













The A222 GNSS Smart Antenna is an affordable, portable solution with professional-level accuracy for agricultural, marine, GIS, mapping, and other applications.

Focus on the job-at-hand with fast start-up and reacquisition times, 60 cm accuracy, and an easy-to-see LED status indicator for power, GNSS, and DGNSS. The durable enclosure houses both antenna and receiver. It can be powered through various sources, making the A222 smart antenna ideal for a variety of applications. Dual-Serial, CAN, and pulse output options make this DGNSS receiver compatible with almost any interface.

A222 is supported by Hemisphere's easy-to-use Atlas Portal (www.atlasgnss.com), which empowers you to update firmware and enable functionality, including Atlas subscriptions for accuracies from meter to sub-decimeter levels.

- Atlas® L-band corrections
- Exclusive Atlas Basic option available when other differential signals are not practical
- Scalable accuracy within a single product for different use cases
- Durable enclosure is proven to withstand the most aggressive environments
- Compact, low-profile design with fixed or magnetic mounting options are ideal for portable and dynamic applications

Receiver Type: Scalable dual-frequency, multi-GNSS RTK

Signals Received: GPS L1CA/L1P/L1C/L2P/L2C

GLONASS G1/G2/P1/P2

BeiDou B1 Galileo E1BC

Atlas

332 Channels: **GPS Sensitivity:** -142 dBm

**SBAS Tracking:** 3-channel, parallel tracking

Update Rate: 10 Hz standard, 20 Hz optional (with

subscription)

Timing (1 PPS)

Accuracy: 20 ns

**Cold Start:** < 60 s typical (no almanac, ephemeris,

position, or RTC)

Warm Start: < 30 s typical (almanac and RTC) **Hot Start:** < 10 s typical (almanac, ephemeris,

position, and RTC)

Maximum Speed: 1,850 mph (999 kts)

Maximum

Altitude: 18,288 m (60,000 ft)

Accuracy

Positionina: 2DRMS (95%) RMS (67%) Autonomous, 2.5 m no SA: 1 1.2 m SBAS: 1 0.3 m 0.6 m Atlas: 1,3 0.08 m 0.16 m RTK: 1,2 8 mm + 1 ppm  $15 \, \text{mm} + 2 \, \text{ppm}$ 

**L-Band Receiver Specifications** 

Receiver Type: Single Channel Channels: 1530 to 1560 MHz

-130 dBm Sensitivity: Channel Spacina: 5 kHz

Satellite Selection: Manual or Automatic

Reacauisition

Time: 15 sec (typical)

Communications

Ports: 2 full-duplex RS-232, CAN <sup>4</sup>

**Baud Rates:** 4800 - 115200

Correction I/O

Protocol: Hemisphere GNSS proprietary, RTCM v2.3

(DGPS), RTCM v3 (RTK)

Data I/O Protocol: NMEA 0183, NMEA 2000, Hemisphere

**GNSS** binary

**Timing Output:** 1 PPS, CMOS, active low, falling edge

sync,  $10 \text{ k}\Omega$ , 10 pF load

**Event Marker** 

Input: CMOS, active low, falling edge sync, 10

 $k\Omega$ , 10 pF load

**Power** 

Input Voltage: 7-32 VDC with reverse polarity operation

**Power** 

Consumption: 4.1 W nominal (L1/L2 GPS/GLONASS;

L-band)

Current

Consumption: 0.35 A nominal (L1/L2 GPS/GLONASS;

L-band)

Power Isolation: No

**Reverse Polarity** 

**Protection:** Yes

Antenna Voltage: Internal Antenna

**Environmental** 

Operating

**Temperature:** -40°C to +70°C (-40°F to +158°F)

Storage

**Temperature:** -40°C to +85°C (-40°F to +185°F)

**Humidity:** 95% non-condensing

Mechanical

Shock: EP455 Section 5.41.1 Operational Vibration: EP455 Section 5.15.1 Random

EMC: CE (ISO 14982 Emissions and Immunity),

FCC Part 15, Subpart B, CISPR 22

**Enclosure:** 

Mechanical

**Dimensions:**  $15.8 L \times 15.8 W \times 7.9 H (cm)$ 

6.2 L x 6.2 W x 3.2 H (in)

Weight: < 1.05 kg (< 2.53 lbs)

**Status Indications** 

(LED): Power, GNSS Lock

Power/Data

Connector: 12-pin male (metal)

Antenna

Mounting: 1-14 UNS-2A female adapter, 5/8-11 UNC

2B adapter, flat mount available

Depends on multipath environment, number of satellites in view, satellite geometry, and ionospheric activity
Depends also on baseline length
Requires a subscription from Hemisphere GNSS 4 Requires software upgrade



**Hemisphere GNSS** 

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The A326 is an all-new multi-GNSS, multi-frequency smart antenna. Showcasing fast start-up and reacquisition times, and an easy-to-see status indicator for power, GNSS, and Bluetooth. The durable enclosure houses the high precision antenna element and GNSS receiver. Resulting in the A326 smart antenna being ideal for a variety of applications. The available multiple communication ports, such as Bluetooth, Wi-Fi, dual-Serial, and CAN options make the A326 compatible with almost any interface. The easy-to-use WebUI allows the user to wirelessly monitor and configure the A326 with any Wi-Fi capable device, making the A326 one of the most versatile GNSS smart antennas in the world.

#### Athena™ RTK

The A326 GNSS Smart Antenna uses Hemisphere GNSS' next-generation Athena RTK engine. Athena offers world class performance in the areas of initialization time, robustness in very difficult operating environments, superior performance over long RTK baselines, and exceptional reliability in scintillation conditions.

#### Atlas® GNSS Global Corrections

A326 is Atlas ready, and capable of receiving corrections from Hemisphere's Atlas Global Correction Service.

A326 is supported by our easy-to-use Atlas Portal (www.atlasgnss.com), which empowers you to update firmware and enable functionality, including Atlas subscriptions for accuracies from meter to sub decimeter levels.

- Atlas GNSS Global Correction Service
- Athena RTK engine
- Powerful WebUI accessed via Wi-Fi
- Internal memory for data logging, download, and upload
- Durable enclosure is proven to withstand aggressive environments

Receiver Type: **GNSS Position RTK Receiver** 

Signals Received: GPS, GLONASS, Galileo, BeiDou, QZSS

Channels: 572 / 488 -142 dBm **GPS Sensitivity:** 

3-channel, parallel tracking **SBAS Tracking:** 

**Update Rate:** 10 Hz standard, 20 Hz optional (with

subscription)

Timing (1 PPS)

Accuracy: 20 ns

Cold Start: < 60 s typical (no almanac, ephemeris,

position, or RTC)

Warm Start: < 30 s typical (almanac and RTC) Hot Start: < 10 s typical (almanac, ephemeris,

position, and RTC)

Maximum Speed: 1,850 mph (999 kts)

Maximum

Altitude: 18,288 m (60,000 ft)

Accuracy

Positioning: RMS (67%) 2DRMS (95%) Autonomous, no SA: 1 1.2 m 2.5 m SBAS: 1 0.3 m 0.6 m Atlas: 1,3 0.16 m  $0.08 \, \text{m}$ **RTK:** 1,2 8 mm + 1 ppm 15 mm + 2 ppm

**L-Band Receiver Specifications** 

Receiver Type: Single Channel Channels: 1530 to 1560 MHz

Sensitivity: -130 dBm Channel Spacing: 5 kHz

Satellite Selection: Manual or Automatic

Reacquisition

Time: 15 sec (typical)

Communications

Ports: 2 full-duplex RS-232, CAN Interface Level: Atlas GNSS (WebUI) **Baud Rates:** 4800 - 115200

Correction I/O

Protocol: Hemisphere GNSS proprietary ROX

format, RTCM v2.3, RTCM v3.2, CMR5,

CMR+5

Data I/O Protocol: NMEA 0183, NMEA 2000, Hemisphere

GNSS binary, Bluetooth 2.0 (Class 2), Wi-Fi

**Timing Output:** 1 PPS, CMOS, active high, rising edge

sync,  $10 \text{ k}\Omega$ , 10 pF load

**Event Marker** 

CMOS, active low, falling edge sync, 10 Input:

 $k\Omega$ , 10 pF load

**Power** 

Input Voltage: 7-32 VDC

**Power** 

Consumption: 4.5 W nominal (L1/L2 GPS/GLONASS/

BeiDou, L-band)

Current

0.38 A nominal (L1/L2 GPS/GLONASS/ Consumption:

BeiDou, L-band)

Power Isolation: No

**Reverse Polarity** 

Protection: Yes

**Environmental** 

Operating

Temperature: -40°C to +70°C (-40°F to +158°F)

