## Modern and Easy-to-use Interface

### WEB INTERFACE

Connect your sensor and configure it throughout the intuitive web interface.



### 3D VIEW

The new 3D View helps you to check your mechanical installation, especially your sensor position, your alignments, and lever arms.





## SBG⊕SERVICES

**NO Surprise!** Navsight solution is based on proven and maintenance-free technologies. Technical assistance is free of charge and firmware upgrades are available during the life of the product without extra cost to secure your day to day operations.



Take advantage of our SBG⊕Services:

### + Warranty Extension

All SBG inertial sensors come with a 2-year warranty. This warranty can be extended up to 5 years. Secure your budget during 3, 4, or 5 years.

### + Check & Calibration

The Check & Calibration service includes a quality check, a firmware update, cleaning, and if required, a calibration in temperature and dynamics. A certificate is delivered with the sensor. It guarantees the quality of the sensor data during 3 years.

### + Back-up System

The back-up system consists in a complete inertial system set delivered in replacement of your sensor during repair operations and during the « check and calibration » service. This service is included into the PREMIUM and ELITE packages.

## INS/GNSS Post-processing Software

Qinertia is the SBG Systems' in-house post-processing software. This full-featured software enhances SBG inertial navigation systems performance by post processing inertial data with raw GNSS observables.

### The Fastest Processing

### Tight Coupling INS/GNSS fusion

### Modern & Intuitive User Interface

### + 7,000 Base Stations always up-to-date



**Why Post-processing ?** By processing all your INS and GNSS raw data forward and backward, Qinertia PPK software greatly increases accuracy, solves GNSS outages, installation errors, etc. Qinertia can save your survey, or allow you to survey in very complicated areas.



# Specifications

All parameters apply to -20 to 60°C temperature range, unless otherwise stated.

Full specifications can be found in the Navsight Hardware Manual available upon request.

## 1. CHOOSE YOUR IMU

				OEM Version Available 
IMU	Ekinox-I Surface	Apogee-I Surface	Horizon-I Surface Enclosure	
size	86 x 100 x 58 mm	130 x 100 x 58 mm	94 x 94 x 177 mm	
Weight	425 g	635 g	1.32 kg	
Rating	IP68	IP68	IP68	

### EKINOX

	Single Point	RTK	PPK	Land RTK Outage (60 s)	PPK Outage (60 s)
Roll, Pitch	0.03 °	0.02 °	0.015 °	0.1 °	0.03 °
Heading (Land)	0.08 °	0.06 °	0.03 °	0.2 °	0.05 °
Heading (Air), Dual antenna 2m   4m	0.08°   0.05°	0.08°   0.05°	0.03°	-	-
Position Horizontal	1.2m	1 cm + 1 ppm	1 cm + 1 ppm	3 m	0.4 m

### APOGEE

	Single Point	RTK	PPK	Land RTK Outage (60 s)	PPK Outage (60 s)
Roll, Pitch	0.01 °	0.01 °	0.005 °	0.012 °	0.008 °
Heading (Land)	0.03 °	0.03 °	0.02 °	0.06 °	0.025 °
Heading (Air), Dual antenna 2m   4m	0.03°   0.015°	0.03°   0.015°	0.015°	-	-
Position Horizontal	1.2 m	1 cm + 1 ppm	1 cm + 1 ppm	0.5 m	0.1 m

### HORIZON

	Single Point	RTK	PPK	Land RTK Outage (60 s)	PPK Outage (60 s)
Roll, Pitch	0.007 °	0.007 °	0.004 °	0.01 °	0.005 °
Heading (Land)	0.01 °	0.01 °	0.008 °	0.015 °	0.01 °
Heading (Air) Single   Dual antenna	0.04 ° / 0.01 ° *	0.04 ° / 0.01 ° *	0.008 °	-	-
Position Horizontal	1.2 m	1 cm + 1 ppm	1 cm + 1 ppm	0.30 m	0.05 m

\* 4m baseline

## 2. CHOOSE YOUR PROCESSING UNIT FUNCTIONALITIES

Navigation with External GNSS Receiver

INTERFACES

Aiding Sensors (input)

2X GNSS, RTCM

Protocols

Output: NMEA, ASCII, Binary, TSS, Simrad  
Input: NMEA, Trimble, Novatel, Septentrio, Hemisphere, Fugro, PDO, PD6

Logging Capacity

8 GB ≈ 48h, 200 Hz

Ports/Communication

5x RS-232/RS-422 Tx/Rx ports

Synchronization

2x Sync Out (PPS) + 5x Sync In signals

Ethernet

5 virtual serial ports  
5x UDP / TCP bidirectional ports  
Web interface , FTP

Navigation with Embedded GNSS Receiver

Constellations

☒

GPS & Glonass

☒

Galileo

☒

Beidou

Positioning

☒

L1/L2/L5

☒

RTK

☒

Raw

PPP Ready

☐

Omnistar

☒

Included

NAVSIGHT PHYSICALS & ENVIRONMENTALS

Size

227 x 156 x 63 mm

Weight

1.9 kg

Wide input voltage range (isolated)

9 – 36V

EN-60945 compliant

Isolated Interfaces and power supply

Power consumption

<3 W, <7W with GNSS

Operating Temperature

-40 to 75°C

MTBF

50,000 hours

RMS values for typical survey trajectories. Performance depends on velocity aiding accuracy and requires frequent turns. Performance may be affected by atmospheric conditions, signal multipath, and satellite geometry. All specifications subject to change without notice.

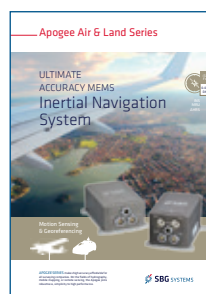


SBG Systems is a leading supplier of MEMS-based inertial motion sensing solutions. The company provides a wide range of inertial solutions from miniature to high accuracy. Combined with cutting-edge calibration techniques and advanced embedded algorithms, SBG Systems products are ideal solutions for industrial & research projects such as unmanned vehicle control, surveying applications, antenna tracking, and camera stabilization.

## PRODUCTS



Qinertia



Apogee Series



Ekinox Series



Ellipse Series

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# Navsight Marine Solution

## Motion & Navigation Solution FOR HYDROGRAPHIC APPLICATIONS



Courtesy of Cadden

### Navigation, Motion & Heave

Extremely easy to set up, and highly versatile, the NAVSIGHT MARINE SOLUTION makes hydrographers' surveying tasks easier on both shallow and deep waters.





# STATE-OF-THE-ART

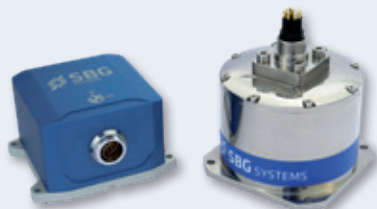
## Navsight Marine Solution

Navsight Marine Solution integrates the latest IMU and GNSS technologies to offer a modern, powerful, and easy-to-use motion and navigation solution for Hydrographers.