Storage

Temperature: -40°C to +85°C (-40°F to +185°F)

**Humidity:** 95% non-condensing

Mechanical

Shock: 50G, 11ms half sine pulse (MIL-STD-810G

w/Change 1 Method 516.7 Procedure 1)

Vibration: 7.7Grms (MIL-STD-810G w/Change 1

Method 514.7 Category 24)

EMC: CE (ISO14982/EN13309/ISO13766/

IEC60945), Radio Equipment Directive

2014/53/EU, E-Mark, RCM

**Enclosure:** IP67

Mechanical

**Dimensions:**  $15.8 L \times 15.8 W \times 7.9 H (cm)$ 

6.2 L x 6.2 W x 3.2 H (in)

Weight: < 1.15 kg (< 2.53 lbs)

**Status Indications** 

(LED): Power, GNSS Status, Bluetooth, Wi-Fi

Power/Data

Connector: 12-pin male

**Antenna** 

Mounting: 1-14 UNS-2A female adapter, 5/8-11 UNC

2B adapter, flat mount available

1. Depends on multipath environment, number of satellites in view, satellite geometry,

2.

and ionospiretic activity
Depends also on baseline length
Requires a subscription from Hemisphere GNSS
With L5 option 5 With B3 option
CMR and CMR+ do not cover proprietary messages outside of the typical standard



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# AtlasLink® GNSS Smart Antenna







AtlasLink is a multi-GNSS, multi-frequency smart antenna preconfigured to receive corrections from Hemisphere's Atlas global corrections service. AtlasLink paired with Atlas provides you with the easiest way to receive Atlas corrections via the industry's most powerful multi-purpose GNSS smart antenna, either directly from AtlasLink or into your existing receiver.

Over are the days of being tied to a single corrections provider who requires you to purchase their corrections, which can only be received by their device. If you use Atlas corrections data on equipment that doesn't have the ability to receive L-band signals, or you would like to use Atlas corrections on systems that currently receive L-band corrections from another source, you now have the freedom to do so. AtlasLink, in SmartLink™ or BaseLink® mode, enables you to use Atlas corrections on any receiver from any vendor that supports industry-standard correction formats.

AtlasLink is supported by our easy-to-use Atlas Portal (www.atlasgnss.com), which empowers you to update firmware and enable functionality, including Atlas subscriptions for accuracies from meter to subdecimeter levels.

- Atlas® L-band corrections
- Athena™ RTK engine
- Powerful WebUI accessed via Wi-Fi
- Internal memory for data logging, download, and upload
- Environment-proven enclosure for the most aggressive user scenarios

Receiver Type: Multi-frequency, Multi-GNSS RTK Sianals Received: GPS, GLONASS, BeiDou, and Atlas

Channels: 572 / 488 -142 dBm **GPS Sensitivity:** 

3-channel, parallel tracking **SBAS Tracking:** 

**Update Rate:** 10 Hz standard, 20 Hz optional (with

subscription)

Timing (1 PPS)

Accuracy: 20 ns

**Cold Start:** 60 s typical (no almanac or RTC) Warm Start: 30 s typical (almanac and RTC)

Hot Start: 10 s typical (almanac, RTC and position)

Maximum Speed: 1,850 mph (999 kts)

Maximum

Altitude: 18,288 m (60,000 ft)

#### Accuracy

,		
Positioning:	RMS (67%)	2DRMS (95%)
Autonomous,		
no SA: 1	1.2 m	2.5 m
SBAS: 1	0.3 m	0.6 m
Atlas H10: 1,3	0.04 m	0.08 m
Atlas H30: 1,3	0.15 m	0.3 m
Atlas Basic: 1,3	0.50 m	1.0 m
RTK: 1	8 mm + 1 ppm	15 mm + 2 ppm

#### **L-Band Receiver Specifications**

Receiver Type: Single Channel Channels: 1525 to 1560 MHz

Sensitivity: -130 dBm Channel Spacing: 5 kHz

Satellite Selection: Manual or Automatic

Reacquisition

Time: 15 sec (typical)

#### **Communications**

2x full-duplex RS-232, 1x CAN

Interface Level: Atlas GNSS (WebUI) **Baud Rates:** 4800 - 115200

Correction I/O

Protocol: Hemisphere GNSS proprietary ROX

format, RTCM v2.3, RTCM v3.2, CMR4,

CMR+4

Data I/O Protocol: NMEA 0183, NMEA 2000, Hemisphere

GNSS binary, Bluetooth 2.0 (Class 2), Wi-Fi

**Timing Output:** 1 PPS, CMOS, active high, rising edge

sync,  $10 \text{ k}\Omega$ , 10 pF load

**Event Marker** 

CMOS, active low, falling edge sync, 10 Input:

 $k\Omega$ , 10 pF load

#### **Power**

Input Voltage: 7-32 VDC

**Power** 

Consumption: 3.4W nominal All Signals + L-band

Current

0.28 A nominal All Signals + L-band

Consumption: **Reverse Polarity** 

Protection: Yes

#### **Environmental**

Operating

Temperature: -40°C to +70°C (-40°F to +158°F)

Storage

-40°C to +85°C (-40°F to +185°F) Temperature:

**Humidity:** 

95% non-condensing Mechanical

Shock: EP455 Section 5.41.1

Vibration: EP455 Section 5.15.1 Random

EMC: CE (ISO 14982 Emissions and Immunity)

FCC Part 15, Subpart B

CISPR 22

IP67 Enclosure:

#### Mechanical

**Dimensions:** 15.8 L x 15.8 W x 7.9 H (cm)

6.2 L x 6.2 W x 3.2 H (in)

Weiaht: 1.05 kg (2.53 lbs)

**Status Indications** 

(LED): Power, RTK/Atlas Float, RTK/Atlas Fixed

Power/Data

Connector: 12-pin male (metal)

Antenna

Mounting: 1-14 female with 5/8-11 adapter, and flat

mount

1 Depends on multipath environment, number of satellites in view, satellite geometry,

Depends on multiparti environment, number of satellites in Fiori, satellites and ionospheric activity
Depends also on baseline length
Requires a subscription from Hemisphere GNSS
CMR and CMR+ do not cover proprietary messages outside of the typical standard

# OHemisphere<sup>®</sup>

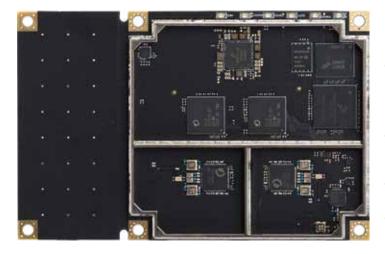
**Hemisphere GNSS** 

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# Crescent® Vector™ H220 GNSS OEM Board

# NEXT GENERATION, HIGH-PERFORMANCE GNSS POSITION AND HEADING MODULE



# **Patlas**°

The Crescent Vector H220 GNSS OEM board is the next generation, single-frequency, high-performance GNSS heading, positioning, and attitude module available from Hemisphere GNSS.

The H220 provides integrators with an opportunity for developing sophisticated marine, navigation, and land applications in challenging dynamic environments. The H220 uses Hemisphere's advancements in Vector technology, advanced multipath mitigation techniques, and Hemisphere's patented Multifunction Application.

H220 is capable of providing heading of 0.04° with a 5 meter antenna baseline and either RTK or SBAS positioning depending on your location requirements. With Atlas corrections, the H220 can obtain instant sub-meter accuracy worldwide.

Integrate the robust H220 GNSS OEM board into your applications to experience exceptional heading, positioning, and attitude performance. Diversity and cost savings make it an ideal part of your solution for system integrators.