### Scalable Performance for Every Application

#### EKINOX GRADE



##### Economic

**Ideal for Shallow Water Applications**

- » 0.02° Roll/Pitch
  - » 0.05 ° Heading
  - » 5 cm Real-time Heave
  - » 2.5 cm Delayed Heave
  - » Up to 1 cm RTK Position
- Low Power Consumption  
Compact, Lightweight

#### APOGEE GRADE



##### Highly Versatile

**Ideal for Challenging Shallow to Deep Water Applications**

- » 0.008° Roll/Pitch
  - » 0.015 ° Heading
  - » 5 cm Real-time Heave
  - » 2 cm Delayed Heave
  - » Up to 1 cm RTK Position
- Amazing performance under  
GNSS Outage

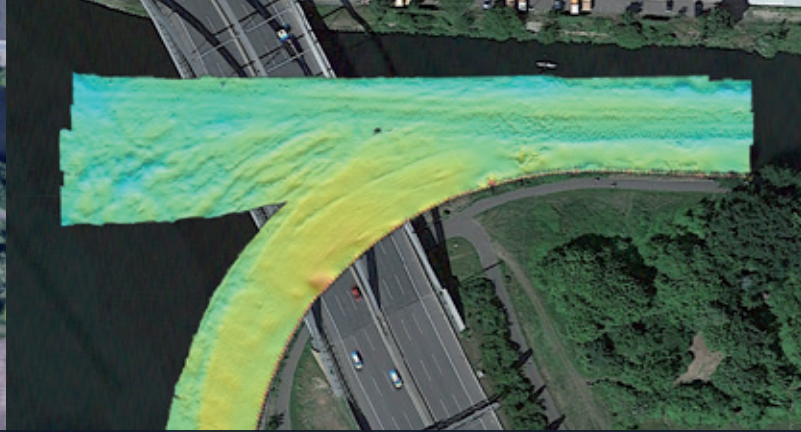
#### HORIZON GRADE



##### FOG Technology

**Large vessels with low Dynamics and Harsh Conditions**

- » 0.007° Roll/Pitch
  - » 0.01 ° Heading
  - » 5 cm Real-time Heave
  - » 2 cm Delayed Heave
  - » Up to 1 cm RTK Position
- Very Low Drift  
Single antenna Heading Capable



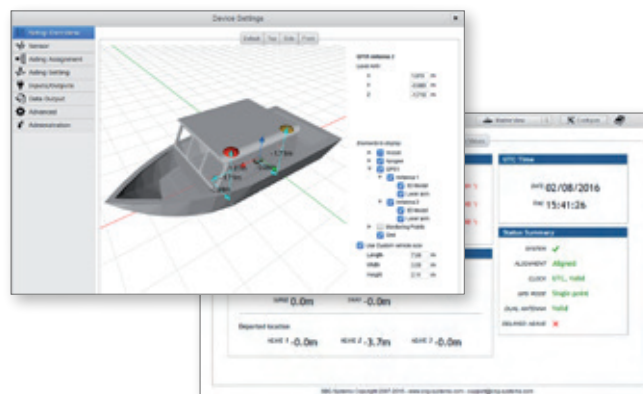
Charting under bridges with the Apogee sensor. The vessel «Spreegrund», property of WSA Berlin, has been equipped by MBT, part of MacArtney group.

**MRU or INS?** Inertial Navigation Systems greatly improves navigation data in all conditions. Position information are fused in real-time with inertial data to provide a robust trajectory when GNSS outages occur (crossing a bridge, surveying a river near several mountains, etc.). In this example, the Apogee sensor is connected to an external GNSS receiver and a DVL for even better performance.

## Configuration Made Easy

The interactive web interface helps you configuring the solution and checking in real-time your mechanical installation, especially your sensor position, your alignments, and GNSS main lever arm (the secondary lever arm is automatically calculated).

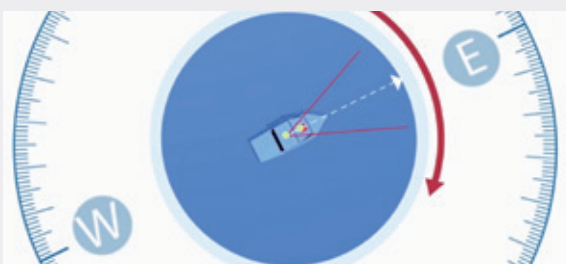
All configuration settings are then stored for further surveys.



Main Drivers available for



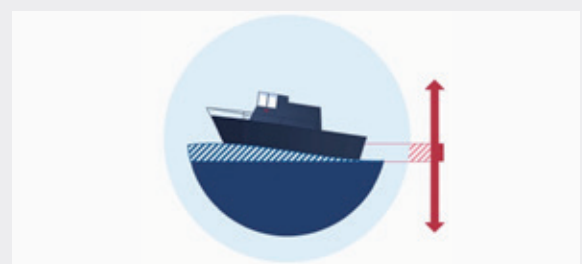
## Fast Initialization with GNSS-based Dual-Antenna Heading



Dual antenna GNSS provides accurate heading with fast initialization time, even if the vessel is mooring.

Additionally, it is not subject to latitude scaling faced by gyro-compass technology.

## Accurate Data in Rough Sea with Delayed Heave



When wave frequency is erratic or in case of long period swell, the delayed heave feature can save the day by allowing survey in rough conditions.

This specific algorithm allows a more extensive calculation, resulting in a heave accurate to 2 cm computed in real-time with a little delay.



# A Full Solution for Hydrographic Applications

## INS/GNSS Post-processing Software

Qinertia is the SBG Systems' in-house post-processing software. This full-featured software enhances SBG inertial navigation systems performance by post processing inertial data with raw GNSS observables.

### The Fastest Processing

### Tight Coupling INS/GNSS fusion

### Modern & Intuitive User Interface

+ 7,000 Base Stations always up-to-date



**Why Post-processing ?** By processing all your INS and GNSS raw data forward and backward, Qinertia PPK software greatly increases accuracy, solves GNSS outages, installation errors, etc. Qinertia can save your survey, or allow you to survey in very complicated areas.

## SBG⊕SERVICES

**NO Surprise!** Navsight solution is based on proven and maintenance-free technologies. Technical assistance is free of charge and firmware upgrades are available during the life of the product without extra cost to secure your day to day operations.

Take advantage of our SBG⊕Services:



### + Warranty Extension

All SBG inertial sensors come with a 2-year warranty. This warranty can be extended up to 5 years. Secure your budget during 3, 4, or 5 years.

### + Check & Calibration

The Check & Calibration service includes a quality check, a firmware update, cleaning, and if required, a calibration in temperature and dynamics. A certificate is delivered with the sensor. It guarantees the quality of the sensor data during 3 years.

### + Back-up System

The back-up system consists in a complete inertial system set delivered in replacement of your sensor during repair operations and during the « check and calibration » service. This service is included into the PREMIUM and ELITE packages.






# Specifications

All parameters apply to -20 to 60°C temperature range, unless otherwise stated.

Full specifications can be found in the Navsight Hardware Manual available upon request.

IHO Compliant

## INERTIAL MEASUREMENT UNIT (IMU)

					
IMU	Ekinox-I Surface	Ekinox-I Subsea Enclosure	Apogee-I Surface	Apogee-I Subsea Enclosure	Horizon-I Surface
Size	86 x 100 x 58 mm	94 x 94 x 112 mm	130 x 100 x 58 mm	94 x 94 x 177 mm	150 x 168 x 215 mm
Weight	425 g	1 kg	635 g	1.32 kg	4.29 kg
Rating	IP68	200 m Depth	IP68	200 m Depth	IP68

OEM Versions available upon request

## EKINOX ACCURACY

	RTK**	PPK***	RTK Outage (30 s)	PPK Outage (30 s)
Roll, Pitch	0.02 °	0.015 °	0.05 °	0.04 °
Heading* - 2 m / 4 m	0.08 ° / 0.05 °	0.03 ° / 0.03 °	0.15 ° / 0.13 °	0.05 ° / 0.05 °
Position (X,Y) / Altitude (Z)	0.01 m / 0.02 m	0.01 m / 0.02 m	3 m / 0.75 m	1 m / 0.3 m

## APOGEE ACCURACY

	RTK**	PPK***	RTK Outage (60 s)	PPK Outage (60 s)
Roll, Pitch	0.008 °	0.005 °	0.012 °	0.008 °
Heading* - 2 m / 4 m	0.03 ° / 0.015 °	0.015 ° / 0.015 °	0.05 ° / 0.04 °	0.025 ° / 0.025 °
Position (X,Y) / Altitude (Z)	0.01 m / 0.02 m	0.01 m / 0.02 m	4 m / 0.75 m	0.15 m / 0.05 m

## HORIZON ACCURACY

	RTK**	PPK***	RTK Outage (60 s)	PPK Outage (60 s)
Roll, Pitch	0.007 °	0.004 °	0.01 °	0.005 °
Heading* - 2 m	0.01 °	0.008 °	0.015 °	0.01 °
Position (X,Y) / Altitude (Z)	0.01 m / 0.02 m	0.01 m / 0.02 m	1 m / 0.5 m	0.1 m / 0.05 m

## HEAVE

	Ekinox	Apogee / Horizon	Wave period	Remarks
Real-time Heave	5 cm	5 cm	up to 20 sec	Automatic adjustment to the sea state
Delayed Heave	2.5 cm	2 cm	up to 40 sec	Internal computation

## VELOCITY AIDED POSITIONING

DVL < 0.2 % Travelled distance

## NAVSIGHT PROCESSING UNIT



Three modes available:

MRU	INS with GNSS	INS + external GNSS
-----	---------------	---------------------

## PHYSICAL & ENVIRONMENTAL

Size (Rugged / Rack)	227 x 156 x 63 mm / 422 x 204 x 44 mm
Weight (Rugged / Rack)	1.9 kg / 1.95 kg
Wide input voltage range (isolated)	9 - 36V
EN-60945 compliant	Isolated Interfaces and power supply
Power consumption	<3 W, <7W with GNSS
Operating Temperature	-40 to 75°C
MTBF	50,000 hours

## INTERFACES

Aiding Sensors (input)	2X GNSS, RTCM, DVL
Protocols	Output: NMEA, ASCII, Binary, TSS, Simrad Input: NMEA, Trimble, Novatel, Septentrio, Hemisphere, Fugro, PDO, PD6
Logging Capacity	8 GB ≈ 48h, 200 Hz
Ports/Communication	5x RS-232/RS-422 Tx/Rx ports
Synchronization	2x Sync Out (PPS) + 5x Sync In signals
Ethernet	5x UDP / TCP bidirectional ports Web interface , FTP

## INTERNAL GNSS

Internal GNSS Receiver	GPS, GLONASS, GALILEO, BEIDOU, L1/L2/L5, RTK, RAW
PPP Ready	PPP Ready Omnistar/Marinestar

\*Baseline, dual antenna \*\*Real Time Kinematic \*\*\*Post-processing Kinematic  
RMS values for typical survey trajectories. Performance depends on velocity aiding accuracy. Performance may be affected by atmospheric conditions, signal multipath, and satellite geometry. All specifications subject to change without notice.

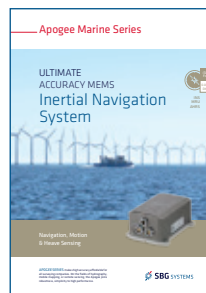


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## PRODUCTS



Qinertia



Apogee Marine



Ekinox Series



Ellipse Series

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[www.sbg-systems.com](http://www.sbg-systems.com)

# Apogee Marine Series

## ULTIMATE ACCURACY MEMS Inertial Navigation System



INS  
MRU  
AHRS



Navigation, Motion  
& Heave Sensing

**APOGEE SERIES** makes high accuracy affordable for all surveying companies. On the fields of hydrography, mobile mapping, or remote sensing, the Apogee joins robustness, simplicity to high performance.





# HIGH QUALITY HIGH ACCURACY

SBG SYSTEMS manufactures high quality, high accuracy inertial navigation systems from the design to the production. The Apogee benefits from our high level of expertise in integrated design, IMU calibration, testing, and filtering.



## Highly Accurate

### ATTITUDE AND POSITION

	GNSS L1/L2/L5	RTK*	PPK**	RTK 60 sec outage	PPK 60 sec outage
Roll/Pitch	0.01°	0.008°	0.005°	0.01°	0.008°
Heading - Dual antenna (2m baseline)	0.03°	0.03°	0.015°	0.05°	0.025°
Heading - Dual antenna (4m baseline)	0.015°	0.015°	0.015°	0.04°	0.02°
Position (X/Y)	0.6 m	0.01 m	< 0.01 m	3 m	0.15 m
Altitude (Z)	1.0 m	0.03 m	< 0.02 m	0.7 m	0.05 m

### Delayed Heave: Accurate Data in Rough Sea

When wave frequency is erratic or in case of long period swell, the delayed heave feature can save the day by allowing survey in rough conditions. This specific algorithm allows a more extensive calculation, resulting in a heave accurate to 2 cm displayed in real-time with a little delay.

### HEAVE

	Accuracy	Wave Period	Remarks
Real-time Heave	5 cm or 5 %	Up to 20 seconds	Automatic adjustment to every sea conditions
Delayed Heave	2 cm or 2 %	Up to 40 seconds	Internal computation