- Extremely accurate heading with short baselines
- Single Frequency GPS/GLONASS/BeiDou/Galileo QZSS RTK capable
- Integrated L-band for Atlas® corrections
- Excellent coasting performance
- 10 cm RMS heave accuracy with RTK
- Strong multipath mitigation and interference rejection
- New multi-axis gyro and tilt sensor for reliable coverage during short GNSS outages

Receiver Type: Single Frequency GPS, GLONASS,

BeiDou, Galileo, QZSS4, and Atlas Signals Received: GPS L1CA/L1P

GLONASS G1, P1 BeiDou B1 GALILEO E1BC QZSS L1CA4 Atlas

Channels: 424 **GPS Sensitivity:** -142 dBm

2-channel, parallel tracking **SBAS Tracking:** Update Rate:

10 Hz standard, 1 Hz, 20 Hz or 50 Hz<sup>5</sup>

optional (with activation)

Timing (1 PPS)

Accuracy:

Rate of Turn: 100°/s maximum

Cold Start: 60 s typical (no almanac or RTC) Warm Start: 30 s typical (almanac and RTC) **Hot Start:** 10 s typical (almanac, RTC and

position) **Heading Fix:** 10 s typical (Hot Start)

**Antenna Input** 

Impedance: Maximum Speed: 1,850 mph (999 kts) Maximum Altitude: 18,288 m (60,000 ft)

Accuracy

Positioning: RMS (67%) 2DRMS (95%)

Autonomous, no SA: 1 1.2 m  $2.5 \, \mathrm{m}$ 0.6 m SBAS: 1  $0.3 \, \mathrm{m}$ Atlas Basic: 1,3  $0.50 \, \text{m}$ 1.0 m

RTK: 1 10 mm + 1 ppm 20 mm + 2 ppm 0.30° @ 0.5 m antenna separation Heading (RMS):

0.15° @ 1.0 m antenna separation 0.08° @ 2.0 m antenna separation  $0.04^{\circ}$  @ 5.0 m antenna separation

Pitch/Roll (RMS):

Heave (RMS): 1 30 cm (DGPS), 10 cm (RTK)

**L-Band Receiver Specifications** 

Receiver Type: Single Channel 1525 to 1560 MHz Channels:

Sensitivity: -130 dBm **Channel Spacing:** 5.0 kHz

Manual and Automatic Satellite Selection: **Reacquisition Time:** 15 seconds (typical)

- Depends on multipath environment, number of satellites in view, satellite geometry, and ionospheric activity
- Based on a 40 second time constant
- Hemisphere GNSS proprietary
- With future firmware upgrade and activation
- CMR and CMR+ do not cover proprietary messages outside of the typical

**Communications** 

4 x full-duplex 3.3V CMOS Ports:

(3 x main serial ports, 1 x differential-

only port) 1 x ÚSB Host 1 x USB Device

Interface Level: 3.3V CMOS **Baud Rates:** 4800 - 115200

Correction I/O Protocol: Hemisphere GNSS proprietary ROX

format, RTCM v2.3, RTCM v3.2,

CMR5, CMR+5

Data I/O Protocol: NMEA 0183, Crescent binary <sup>3</sup> Timing Output: 1 PPS, CMOS, active high, rising edge sync,  $10 \text{ k}\Omega$ , 10 pF loadCMOS, active low, falling edge **Event Marker Input:** 

sync,  $10 \text{ k}\Omega$ , 10 pF load

**Power** 

Input Voltage: 3.3 VDC +/- 5%

2.1 W nominal GPS (L1) and **Power Consumption:** GLONASS (L1) 0.64 A nominal GPS (L1) and **Current Consumption:** 

Yes

GLONASS (L1) Antenna Voltage: 5 VDC maximum **Antenna Short Circuit** 

**Protection:** 

Antenna Gain Input

Range:

10 to 40 dB

**Environmental** 

Operating Temperature:

Storage Temperature:

**Humidity**:

-40°C to +85°C (-40°F to +185°F) -40°C to +85°C (-40°F to +185°F) 95% non-condensing (when in an

enclosure)

Mechanical Shock: EP455 Section 5.14.1

Operational (when mounted in an enclosure with screw mounting

holes utilized)

EP455 Section 5.15.1 Random CE (IEC 60945 Emissions and Vibration: EMC:

Immunity)

FCC Part 15, Subpart B

CISPR 22

Mechanical

**Dimensions:** 109 L x 71 W x 5 H (mm) 4.3 L x 2.8 W x 0.2 H (in)

Weight: 50 g (1.77 oz)

Status Indications (LED): Power, Primary and Secondary GNSS lock, Differential lock, DGNSS

position, Heading

Power/Data Connector:

34-pin male header 2 mm pitch

**Antenna Connectors:** MCX, female, straight

**Aiding Devices** 

Gvro:

Provides smooth and fast heading reacquisition. During loss of GNSS signals heading stability is degraded

by < 1° per minute for up to 3

minutesi.<sup>2</sup>

Tilt Sensors: Provide pitch and roll data and

assist in fast startup and

reacquisition of heading solution.



#### **Hemisphere GNSS**

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# Eclipse<sup>™</sup> Vector<sup>™</sup> H328 GNSS OEM Board





# **Vatlas**°

Develop sophisticated machine control and navigation solutions in a complex world full of dynamic environments. The Vector H328 is our most advanced GNSS heading and positioning board.

The Vector H328 uses dual antenna ports to create a series of additional capabilities to Eclipse Vector technology including fast, high-accuracy heading over short baselines, RTK positioning, onboard Atlas L-band, RTK-enabled heave, low-power consumption, and precise timing.

#### **Scalable Solutions**

With the Vector H328, positioning is scalable and field upgradeable with all Hemisphere software and service options. Use the same centimeter-level accuracy in either single frequency mode, or employ the full performance and fast RTK initialization times over long distances with multi-frequency multi-constellation GNSS signals. High-accuracy L-band positioning from meter to sub-decimeter levels are available via Atlas correction service.

#### **Ease of Migration**

Leverage the industry standard form factor for easy upgradeability from other manufacturers' modules.

- Extremely accurate heading with long baselines
- Multi-frequency position, dual-frequency heading supporting GPS, GLONASS, BeiDou, Galileo, QZSS, IRNSS, and L-band
- Atlas® L-band capable to 4 cm RMS
- Athena™ GNSS engine providing best-in-class RTK performance
- Excellent coasting performance
- 5 cm RMS RTK-enabled heave accuracy
- Strong multipath mitigation and interference rejection
- New multi-axis gyro and tilt sensor for reliable coverage during short GNSS outages

**Receiver Type:** Multi-Frequency GPS, GLONASS,

BeiDou, Galileo, QZSS, and Atlas GPS L1CA/L1P/L1C/L2P/L2C/L5 Signals Received:

GLONASS G1/G2, P1/P2 BeiDou B1/B2/B3 GALILEO E1BC/E5a/E5b QZSS L1CA/L2C/L5/L1C

Atlas 1059

Channels: **GPS Sensitivity:** -142 dBm

**SBAS Tracking:** 3-channel, parallel tracking **Update Rate:** 10 Hz standard, 1 Hz or 20 Hz optional (with activation)

Timing (1 PPS)

Accuracy: 20 ns

Rate of Turn: 100°/s maximum

Cold Start: 60 s typical (no almanac or RTC) 30 s typical (almanac and RTC) Warm Start: **Hot Start:** 10 s typical (almanac, RTC and

position)

**Heading Fix:** 10 s typical (Hot Start)

**Antenna Input** 

Impedance: 50 Ω

Maximum Speed: 1,850 mph (999 kts) Maximum Altitude: 18,288 m (60,000 ft)

Accuracy

Positioning: RMS (67%) 2DRMS (95%) 1.2 m  $2.5 \, \mathrm{m}$ 

Autonomous, no SA: 1 0.6 m SBAS: 1  $0.3 \, \mathrm{m}$ Atlas H10: 1, 3  $0.08 \, \text{m}$  $0.04 \, \text{m}$ Atlas H30: 1, 3  $0.15 \, \text{m}$  $0.3 \, \mathrm{m}$ Atlas Basic: 1,3 1.0 m  $0.50 \, \text{m}$ 

RTK: 1 8 mm + 1 ppm 15 mm + 2 ppm

Heading (RMS): 0.16° rms @ 0.5 m antenna

separation

0.08° rms @ 1.0 m antenna

separation

0.04° rms @ 2.0 m antenna

separation

0.02° rms @ 5.0 m antenna

separation

Pitch/Roll (RMS): 10

30 cm rms (DGNSS), 5 cm rms (RTK) Heave (RMS): 1

**L-Band Receiver Specifications** 

Receiver Type: Single Channel Channels: 1525 to 1560 MHz

Sensitivity: -130 dBm **Channel Spacing:** 5.0 kHz

Satellite Selection: Manual and Automatic **Reacquisition Time:** 15 seconds (typical)

Depends on multipath environment, number of satellites in view, satellite geometry, and ionospheric activity

Depends on multipath environment, number of satellites in view, SBAS coverage, satellite geometry, and ionospheric activity

Hemisphere GNSS proprietary

With future firmware upgrade and activation

CMR and CMR+ do not cover proprietary messages outside of the typical standard



**Communications** 

3 x full-duplex (1 x 3.3V CMOS, 1 x 3.3V CMOS with flow control, 1 x RS-232 with flow

control)

1 x USB Device

1 x Ethernet 10/100Mbps

2 x CAN (NMEA2000, ISO 11783)