### VELOCITY AIDED POSITIONING

DVL\*\*\* < 0.2 % of Travelled Distance

Driver available for



Others upon request

\*Real Time Kinematic

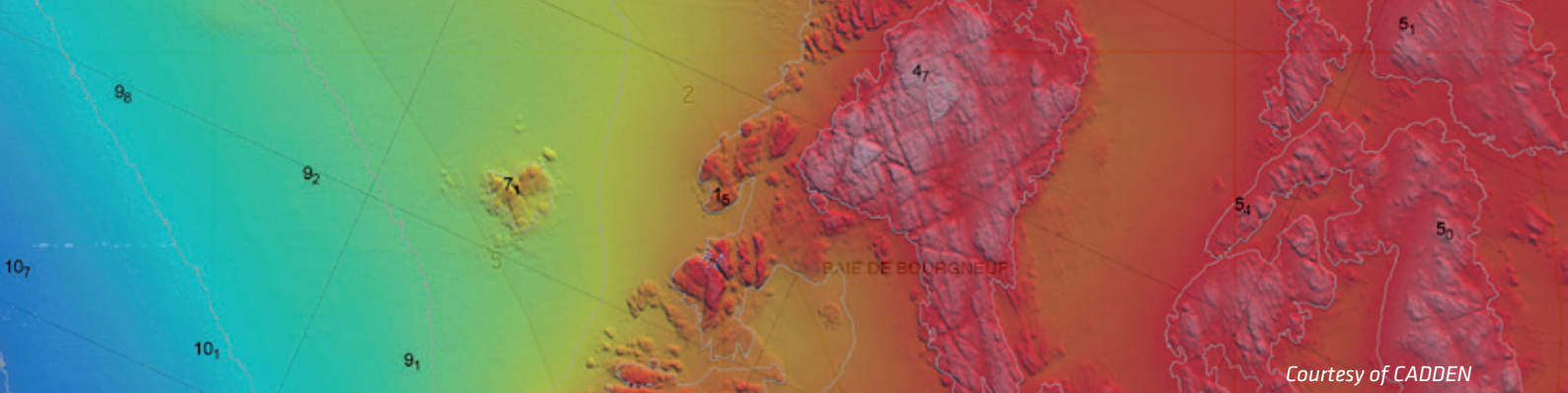
\*\* Post-processing Kinematic

\*\*\*Depends on velocity aiding accuracy

RMS values for typical survey trajectories

Performance may be affected by atmospheric conditions, signal multipath, and satellite geometry.

All specifications subject to change without notice.



## The Highest Accuracy Affordable in Powerful Models



APOGEE-E  
IP68

### FOR ALL HYDROGRAPHIC SURVEYORS

Ideal to mount on the center of gravity of the boat, the Apogee-E connects to any survey grade GNSS receiver for navigation, and aiding equipment such as odometer or DVL.



APOGEE-A  
IP68

### FOR SHIP MOTION MONITORING

Ideal for ship motion monitoring, the Apogee-A is a Motion Reference Unit (MRU). Allowing GNSS\* input, they provide high accuracy roll, pitch, heading, and heave.

*\*Dual Antenna GNSS input for the best performance.*



APOGEE-D  
IP68

### FOR UNMANNED SYSTEMS

Especially fitted for Unmanned Marine Vessels, Apogee-D is a very compact INS with embedded tri-frequency GNSS receiver. It allows RTK and Omnistar/Marinestar corrections.

### WHY MEMS TECHNOLOGY?

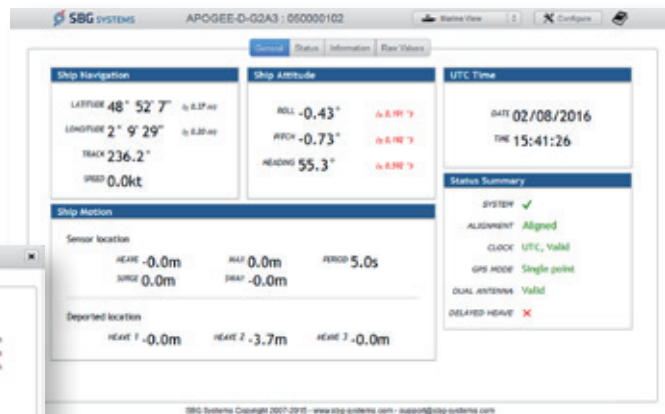
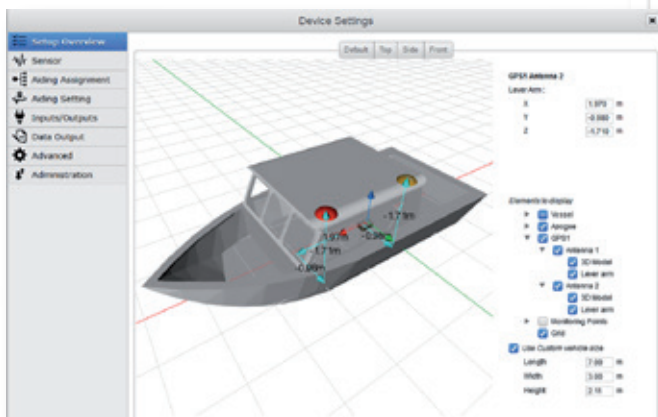
- » Low-power consumption
- » Cost-effective
- » Highly Robust
- » Compact and Light-weight



## Modern and Easy-to-use

### WEB INTERFACE

Connect your sensor and configure it throughout the intuitive web interface.



### 3D VIEW

The new 3D View helps you to check your mechanical installation, especially your sensor position, your alignments, and lever arms.

## INS/GNSS Post-processing Software

Qinertia is the SBG Systems' in-house post-processing software. This full-featured software enhances SBG inertial navigation systems performance by post processing inertial data with raw GNSS observables.

The Fastest Processing

Tight Coupling INS/GNSS fusion

Modern & Intuitive User Interface

+ 7,000 Base Stations always up-to-date



### Why Post-processing ?

By processing all your INS and GNSS raw data forward and backward, Qinertia PPK software greatly increases accuracy, solves GNSS outages, installation errors, etc. Qinertia can save your survey, or allow you to survey in very complicated areas.



# Specifications

All parameters apply to -20 to 60°C temperature range, unless otherwise stated.  
Full specifications can be found in the Apogee User Manual available upon request.

## PHYSICAL CHARACTERISTICS



Model	Apogee-A/E	Apogee-D
Weight	< 690 grams 1.52 pounds	< 900 grams 1.98 pounds
Dimensions (L x W x H)	130 x 100 x 58 mm 5.12 x 3.94 x 2.28 "	130 x 100 x 75 mm 5.12 x 3.94 x 2.95 "
Power Consumption	< 3 W	< 7 W
Supply Voltage	9 to 36 VDC	9 to 36 VDC

## INTERFACE

Aiding Sensors (input)	2x GNSS, RTCM, DVL
Protocols	Output: NMEA, ASCII, Binary, TSS, Simrad Input: NMEA, Trimble, Novatel, Septentrio, Hemisphere, Fugro, PD0, PD6
Output rate	0.1 to 200 Hz
Logging Capacity	8 GB or 48 h @ 200 Hz
Serial RS-232/422	Model D - 2 outputs / 4 inputs Model A/E - 3 outputs / 5 inputs
CAN	1 CAN 2.0 A/B bus up to 1 Mbit/s
Ethernet	Full Duplex (10/100 base-T)

## ENVIRONMENTAL

IP rating Apogee-A/D/E	IP68 (Aluminium)
Specified temperature	-20 to 60 °C / -4 to 140 °F
Operating temperature	-40 to 71 °C / -40 to 160 °F
MTBF (computed)	50,000 hours
Operating vibrations	20 Hz to 2 kHz as per MIL-STD-810G Accelerometer 2 g: 1 g RMS

## SENSOR PERFORMANCE

	Accelerometers	Gyroscopes
Measurement range	2 g	200 °/s
Bias in-run instability	< 2 µg	< 0.08 °/hr
Random walk	< 15 µg/√Hz	< 0.012 °/√hr

Subscription available from third party PPP service provider

RMS values for typical survey trajectories. Performance may be affected by atmospheric conditions, signal multipath, and satellite geometry.



### CONTINUOUS POSITION

Continuous fusion of inertial data with GNSS information stabilizes the position output, effectively eliminating the impact of multipath and signal outages, when the vessel is passing underneath bridges for example.

### ROBUST HEADING

Apogee is 20 to 30 times faster than traditional gyrocompasses to align heading angle. It provides the same quality of data, whatever the latitude is. By fusing GNSS and IMU data, it provides a robust and accurate heading in any conditions.

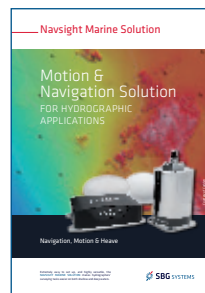


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## PRODUCTS



Ekinox Series



Navsight Marine



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# Ekinox Series

## TACTICAL GRADE MEMS Inertial Systems



ITAR  
Free

0.02°  
RMS

IMU  
AHRS  
MRU  
INS  
VG



### Motion Sensing & Navigation



AEROSPACE



GROUND



MARINE

EKINOX SERIES R&D specialists usually compromise between high accuracy and price. The Ekinox Series has been designed to bring robust and cost-effective MEMS solutions to the FOG technology's level of accuracy. Ekinox Series opens a new world of opportunities.





# Ekinox Series

## Brings robust and cost-effective MEMS to the Tactical Grade

- » High Performance Inertial Systems
- » ITAR Free
- » Cost-effective & Robust MEMS technology
- » Maintenance Free

### KEY FEATURES

- » Up to 4 connected equipment
- » Survey Grade GNSS receiver (Ekinox2-D)
- » 8 GB Data Logger
- » IP68 Enclosure
- » Web Interface & Ethernet
- » 200 Hz Output Rate

Ekinox Series is a product range of high accuracy inertial systems. It has been designed to bring robust, maintenance free, and cost-effective MEMS to the tactical grade. Thanks to a drastic selection of high end MEMS sensors, an advanced calibration procedure, and powerful algorithm design, the Ekinox Series achieves 0.02° attitude accuracy.



## Accuracy

### 3D ORIENTATION

Roll, Pitch	0.03°	GNSS aiding
	0.02°	RTK aiding
	0.015°	Post-Processing
Heading	0.08°	Dual Antenna GNSS (baseline < 2 m)
	0.05°	Dual Antenna GNSS (baseline < 4 m)
	0.03°	Post-Processing

### POSITION

Single Point L1/L2	1.2 m	
SBAS	0.6 m	
DGPS	0.4 m	
RTK	0.01 m	
RTK 30s Outage	3 m	Marine conditions
RTK 60s Outage	0.2% TD	Marine conditions, DVL* aided
	3 m	Automotive mode - With odometer
PPK**	0.02 m	3 m

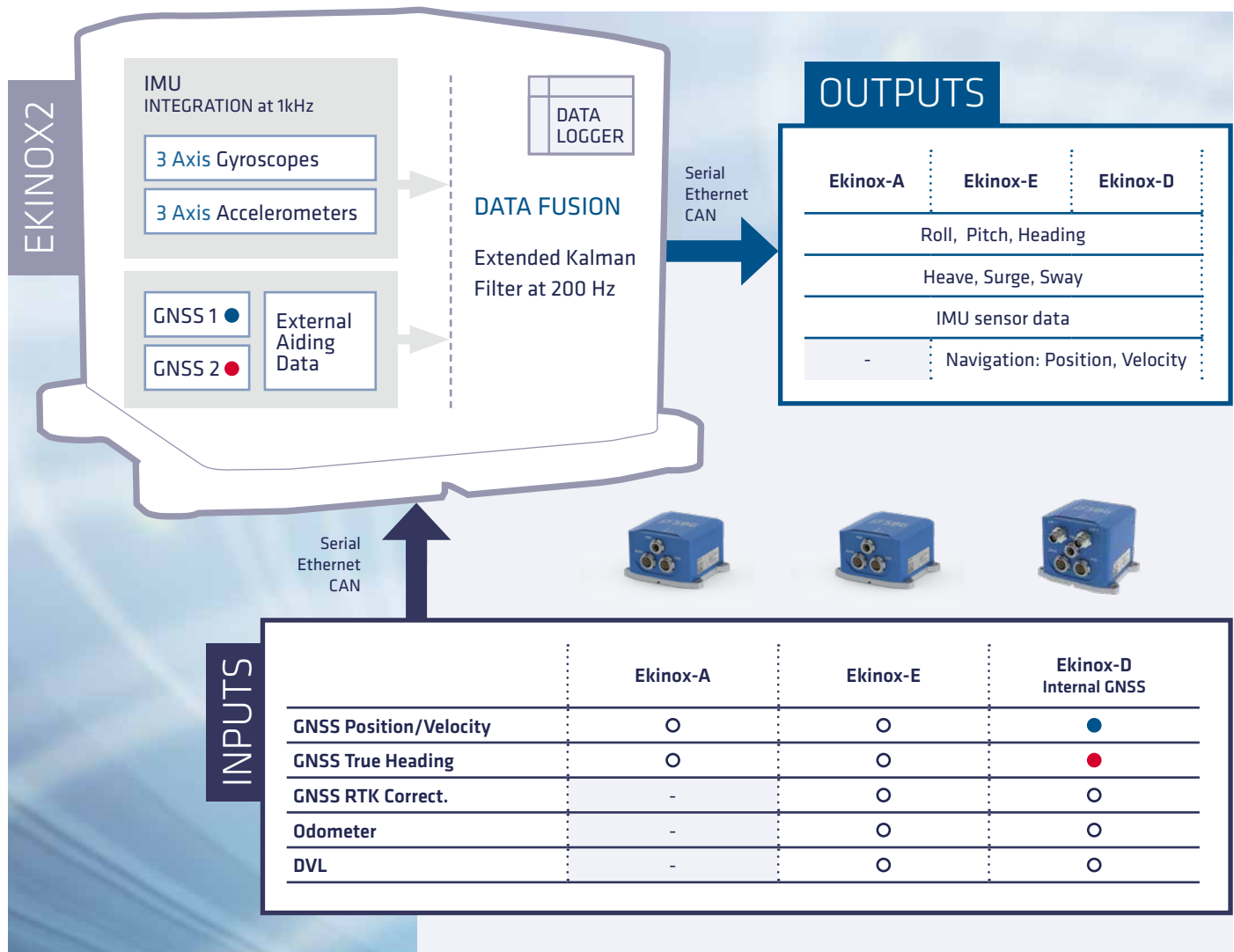
### HEAVE

Real-time	5 cm or 5%	Whichever is greater, velocity aided
Wave period	0 to 20 s	Auto-adjusting
Delayed	2.5 cm or 2.5%	Whichever is greater, velocity aided
Wave period	0 to 40 s	

\* Depends on DVL performance. - TD: Travelled Distance.- Typical RMS values

\*\*Post-processing Kinematic

## A Cutting-Edge Architecture

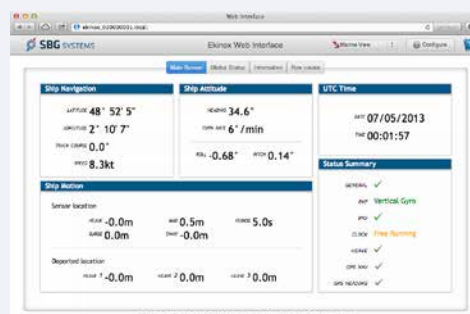


## Software

### CONFIGURATION, REAL-TIME DISPLAY & REPLAY

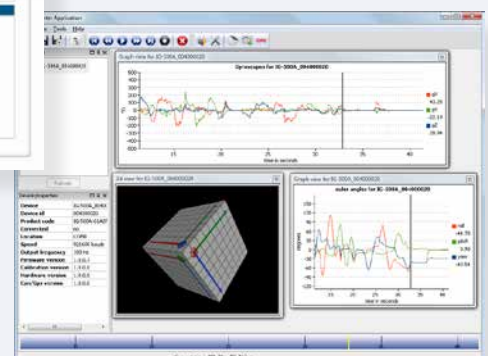
Configuration is made easy through our intuitive embedded web interface where all parameters can be quickly displayed and adjusted.