1 x SPI

Interface Level: 3.3V CMOS 4800 - 115200 **Baud Rates:** 

Correction I/O Protocol: Hemisphere GNSS proprietary ROX

format, RTCM v2.3, RTCM v3.2,

CMR<sup>5</sup>, CMR+<sup>5</sup> NMEA 0183, Crescent binary <sup>5</sup> 1 PPS, CMOS, active high, rising Data I/O Protocol: **Timing Output:** 

edge sync,  $10 \text{ k}\Omega$ , 10 pF loadCMOS, active low, falling edge

sync,  $10 \text{ k}\Omega$ , 10 pF load

**Power** 

Input Voltage: 3.3 VDC +/- 5%

**Power Consumption:** 

2.0 W nominal GPS (L1) 2.7 W nominal GPS (L1/L2) and

GLONASS (G1/G2)

3.8 W nominal All Signals + L-band 0.61 A nominal GPS (L1) 0.82 A nominal GPS (L1/L2)

**Current Consumption:** 

1.15 A nominal All Signals + L-band 5 VDC maximum

**Antenna Voltage:** Antenna Short Circuit **Protection:** 

Antenna Gain Input

**Event Marker Input:** 

Range:

Yes

10 to 40 dB

**Environmental** 

Operating Temperature:

Storage Temperature:

Humidity:

 $-40^{\circ}$ C to +85°C (-40°F to +185°F -40°C to +85°C (-40°F to +185°F) 95% non-condensing (when in an

enclosure)

**Mechanical Shock:** EP455 Section 5.14.1

Operational (when mounted in an enclosure with screw mounting

holes utilized)

Vibration: EP455 Section 5.15.1 Random CE (IEC 60945 Emissions and EMC:

Immunity) FCC Part 15, Subpart B

CISPR 22

Mechanical

100 L x 60 W x 10 H (mm) 3.9 L x 2.4 W x 0.4 (in) 44 g (1.56 oz) **Dimensions:** 

Weight:

Status Indications (LED): Power, Primary and Secondary GNSS lock, Differential lock, DGNSS

position, Heading

Power/Data

24-pin male header 2 mm pitch 16-pin male header 2 mm pitch Connector:

**Antenna Connectors:** MMCX, female, straight

**Aiding Devices** 

Gyro:

Provides smooth and fast heading reacquisition. During loss of GNSS signals heading stability is degraded by < 1° per minute for up to 3

minutes.

Provide pitch, roll data and assist in Tilt Sensors:

fast start-up and reacquisition of

heading solution

#### **Hemisphere GNSS**

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## Crescent® P206 & P207 GNSS OEM Boards







- Extremely affordable single frequency, multi constellation solution with up to 20 Hz update rate
- GPS, GLONASS, BeiDou, Galileo, and QZSS-ready
- Fast start-up and reacquisition times allow you to get right to work
- High-precision, differential positioning accuracy of 60 cm, 95% of the time
- Exclusive e-Dif® option where other differential signals are not practical
- COAST and SureTrack maintain sub-meter DGNSS positioning for 40 minutes after correction loss
- Small form and low-power consumption design is ideal for easy integration





Hemisphere GNSS' Crescent P206 and P207 OEM modules use GPS, GLONASS, and BeiDou, and are Galileo and QZSS ready. Track more signals for unparalleled positioning performance even in challenging environments. Leverage the compact size and easy integration in your design. The 34-pin P206 module is a drop-in upgrade for many Hemisphere products. P207 is a drop in upgrade for existing Crescent designs using standard 20 pin modules from other manufacturers.

DGPS and SBAS with patented COAST™ software enables Hemisphere receivers to use previous DGPS and SBAS correction data during times of interference, signal blockage and weak signal. The receiver will coast and continue to maintain sub-meter positioning for up to 40 minutes without any DGPS signal. When your corrections are only for one GNSS constellation, for example GPS using SBAS, Hemisphere's patented SureTrack™ goes to work to model all other satellites, helping maintain an accurate solution in challenging environments.

**Receiver Type:** GNSS single-frequency RTK with

carrier phase

**Signals Received:** GPS, GLONASS, BeiDou,

GALILEO 1, and QZSS 1

Channels: 103 GPS Sensitivity: -142 dBm

SBAS Tracking: 3-channel, parallel tracking
Update Rate: 1 Hz standard, 10 or 20 Hz

optional

Timing (1 PPS)

Accuracy: 20 ns

Cold Start: < 60 s typical (all unknown)
Warm Start: < 30 s typical (no ephemeris)
Hot Start: < 10 s typical (all known)
Removable, auto-recharging

onboard clock battery

**Maximum Speed:** 1,850 mph (999 kts) **Maximum Altitude:** 18,288 m (60,000 ft)

Accuracy

Positioning: RMS (67%) 2DRMS (95%)

**Autonomous, no SA:** 3 1.2 m 2.5 m **SBAS:** 3 0.3 m 0.6 m

**RTK:** <sup>2</sup> 10 mm + 1 ppm 20 mm + 2 ppm

**Communications** 

**Event Marker Input:** 

Ports: 4x full-duplex 3.3 V CMOS (3 main

serial ports

1x differential-only port)

1x USB Host <sup>6</sup>
1x USB Device

**Baud Rates:** 4800 - 115200

Correction I/O Protocol: Hemisphere GNSS proprietary ROX

format, RTCM v2.3, RTCM v3.2,

CMR<sup>8</sup>, CMR+<sup>8</sup>

**Data I/O Protocol:** NMEA 0183, Crescent binary <sup>7</sup> 1 PPS, CMOS, active high, rising

edge sync, 10 k $\Omega$ , 10 pF load CMOS, active low, falling edge

sync,  $10 \text{ k}\Omega$ , 10 pF load

**Power** 

Input Voltage: 3.3 VDC +/- 5% Power Consumption: 1.2 W nominal L1 GPS

1.4 W nominal single frequency

GPS + GLONASS + BeiDou Current Consumption: 0.30 A nominal GPS (L1)

370 mA nominal L1 GPS

420 mA nominal single frequency

GPS + GLONASS + BeiDou

Antenna Voltage: 15 VDC maximum Antenna Short

10 to 40 dB

Circuit

Yes

Antenna Short Circuit Protection:

Antenna Gain Input

Range:

Antenna Input

Impedance:  $50 \Omega$ 

**Environmental** 

Operating

Temperature: -40°C Storage Temperature: -40°C

Humidity:

-40°C to +85°C (-40°F to +185°F) -40°C to +85°C (-40°F to +185°F) 95% non-condensing (when in an

enclosure)

Mechanical

Dimensions: 7.25 L x 4.1 W x 1.1 H (cm) 2.85 L x 1.61 W x 0.43 H (in)

**Weight:** .105 kg (3.70 oz.)

Status Indications (LED): Power, Primary and Secondary GPS

lock, Differential lock, DGPS position, Heading, RTK lock, Atlas L-band lock

Power/Data Connector:

**P206:** 34-pin male header 0.05" pitch **P207:** 20-pin male header 0.05" pitch

**Antenna Connectors:** MCX, female, straight

1. Firmware update required

2. Depends on multipath environment, number of satellites in view, satellite geometry baseline length (up to 10 km) and ionospheric activity

Depends on multipath environment, number of satellites in view, satellite geometry and ionospheric activity

 Cold start means no approx. position, no approx. time, no almanac, no ephemeris - Warm starts require an approx. position, approx. time, and almanac - Hot starts require an approx. position, approx. time, and valid ephemeris

5. Maintains time while receiver is powered off, reducing cold start occurrences

6. P206 Only

7. Hemisphere GNSS proprietary

 CMR and CMR+ do not cover proprietary messages outside of the typical standard



**Hemisphere GNSS** 

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#### **Key Features**

- Multi-Frequency GPS, GLONASS, BeiDou, Galileo and QZSS-ready
- Long-range RTK baselines up to 50 km with fast acquisition times
- Compatible with many RTK sources including Hemisphere GNSS' ROX format, RTCM, CMR, CMR+
- Mechanically and electrically (pin-for-pin) compatible with many Hemisphere and other manufacturers' modules
- Atlas<sup>®</sup> L-band capable to 4 cm RMS
- Athena™ GNSS engine providing best-in- class RTK performance

#### Track More Signals for the Most Robust Low-Power, Multi-Frequency, Multi-GNSS Solution

Track more signals for unparalleled positioning performance with Hemisphere GNSS' new Eclipse P326 and P327 OEM modules. The latest technology platform enables simultaneous tracking of all satellite signals including GPS, GLONASS, BeiDou, Galileo, and L-band (QZSS ready) making it the most robust and reliable solution. The updated power management system efficiently governs the processor, memory, and ASIC making it ideal for multiple integration applications including handheld and battery- powered devices.