The sbgCenter offers all the tools for real-time visualization (200 Hz) and replay of the records stored in the internal data logger.



Embedded Web Interface

sbgCenter



# Specifications

## SENSORS PERFORMANCE

	Accelerometers		Gyroscopes
	A2	A3	
Measurement range	8 g	14 g	300 °/s
Random walk	7 µg/√Hz	30 µg/√Hz	0.14°/√hr
Bias in-run instability	2 µg	5 µg	< 0.5 °/hour

## INTERFACE

Aiding Sensors	2x GNSS, RTCM, DVL, Odometer, Gyro-compass
Protocols	Output: NMEA, ASCII, Binary, TSS, Simrad Input: NMEA, Trimble, Novatel, Septentrio, Hemisphere, Veripos, Fugro, PDO, PD6
Output Rate	1 to 200 Hz
Logging Capacity	8 GB or 48h @ 200 Hz
Serial RS-232/422	Model D - 2 outputs / 4 inputs Model A/E - 3 outputs / 5 inputs
CAN	1 CAN 2.0 A/B bus up to 1 Mbit/s
Pulses	Inputs: PPS, Event marker up to 1 kHz Outputs: SyncOut, Trigger 5 inputs / 2 outputs
Ethernet	Full Duplex (10/100 Base T)

## ENVIRONMENTAL SPECIFICATIONS

Operating Vibrations	20 Hz to 2 kHz as per MIL-STD-810G Accelerometer 8 g: 3 g RMS Accelerometer 14 g: 8 g RMS
IP Rating	IP68
Operating Temperature	-40 to 75°C / -40 to 167°F
MTBF	50,000 hours
EMC	EN60945

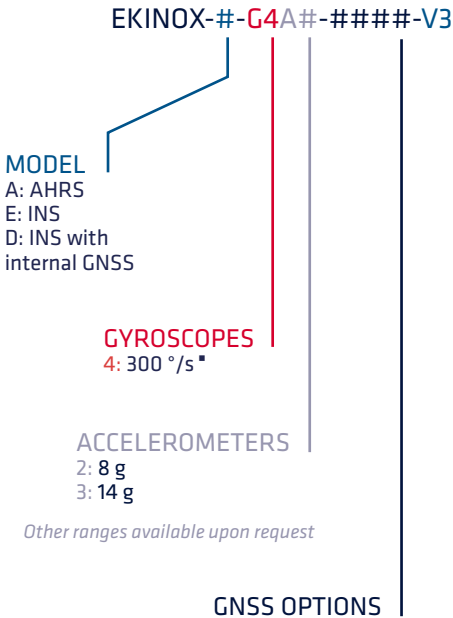
## PHYSICAL CHARACTERISTICS

	Ekinox-A/E	Ekinox-D
GPS	-	L1/L2 Single or Dual Antenna GNSS receiver 448 channels, GPS, GLONASS, GALILEO, BEIDOU
Weight	400 grams 0.88 pounds	600 grams 1.32 pounds
Dimensions (L x W x H)	10 x 8.6 x 5.8 cm 3.9 x 3.4 x 2.2 "	10 x 8.6 x 7.5 cm 3.9 x 3.4 x 2.9 "
Power Consumption	< 3 W	< 5 W
Supply Voltage	9 to 36 VDC	9 to 36 VDC

Typical RMS values. All specifications subject to change without notice.

## PRODUCT CODE INS

▪ standard product options





## Applications



### AEROSPACE

Mid-sized & large UAV  
Avionics  
LiDAR  
Gyro-stabilized camera  
Flight data recorder

- Ready-to-use INS/GPS (Ekinox-D)
- Designed for harsh environments
- Temperature calibrated (-40 to 75°C)
- Unmatched precision in high vibration conditions (MIL-STD-810G)
- Robust IP68 enclosure



### LAND

Car motion  
Unmanned Ground Vehicle  
Camera and 3D scanner  
SATCOM antenna  
Machine Control

- All-in-one solution with Dual Antenna GPS, RTK GNSS, and odometer
- Ethernet & CAN connectivity
- Precise GPS UTC synchronization
- Low latency (2 ms)
- Very low noise on Attitude & Navigation data



### MARINE

Hydrography  
Motion monitoring  
Performance sailing  
Offshore  
Targeting system

- Integrated Dual Antenna GPS for True Heading (Ekinox-D)
- Real-time Auto adjusting heave on 4 monitoring points
- NMEA, TSS & Simrad protocols
- Ethernet & Web interface



### SUBSEA

AUV, ROV  
SONAR, LiDAR, Camera

- Compact and low-power consumption
- Real-time data fusion with DVL, etc.
- Up to 4 simultaneously connected equipment

## Seamless Integration



### STARTING BOX

The selected Ekinox model is shipped with a quick start guide and its own calibration report.

A set of software tools is included such as the sbgCenter application, API C libraries with code examples, etc.

A robust and waterproof transport case is fitted to contain other ordered items such as cables, GNSS antennas, etc.

### NEED A CUSTOM PACKAGE?

Every industry has its own constraints. Our Sales Engineers will work with you to recommend the right solution for your project, or for an entirely custom design.

### SBG SYSTEMS SERVICES

Support – Training – Custom Design



SBG Systems is a leading supplier of inertial motion sensing solutions. The company provides a wide range of inertial solutions from miniature to high accuracy. Combined with cutting-edge calibration techniques and advanced embedded algorithms, SBG Systems products are ideal solutions for industrial & research projects such as unmanned vehicle control, antenna tracking, camera stabilization, and surveying applications.