# Experience Unparalleled Accuracy and Reliability with Advanced Technology Features

The P326 and P327 are the most accurate and reliable OEM modules with two new advanced technology features; aRTK $^{\text{TM}}$  and Tracer $^{\text{TM}}$ . Hemisphere's aRTK technology, powered by Atlas, allows the P326 and P327 to operate with RTK accuracies when RTK corrections fail. Tracer utilizes specialized algorithms to sustain positioning in the absence of corrections data.

#### **Scalable Solutions**

With the Eclipse P326 and P327, positioning is scalable and field upgradeable with all Hemisphere software and service options. Use the same centimeter-level accuracy in either single frequency mode, or employ the full performance and fast RTK initialization times over long distances with multifrequency, multi-constellation GNSS signals. High-accuracy L-band positioning from meter to sub-decimeter levels available via Atlas correction service.

#### **Ease of Migration**

Leverage the compact size and easy integration in your design. The 34-pin P326 module is a drop-in upgrade for many Hemisphere products. P327 is a drop-in upgrade for existing designs using standard 20-pin modules from other manufacturers.

Receiver Type: Multi-Frequency GPS, GLONASS, BeiDou, Galileo, QZSS, and Atlas

GPS L1CA/L1P/L1C/L2P/L2C/L5 Signals Received:

GLONASS G1/G2, P1/P2

BeiDou, B1/B2 (B3 separate variant

without L5)

GALILEO E1BC/E5a/E5b QZSS L1CA/L2C/L5/L1C

Channels:

P326/P327 (L5): 572 P326/P327 (B3): 488 **GPS Sensitivity:** -142 dBm

**SBAS Tracking:** 3-channel, parallel tracking

Update Rate: 1 Hz standard, 10 Hz, 20 Hz, or 50Hz

optional (with activation)

Timing (1 PPS)

20 ns Accuracy:

**Cold Start:** 60 s typical (no almanac or RTC) Warm Start: 30 s typical (almanac and RTC) **Hot Start:** 10 s typical (almanac, RTC and

position)

**Antenna Input** 

Impedance: 50 Ω

Maximum Speed: 1,850 mph (999 kts) Maximum Altitude: 18,288 m (60,000 ft)

Accuracy

Positioning: RMS (67%) 2DRMS (95%) Autonomous, no SA: 1 1.2 m 2.5 m SBAS: 1  $0.3 \, \mathrm{m}$ 0.6 m Atlas H10: 1,3  $0.04 \, \text{m}$  $0.08 \, \text{m}$ Atlas H30: 1, 3 0.15 m  $0.3 \, \text{m}$ Atlas Basic: 1,3 1.0 m  $0.50 \, \text{m}$ RTK: 1 8 mm + 1 ppm 15 mm + 2 ppm

**L-Band Receiver Specifications** 

Single Channel Receiver Type: Channels: 1525 to 1560 MHz

Sensitivity: -130 dBm **Channel Spacing:** 5.0 kHz

Satellite Selection: Manual and Automatic **Reacquisition Time:** 15 seconds (typical)

Depends on multipath environment, number of satellites in view, satellite geometry, and ionospheric activity

Depends on multipath environment, number of satellites in view, SBAS coverage, satellite geometry, and ionospheric activity

Hemisphere GNSS proprietary

With future firmware upgrade and activation

CMR and CMR+ do not cover proprietary messages outside of the typical standard



**Communications** 

4x full-duplex 3.3V CMOS Ports:

(3 x main serial ports, 1 x differential-

only port) 1x USB Host 1x USB Device 2x CAN 3.3V CMOS

Interface Level: 4800 - 115200 **Baud Rates:** 

Correction I/O Protocol: Hemisphere GNSS proprietary ROX

format, RTCM v2.3, RTCM v3.2,

CMR5, CMR+5

Data I/O Protocol: NMEA 0183, Crescent binary <sup>3</sup> 1 PPS, CMOS, active high, rising **Timing Output:** 

edge sync,  $10 \text{ k}\Omega$ , 10 pF load**Event Marker Input:** CMOS, active low, falling edge

sync,  $10 \text{ k}\Omega$ , 10 pF load

**Power** 

Input Voltage: 3.3 VDC +/- 5%

**Power Consumption:** 1.0 W nominal GPS (L1)

1.6 W nominal GPS (L1/L2) and

GLONASS (G1/G2)

2.3 W nominal All Signals + L-Band

0.30 A nominal GPS (L1) **Current Consumption:** 

0.48 A nominal GPS (L1/L2) and

GLONASS (G1/G2)

0.70 A nominal All Signals + L-Band 5 VDC maximum

Antenna Voltage: **Antenna Short Circuit** 

**Protection:** 

Antenna Gain Input

Yes

10 to 40 dB Range:

**Environmental** 

Operating Temperature:

Storage Temperature: **Humidity:** 

-40°C to +85°C (-40°F to +185°F) -40°C to +85°C (-40°F to +185°F) 95% non-condensing (when in an

enclosure)

**Mechanical Shock:** EP455 Section 5.14.1

Operational (when mounted in an enclosure with screw mounting

holes utilized)

Vibration: EP455 Section 5.15.1 Random EMC: CE (IEC 60945 Emissions and

Immunity)

FCC Part 15, Subpart B

CISPR 22

Mechanical

**Dimensions:** 

P326: 71 L x 41 W x 10.1 H (mm)  $2.8 L \times 1.6 W \times 0.4 H (in)$ P327: 72 L x 41 W x 10.1 H (mm)  $2.8 L \times 1.6 W \times 0.4 H$  (in)

Weight: 22 g (0.79 oz)

Status Indications (LED): Power, GNSS lock, Differential lock,

DGNSS position

Power/Data Connector:

> P326: 34-pin male header, 0.05" (1.27 mm)

> > pitch

P327: 20-pin male header, 0.08" (2 mm)

pitch

MCX, female, straight **Antenna Connectors:** 

**Hemisphere GNSS** 

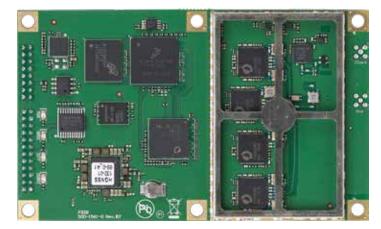
8515 E. Anderson Drive Scottsdale, AZ 85255, USA Phone: +1 (480) 348-6380 Toll-Free: +1 (855) 203-1770 Fax: +1 (480) 270-5070











#### **Key Features**

- Multi-Frequency GPS, GLONASS, BeiDou, Galileo, and QZSS
- Long-range RTK baselines up to 50 km with fast acquisition times
- Compatible with many RTK sources including Hemisphere GNSS' ROX format, RTCM, CMR, CMR+
- Mechanically and electrically (pin-for-pin) compatible with many other manufacturers' modules
- Atlas® L-band capable to 4 cm RMS
- Athena™ GNSS engine providing best-in- class RTK performance
- Serial, USB, Ethernet and CAN connectivity for ease of use and integration

# Track More Signals for the Most Robust Low-Power Multi-Frequency, Multi-GNSS Solution

Track more signals for unparalleled positioning performance with Hemisphere GNSS' new Eclipse P328 OEM board. The latest technology platform enables simultaneous tracking of all satellite signals including GPS, GLONASS, BeiDou, Galileo, QZSS, and L-band making it the most robust and reliable solution for machine control. The power management system efficiently governs the processor, memory, and ASIC making it ideal for multiple integration applications.

# Experience Unparalleled Accuracy and Reliability with Advanced Technology Features

The P328 is the most accurate and reliable OEM module with two new advanced technology features; aRTK™ and Tracer™. Hemisphere's all-new aRTK technology, powered by Atlas, allows the P328 to operate with RTK accuracies when RTK corrections fail. Tracer utilizes specialized algorithms to sustain positioning in the absence of correction data.

#### **Scalable Solutions**

With the Eclipse P328, positioning is scalable and field upgradeable with all Hemisphere software and service options. Utilize the same centimeter-level accuracy in either single frequency mode, or employ the full performance and fast RTK initialization times over long distances with multi-frequency, multi-constellation GNSS signals. High-accuracy L-band positioning from meter to sub-decimeter levels available via Atlas GNSS correction service.

#### **Ease of Migration**

Leverage the industry standard form factor for easy upgradeability from other manufacturers' modules.

Receiver Type: Multi-Frequency GPS, GLONASS, BeiDou, Galileo, QZSS, and Atlas

Signals Received: GPS L1CA/L1P/L1C/L2P/L2C/L5

GLONASS G1/G2, P1/P2

BeiDou B1/B2/B3 GALILEO E1BC/E5a/E5b QZSS L1CA/L2C/L5/L1C

Atlas

Channels: 600 GPS Sensitivity: -142 dBm

SBAS Tracking: 3-channel, parallel tracking
Update Rate: 1 Hz standard, 10 Hz, 20 Hz or 50Hz

optional (with activation)

Timing (1 PPS)

Accuracy: 20 ns

Cold Start:60 s typical (no almanac or RTC)Warm Start:30 s typical (almanac and RTC)Hot Start:10 s typical (almanac, RTC and

position)

Antenna Input

Impedance:  $50 \Omega$ 

 Maximum Speed:
 1,850 mph (999 kts)

 Maximum Altitude:
 18,288 m (60,000 ft)

#### **Accuracy**

Positioning:	RMS (67%)	2DRMS (95%)
Autonomous, no SA: 1	1.2 m	2.5 m
SBAS: 1	0.3 m	0.6 m
Atlas H10: 1, 3	0.04 m	0.08 m
Atlas H30: 1, 3	0.15 m	0.3 m
Atlas Basic: 1,3	0.50 m	1.0 m
RTK: 1	8 mm + 1 ppm	15 mm + 2 ppm

#### **L-Band Receiver Specifications**

**Receiver Type:** Single Channel Channels: 1525 to 1560 MHz

Sensitivity: -130 dBm Channel Spacing: 5.0 kHz

Satellite Selection: Manual and Automatic Reacquisition Time: 15 seconds (typical)

- Depends on multipath environment, number of satellites in view, satellite geometry, and ionospheric activity
- 2. Based on a 40 second time constant
- 3. Hemisphere GNSS proprietary
- With future firmware upgrade and activation
- CMR and CMR+ do not cover proprietary messages outside of the typical standard



#### Communications

**Ports:** 3 x full-duplex

(1 x 3.3V CMOS, 1 x 3.3V CMOS with flow control, 1 x RS-232 with flow

control)
1 x USB Device

1 x Ethernet 10/100Mbps 2 x CAN (NMEA2000, ISO 11783)

Interface Level: 3.3V CMOS Baud Rates: 4800 - 115200

**Correction I/O Protocol:** Hemisphere GNSS proprietary ROX

format, RTCM v2.3, RTCM v3.2,

CMR<sup>5</sup>, CMR+<sup>5</sup>

**Data I/O Protocol:** NMEA 0183, Crescent binary <sup>3</sup> 1 PPS, CMOS, active high, rising

edge sync,  $10 \text{ k}\Omega$ , 10 pF load CMOS, active low, falling edge

sync,  $10 \text{ k}\Omega$ , 10 pF load

**Power** 

Input Voltage: 3.3 VDC +/- 5% Power Consumption: 1.1 W GPS (L1)

1.8 W GPS (L1/L2) and GLONASS

(G1/G2)

2.9 W All Signals + L-band Ourrent Consumption: 0.33 A nominal GPS (L1)

Yes

0.55 A nominal GPS (L1/L2) and

GLONASS (G1/G2)

0.88 A nominal All Signals + L-band 5 VDC maximum

Antenna Voltage: Antenna Short Circuit

Protection:

**Event Marker Input:** 

Antenna Gain Input

Antenna Gain Input

**Range:** 10 to 40 dB

#### **Environmental**

Operating

Temperature: -40°C to +85°C (-40°F to +185°F)

Storage Temperature: -40°C to +85°C (-40°F to +185°F)

Humidity: 95% non-condensing (when in an

enclosure)

Mechanical Shock: EP455 Section 5.14.1

Operational (when mounted in an enclosure with screw mounting

holes utilized)

Vibration: EP455 Section 5.15.1 Random EMC: CE (IEC 60945 Emissions and

Immunity)

FCC Part 15, Subpart B

CISPR 22

Mechanical

**Dimensions:**  $100 L \times 60 W \times 10 H (mm)$ 

3.9 L x 2.4 W x 0.4 (in)

**Weight:** 44 g (1.56 oz)

Status Indications (LED): Power, GNSS lock, Differential lock,

DGNSS position

Power/Data

**Connector:** 24 pin male header 2 mm pitch

16 pin male header 2 mm pitch

Antenna Connectors: MMCX, female, straight

#### **Hemisphere GNSS**

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#### **Key Features**

- Multi-Frequency GPS, GLONASS, BeiDou, Galileo, and QZSS
- Long-range RTK baselines up to 50 km with fast acquisition times
- Compatible with many RTK sources including Hemisphere GNSS' ROX format, RTCM, CMR, CMR+
- Mechanically and electrically (pin-for-pin) compatible with many other manufacturers' modules
- Atlas® L-band capable to 4 cm RMS
- Athena™ GNSS engine providing best-in-class RTK performance
- Serial, USB host (Phantom 34 only), USB device, and CAN connectivity for ease of use and integration

# Track More Signals for the Most Robust Low-Power Multi-Frequency, Multi-GNSS Solution

Track more signals for unparalleled positioning performance with Hemisphere GNSS' new Phantom 20 and 34 OEM boards. The latest technology platform enables simultaneous tracking of all satellite signals including GPS, GLONASS, BeiDou, Galileo, QZSS, IRNSS and L-band making it the most robust and reliable solution for GIS, agriculture, and machine control. The power management system efficiently governs the processor, memory, and ASIC making it ideal for multiple integration applications.

# Experience Unparalleled Accuracy and Reliability with Advanced Technology Features

The Phantom 20 and 34 are the most accurate and reliable OEM modules with two advanced technology features; aRTK™ and Tracer™. Hemisphere's aRTK technology, powered by Atlas, allows the Phantom 20 and 34 to operate with RTK accuracies when RTK corrections fail. Tracer uses specialized algorithms to sustain positioning in the absence of correction data.

#### **Scalable Solutions**

With the Phantom 20 and 34, positioning is scalable and field upgradeable with all Hemisphere software and service options. Use the same centimeter-level accuracy in either single frequency mode, or employ the full performance and fast RTK initialization times over long distances with multi-frequency, multiconstellation GNSS signals. High- accuracy L-band positioning from meter to sub-decimeter levels available via Atlas GNSS correction service.

#### **Ease of Migration**

Leverage the industry standard form factor for easy upgradeability from other manufacturers' modules.

Receiver Type: Multi-Frequency GPS, GLONASS, BeiDou, Galileo, QZSS, and Atlas

GPS L1CA/L1P/L1C/L2P/L2C/L5 Signals Received:

GLONASS G1/G2/G3, P1/P2 BeiDou B1i/B2i/B3i/B10C/B2A/B2B/

**ACEBOC** 

GALILEO E1BC/E5a/E5b/E6BC/

**ALTBOC** 

QZSS L1CA/L2C/L5/L1C/LEX

**IRNSS L5** Atlas +008

Channels: **GPS Sensitivity:** -142 dBm

**SBAS Tracking:** 3-channel, parallel tracking Update Rate: 1 Hz standard, 10 Hz, 20 Hz or 50Hz

optional (with activation)

Timing (1 PPS)

Accuracy: 20 ns

**Cold Start:** 60 s typical (no almanac or RTC) Warm Start: 30 s typical (almanac and RTC) Hot Start: 10 s typical (almanac, RTC and

position)

**Antenna Input** 

Impedance: 50 Ω

Maximum Speed: 1,850 mph (999 kts) Maximum Altitude: 18,288 m (60,000 ft)

#### Accuracy

Positioning: RMS (67%) 2DRMS (95%) Autonomous, no SA: 1 1.2 m 2.5 m SBAS: 1 0.3 m 0.6 m Atlas H10: 1,3  $0.04 \, \text{m}$  $0.08 \, \text{m}$ Atlas H30: 1, 3 0.15 m  $0.3 \, \text{m}$ Atlas Basic: 1,3  $0.50 \, \text{m}$ 1.0 m RTK: 1  $8 \text{ mm} + 1 \text{ ppm} \quad 15 \text{ mm} + 2 \text{ ppm}$ 

#### **L-Band Receiver Specifications**

Single Channel Receiver Type: Channels: 1525 to 1560 MHz

Sensitivity: -130 dBm **Channel Spacing:** 5.0 kHz

Satellite Selection: Manual and Automatic **Reacquisition Time:** 15 seconds (typical)

- Depends on multipath environment, number of satellites in view, satellite geometry, and ionospheric activity
- Depends on multipath environment, number of satellites in view, SBAS coverage, satellite geometry, and ionospheric activity
- Hemisphere GNSS proprietary
- With future firmware upgrade and activation
- CMR and CMR+ do not cover proprietary messages outside of the typical standard



#### Communications

Ports: 4 x full-duplex 3.3V CMOS

(3 x main Serial ports, 1x differential

1 x USB Host (Phantom 34 only)

1 x USB Device

2 x CAN (NMEA2000, ISO 11783)