## TEST RESULTS

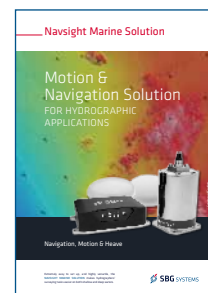


Marine



Hydrography

## PRODUCTS



Navsight Marine



Automotive



Aerospace

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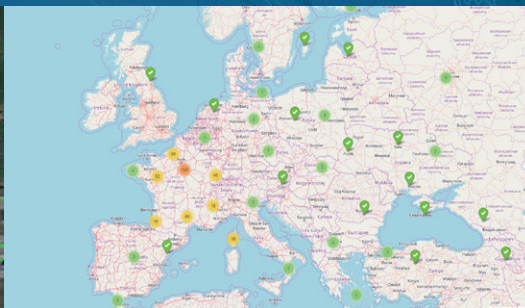
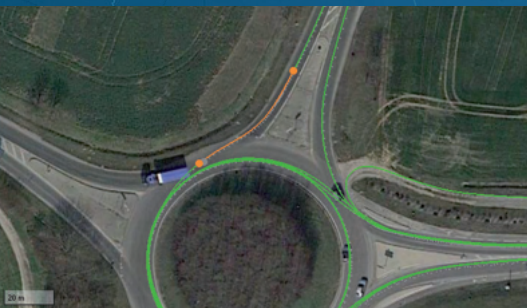
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# Qinertia



## THE NEXT GENERATION INS/GNSS POST-PROCESSING SOFTWARE



For all mobile  
surveying applications



Survey Efficiently, Survey Anywhere, Survey Serenely.  
QINERTIA has been designed to help surveyors get the  
most of their surveys with simplicity.





# Qinertia

## The Next Generation INS/GNSS Post-processing Software

Qinertia is the SBG Systems in-house post-processing software. Full-featured, Qinertia enhances SBG inertial navigation systems performance by post processing inertial data with raw GNSS observables.



### ALL-IN-ONE SOLUTION

INS/GNSS Tight Coupling  
Post-processing

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Static and Kinematic GNSS  
Post-processing

### KEY FEATURES

- » Tightly coupled solution for unmatched accuracy and reliability
- » Centimetric position using offline RTK corrections or Precise Point Positioning
- » Seamless Integration of Odometer and Dual Antenna GNSS Receiver
- » Multi-Constellation Support (GPS, GLONASS, GALILEO, BEIDOU)
- » Support of third-party IMUs and any GNSS receivers

## Qinertia, the PPK Software for All your Projects



### Open to third-party IMUs

Qinertia has been designed to help surveyors get the most of their survey very easily with a simple workflow. Because a park of sensors could be heterogeneous, Qinertia supports third-party Inertial Measurement Unit (IMU). Several IMU and INS have already been successfully integrated with Qinertia including LN-200, LCI-100 and  $\mu$ IMU. You can contact us to study how you can integrate your IMU in Qinertia's workflow.



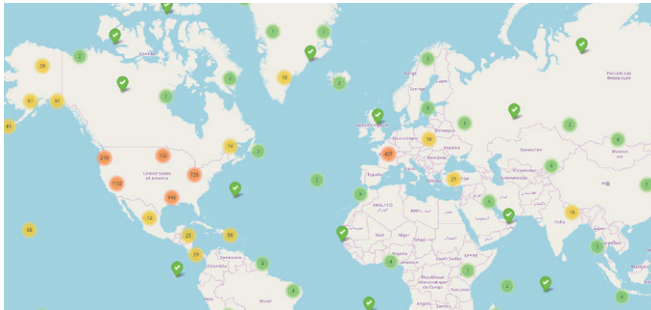
### Open to all GNSS receivers

Qinertia post-process data from any GNSS receiver through RINEX, and with binary files from Novatel, Septentrio, Trimble and Ublox for a straight-forward workflow. In the same way, the VBS feature is able to compute virtual networks from various GNSS receivers, including different models, configurations or constellations, and even with different coordinate systems. Qinertia automatically adjusts the VBS network to compensate for any base station position inaccuracy and provides full quality control indicators to assess the expected accuracy and reliability.



## Powerful Base Station Management

- » 2 modes available:
  - Single Base Station
  - Virtual Base Station
- » Drag & drop user's base station (binary or RINEX format)
- » Preview trajectory and base stations on a map
- » Virtual Base Station computation using both permanent and user's base stations
- » Visualization of expected accuracy and quality
- » Base station position review with PPP computation



## Intuitive Base Station Explorer

- » Access to more than 7,000 base stations over 164 countries
- » Always up-to-date database
- » Automatic download and quality check
- » Web-based pre-mission visualization

## Fast and Simple Workflow

### IMPORT

Easily import SBC inertial data  
Compatible with industry standard  
GNSS receivers (RINEX)<sup>01</sup>  
Native support of Septentrio,  
Novatel, Trimble, and Ublox.

1 Download  
or import  
Base stations

2 Review  
mechanical  
installation

3 Launch  
Processing



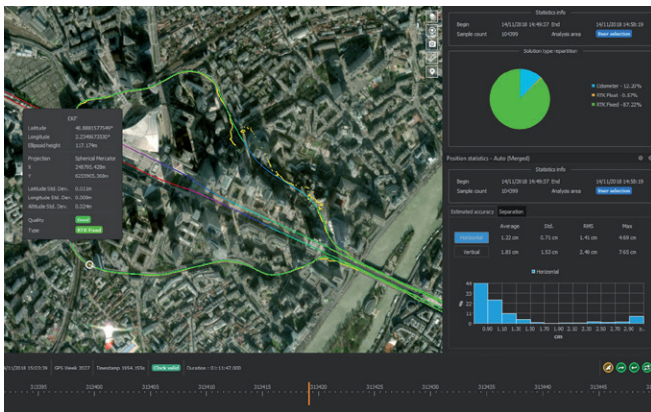


## Processing Made Easy

- » Motion Profiles selection to tune sensor behavior to the application dynamics
- » Seamless Integration of aiding equipment with specific error models
- » Advanced multipath and rejection filters
- » Automatic Lever arm and alignment estimation

## Fast & Modern Technology

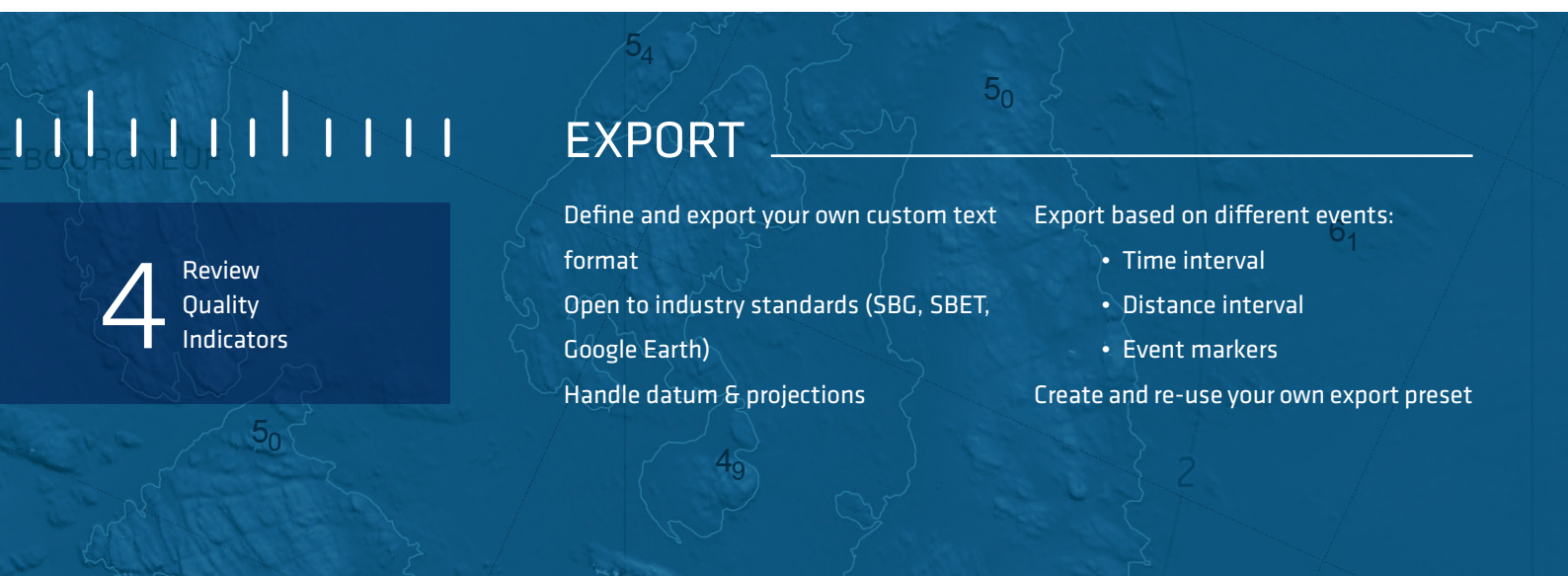
- » Less than 3 minutes for a 6-hour log thanks to Forward and Backward computation at the same time
- » Handle very large logs thanks to modern 64-bits design
- » Cross-platform support:
  - Windows
  - Mac OS X\*
  - Linux\*



## Extensive Quality Indicators

- » Interactive quality indicators assessment
- » Display of advanced parameters (separation, standard deviation, bias, scale factor, lever arm)
- » Statistics report generation (RMS, min/max)

*\* Will be available in the next major update for users under valid maintenance plan*



## 4 Review Quality Indicators

## EXPORT

Define and export your own custom text format

Open to industry standards (SBG, SBET, Google Earth)

Handle datum & projections

Export based on different events:

- Time interval
- Distance interval
- Event markers

Create and re-use your own export preset



# Qinertia - Your Full-featured Post Processing Solution



## GNSS ONLY



All applications  
Post-processing of  
GNSS Static and  
Kinematic data.

## ECONOMICAL PPK FOR UAV\*



UAV applications  
Processing trajectory  
within a 3km radius  
limit.  
GNSS Only included.

## ENTRY-LEVEL PPK WITH ELLIPSE SENSORS



Land/Air applications  
Full processing with  
Ellipse sensors in  
Land/Air applications.  
GNSS Only included.

## FULL-FEATURED PPK



All applications  
Full processing with  
any IMUs and GNSS  
receiver.  
GNSS Only included.

## FLEXIBLE LICENSING

Easily share your floating license with your team.  
We offer flexible licensing options (perpetual or  
subscription) to best fit your needs.

### PERPETUAL LICENSE

Initial purchase  
+ yearly maintenance

### SUBSCRIPTION

1 Month

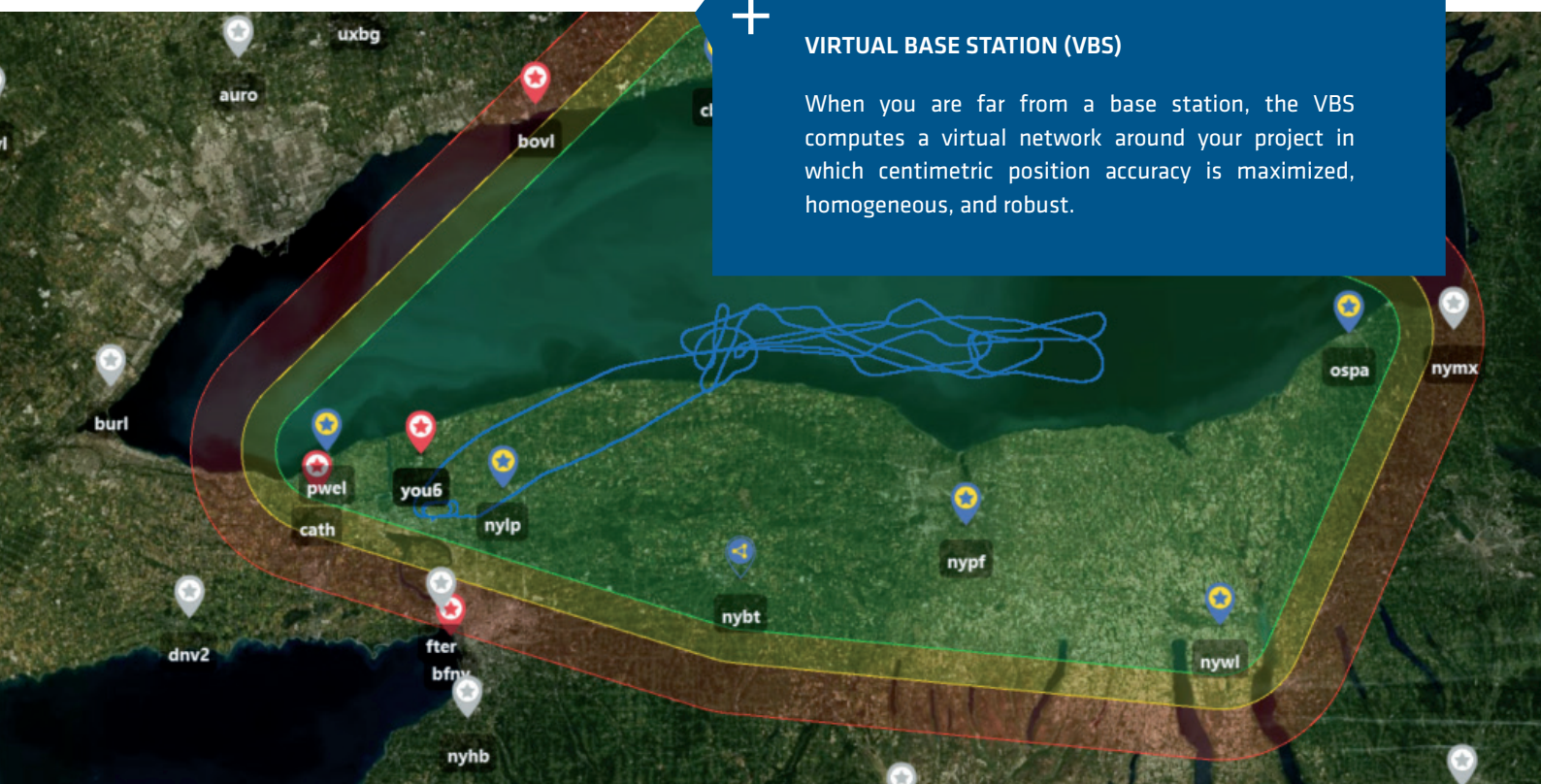
12 Months

\* Processing trajectory within a 3km radius limit. 1 year free subscription when buying a Quanta solution.



### VIRTUAL BASE STATION (VBS)

When you are far from a base station, the VBS  
computes a virtual network around your project in  
which centimetric position accuracy is maximized,  
homogeneous, and robust.





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