Interface Level: 3.3V CMOS **Baud Rates:** 4800 - 115200

Correction I/O Protocol: Hemisphere GNSS proprietary ROX

format, RTCM v2.3, RTCM v3.2,

CMR<sup>5</sup>, CMR+<sup>5</sup>

Data I/O Protocol: NMEA 0183, Crescent binary <sup>3</sup> **Timing Output:** 1 PPS, CMOS, active high, rising edge sync,  $10 \text{ k}\Omega$ , 10 pF load**Event Marker Input:** CMOS, active low, falling edge

sync,  $10 \text{ k}\Omega$ , 10 pF load

#### **Power**

3.3 VDC +/- 5% Input Voltage:

Power Consumption: < 1.8 W all signals + L-Band

**Current Consumption:** 545 mA

Antenna Voltage: 5 VDC maximum

**Antenna Short Circuit** 

**Protection:** Yes

Antenna Gain Input

10 to 40 dB Range:

#### **Environmental**

Operatina

Temperature: -40°C to +85°C (-40°F to +185°F) Storage Temperature: -40°C to +85°C (-40°F to +185°F) **Humidity:** 95% non-condensing (when in an

enclosure)

Mechanical Shock: EP455 Section 5.14.1

> Operational (when mounted in an enclosure with screw mounting

holes utilized)

Vibration: EP455 Section 5.15.1 Random CE (IEC 60945 Emissions and EMC:

Immunity)

FCC Part 15, Subpart B

CISPR 22

#### Mechanical

**Dimensions:** 

Phantom 20: 72 L x 41 W x 10 H (mm) 2.8 L x 1.6 W x 0.4 H (in) Phantom 34: 71 L x 41 W x 10 H (mm)  $2.8 L \times 1.6 W \times 0.4 H (in)$ 

22 g (0.79 oz)

Status Indications (LED): Power, GNSS lock, Differential lock,

DGNSS position

Power/Data Connector:

> Phantom 20: 20-pin male header, 0.08" (2 mm)

pitch

Phantom 34: 34-pin male header, 0.05" (1.27

mm) pitch

**Antenna Connectors:** MMCX, female, straight

#### **Hemisphere GNSS**

8515 E. Anderson Drive Scottsdale, AZ 85255, USA

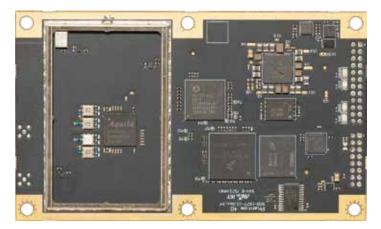
Phone: +1 (480) 348-6380 Toll-Free: +1 (855) 203-1770 Fax: +1 (480) 270-5070











#### **Key Features**

- Multi-Frequency GPS, GLONASS, BeiDou, Galileo, and QZSS
- Long-range RTK baselines up to 50 km with fast acquisition times
- Compatible with many RTK sources including Hemisphere GNSS' ROX format, RTCM, CMR, CMR+
- Mechanically and electrically (pin-for-pin) compatible with many other manufacturers' modules
- Atlas® L-band capable to 4 cm RMS
- Athena™ GNSS engine providing best-in-class RTK performance
- Serial, USB, Ethernet and CAN connectivity for ease of use and integration

# Track More Signals for the Most Robust Low-Power Multi-Frequency, Multi-GNSS Solution

Track more signals for unparalleled positioning performance with Hemisphere GNSS' new Phantom 40 OEM board. The latest technology platform enables simultaneous tracking of all satellite signals including GPS, GLONASS, BeiDou, Galileo, QZSS, IRNSS and L-band making it the most robust and reliable solution for machine control. The power management system efficiently governs the processor, memory, and ASIC making it ideal for multiple integration applications.

# Experience Unparalleled Accuracy and Reliability with Advanced Technology Features

The Phantom 40 is the most accurate and reliable OEM module with two advanced technology features; aRTK™ and Tracer™. Hemisphere's aRTK technology, powered by Atlas, allows the Phantom 40 to operate with RTK accuracies when RTK corrections fail. Tracer uses specialized algorithms to sustain positioning in the absence of correction data.

#### **Scalable Solutions**

With the Phantom 40, positioning is scalable and field upgradeable with all Hemisphere software and service options. Use the same centimeter-level accuracy in either single frequency mode, or employ the full performance and fast RTK initialization times over long distances with multi-frequency, multi-constellation GNSS signals. High-accuracy L-band positioning from meter to sub-decimeter levels available via Atlas GNSS correction service.

#### **Ease of Migration**

Leverage the industry standard form factor for easy upgradeability from other manufacturers' modules.

**Receiver Type:**Multi-Frequency GPS, GLONASS,
BeiDou, Galileo, QZSS, and Atlas

Signals Received: GPS L1CA/L1P/L1C/L2P/L2C/L5

GLONASS G1/G2/G3, P1/P2 BeiDou B1i/B2i/B3i/B10C/B2A/B2B/

**ACEBOC** 

GALILEO E1BC/E5a/E5b/E6BC/

**ALTBOC** 

QZSS L1CA/L2C/L5/L1C/LEX

IRNSS L5 Atlas 800+

Channels: 800+ GPS Sensitivity: -142 dBm

SBAS Tracking: 3-channel, parallel tracking
Update Rate: 1 Hz standard, 10 Hz, 20 Hz or 50Hz

optional (with activation)

Timing (1 PPS)

Accuracy: 20 ns

Cold Start:60 s typical (no almanac or RTC)Warm Start:30 s typical (almanac and RTC)Hot Start:10 s typical (almanac, RTC and

position)

**Antenna Input** 

Impedance:  $50 \Omega$ 

 Maximum Speed:
 1,850 mph (999 kts)

 Maximum Altitude:
 18,288 m (60,000 ft)

#### Accuracy

Positioning: RMS (67%) 2DRMS (95%) Autonomous, no SA: 1 1.2 m 2.5 m SBAS: 1 0.3 m 0.6 m Atlas H10: 1,3  $0.04 \, \text{m}$  $0.08 \, \text{m}$ Atlas H30: 1, 3 0.15 m  $0.3 \, \text{m}$ Atlas Basic: 1,3  $0.50 \, \text{m}$ 1.0 m RTK: 1 8 mm + 1 ppm 15 mm + 2 ppm

#### **L-Band Receiver Specifications**

**Receiver Type:** Single Channel Channels: 1525 to 1560 MHz

Sensitivity: -130 dBm Channel Spacing: 5.0 kHz

Satellite Selection: Manual and Automatic Reacquisition Time: 15 seconds (typical)

- Depends on multipath environment, number of satellites in view, satellite geometry, and ionospheric activity
- Depends on multipath environment, number of satellites in view, SBAS coverage, satellite geometry, and ionospheric activity
- 3. Hemisphere GNSS proprietary
- 4. With future firmware upgrade and activation
- 5. CMR and CMR+ do not cover proprietary messages outside of the typical

#### **Communications**

**Ports:** 3 x full-duplex

(1 x 3.3V CMOS, 1 x 3.3V CMOS with flow control, 1 x RS-232 with flow

control)

1 x USB Host/Device 1 x Ethernet 10/100Mbps 2 x CAN (NMEA2000, ISO 11783)

Interface Level: 3.3V CMOS Baud Rates: 4800 - 115200

Correction I/O Protocol: Hemisphere GNSS proprietary ROX

format, RTCM v2.3, RTCM v3.2,

CMR5, CMR+5

Data I/O Protocol:NMEA 0183, Crescent binary  $^3$ Timing Output:1 PPS, CMOS, active high, rising edge sync,  $10 \text{ k}\Omega$ , 10 pF load

**Event Marker Input:** CMOS, active low, falling edge

sync,  $10 \text{ k}\Omega$ , 10 pF load

**Power** 

Input Voltage: 3.3 VDC +/- 5%

**Power Consumption:** < 1.8 W all signals + L-Band

Current Consumption: 545 mA

**Antenna Voltage:** 5 VDC maximum

Antenna Short Circuit

**Protection:** Yes

Antenna Gain Input

**Range:** 10 to 40 dB

#### **Environmental**

Operating

Temperature: -40°C to +85°C (-40°F to +185°F)
Storage Temperature: -40°C to +85°C (-40°F to +185°F)
Humidity: 95% non-condensing (when in an

enclosure)

Mechanical Shock: EP455 Section 5.14.1

Operational (when mounted in an enclosure with screw mounting

holes utilized)

Vibration: EP455 Section 5.15.1 Random EMC: CE (IEC 60945 Emissions and

Immunity)

FCC Part 15, Subpart B

CISPR 22

Mechanical

Dimensions: 100 L x 60 W x 10 H (mm) 3.9 L x 2.4 W x 0.4 (in)

**Weight:** 44 g (1.56 oz)

Status Indications (LED): Power, GNSS lock, Differential lock,

DGNSS position

Power/Data

**Connector:** 24-pin male header 2 mm pitch 16-pin male header 2 mm pitch

Antenna Connectors: MMCX, female, straight



#### **Hemisphere GNSS**

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# MULTI-GNSS RTK, HIGH-ACCURACY RECEIVER









The R330 GNSS receiver is a full solution product in a compact enclosure. The R330 use the Hemisphere GNSS' Eclipse™ platform and our latest GNSS patented technology. The R330 provides accurate positioning using several differential correction methods such as Athena™RTK, Atlas® L-band corrections (Atlas Basic, H30, H10), Beacon, and SBAS. Our patented Multifunction Application (MFA) firmware allows the R330 to smoothly transition between DGNSS systems.

The R330 GNSS receiver works well in any marine or land application where positioning accuracy is required. The base unit is configured as single frequency, 10 Hz, SBAS, and raw data. The unit can be optionally subscribed to multi-frequency, multi-GNSS, 20 Hz, RTK, Atlas (Atlas Basic, H30, or H10), and Beacon. Compatible GNSS antennas for the R330 are A21, A25, A31, A42, A43, A45 and A52.

The R330 GNSS receiver works with two new advanced technology features; aRTK™ and Tracer™. Hemisphere's aRTK technology, powered by Atlas, allows the R330 to operate with RTK accuracies when RTK corrections fail. Tracer uses specialized algorithms to sustain positioning in the absence of corrections data.

- Atlas® L-band capable to 4 cm RMS
- Athena™ GNSS engine providing best-in- class RTK performance
- Fast update rate of up to 20 Hz
- Status LEDs and menu system make R330 easy to monitor and configure
- USB flash drive for data logaina

Multi-Fregeuncy GPS, GLONASS, BeiDou, Receiver Type:

Galileo, and Atlas

Signals Received: GPS, GLONASS, BeiDou, Galileo, and Atlas

Channels: **GPS Sensitivity:** -142 dBm

**SBAS Tracking:** 3-channel, parallel tracking Update Rate: 10 Hz standard, 20 Hz optional

Timing (1 PPS)

20 ns Accuracy:

**Cold Start:** 60 s typical (no almanac or RTC) Warm Start: 30 s typical (almanac and RTC)

**Hot Start:** 10 s typical (almanac, RTC and position)

Antenna Input

Impedance:

Maximum Speed: 1,850 mph (999 kts)

Maximum

Altitude: 18,288 m (60,000 ft)

Accuracy

Positioning:	RMS (67%)	2DRMS (95%)
Autonomous,		
no SA: 1	1.2 m	2.5 m
SBAS: 2	0.3 m	0.6 m
Atlas H10: 3, 5	0.04 m	0.08 m
Atlas H30: 3, 5	0.15 m	0.30 m
Atlas Basic: 3,5	0.50 m	1.0 m
RTK: 4	8 mm + 1 ppm	15 mm + 2 ppm

#### **Beacon Receiver Specifications**

Channels: 2-channel parallel tracking

Frequency Range: 283.5 to 325.0 kHz

Operating Modes: Manual, Automatic, and Database Compliance: IEC 61108-4 beacon standard

#### **L-Band Receiver Specifications**

Receiver Type: Single Channel Channels: 1525 to 1560 MHz

-130 dBm Sensitivity: Channel Spacing: 5 kHz

Satellite Selection: Manual or Automatic

Reacquisition

Time: 15 sec (typical)

Communications

Ports: 2 x full-duplex (RS-232)

> 1 x USB Host 1 x USB Device 4800 - 115200

**Baud Rates:** Correction I/O

Protocol: Hemisphere GNSS proprietary ROX

format, RTCM v2.3, RTCM v3.2, CMR6,

CMR+6

Data I/O Protocol: NMEA 0183, Hemisphere GNSS binary <sup>5</sup> **Timing Output:** 1 PPS (CMOS, active high, rising edge

sync,  $10 \text{ k}\Omega$ , 10 pF load)

**Event Marker** 

Input: CMOS, active low, falling edge sync, 10

**Power** 

Input Voltage: 8-36 VDC

**Power** 

Consumption: 2.8W nominal All Signals + L-band

Current

Consumption: 0.24 A nominal All Signals + L-band

**Reverse Polarity** Protection: Yes Antenna Voltage

Output: 5 VDC maximum

**Antenna Short** Circuit Protection: Yes

Antenna Gain

10 to 40 dB Input Range:

**Environmental** 

Operating

Temperature:  $-30^{\circ}$ C to +  $70^{\circ}$ C ( $-22^{\circ}$ F to +  $158^{\circ}$ F)

Storage

-40°C to +85°C (-40°F to +185°F) Temperature:

**Humidity:** 95% non-condensing

Mechanical

Shock: EP455 Section 5.41.1 Operational Vibration: EP455 Section 5.15.1 Random

EMC: CE (IEC 60945 Emissions and Immunity)

FCC Part 15, Subpart B

CISPR22

Mechanical

**Dimensions:** 17.8 L x 12.0 W x 4.6 H (cm)

 $7.0 L \times 4.7 W \times 1.8 H (in)$ 

Display:

Weight: 0.65 kg (1.42 lbs)

**Status Indications** 

Power, GNSS lock, Differential lock (LED):

**Power Switch:** Soft Switch Power Connector: 2-pin metal ODU **Data Connector:** 2 x DB9 (female)

2 x USB-A

Antenna

Connector: TNC (female), straight

1. Depends on multipath environment, number of satellites in view, satellite geometry,

2.

Depends on multipath environment, number of satellites in view, satellite geometry, no SA, and ionospheric activity
Depends on multipath environment, number of satellites in view, SBAS coverage and satellite geometry
Requires a subscription
Depends on multipath environment, number of satellites in view, satellite geometry, baseline length (for differential services), and ionospheric activity
Hemisphere GNSS proprietary
CMR and CMR+ do not cover proprietary messages outside of the typical standard

**D**Hemisphere

**Hemisphere GNSS** 

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Provide a reliable source of differential corrections with the SBX-4 radiobeacon board that augments a separate GPS receiver with free accuracy-improving correction data from networks of beacon stations located throughout the world.

With dual-channel architecture to ensure the best station is always being decoded, the SBX-4 delivers high performance reception and a wide range of functionality including the capability to be tuned to signal strength or station distance.

The SBX-4 outputs the industry standard RTCM SC-104 format accepted by differential-ready GPS receivers and can also be configured and monitored with NMEA 0183 protocol.

- Certified IEC 61108-4 compliant
- Dual-channel design allows strongest signal or closest station tracking
- Dual serial ports accommodate separate RTCM and NMEA communications
- Patented ceramic filter blocks out-of-band signals, optimizing reception
- Low power consumption extends battery life
- Power and signal lock LEDs permit visual verification of receiver status
- Reverse-compatibility ensures operation in existing SBX-2 and SBX-3 integrations
- Boot loader provides firmware upgrade reliability

#### **Operating Specifications**

**Channels:** 2-channel parallel tracking

Frequency Range: 283.5 to 325.0 kHz

Channel Spacing: 500 Hz

**MSK Bit Rates:** 50, 100, and 200 bps

Operating Modes: Manual, automatic and database

**Cold Start Time:** < 1 minute typical **Reacquisition Time:** < 2 seconds typical

 $\begin{array}{lll} \textbf{Demodulation:} & \text{Minimum shift keying (MSK)} \\ \textbf{Sensitivity:} & 2.5 \ \mu\text{V/m for 6 dB SNR @ 200 bps} \\ \textbf{Out-of-Band Rejection:} & 60 \ dB < 204 \ kHz \ and > 404 \ kHz \\ \textbf{Spurious Response:} & < -55 \ dB \ (0.1 \ MHz \ to \ 1.6 \ MHz) \\ \end{array}$ 

**Ripple (In-band):** 3 dB **Dynamic Range:** 100 dB

Frequency Offset: ± 8 Hz (~ 27 ppm)

**Adjacent Channel** 

**Rejection:** 61 dB  $\pm$  1 dB @ fo  $\pm$  400 Hz

**Antenna Input** 

Impedance:  $50 \Omega$ 

#### **Communications**

**Ports:** 2x full-duplex

Interface Level: HCMOS, tracks input voltage
Baud Rates: 4800, 9600, 19200, 38400, and 57600

Correction I/O Protocol: RTCM SC-104, NMEA 0183

#### **Environmental**

**Operating** 

Temperature:  $-30^{\circ}\text{C}$  to  $+70^{\circ}\text{C}$  (-22°F to +158°F) Storage Temperature:  $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$  (-40°F to +185°F)

**Humidity:** 95% non-condensing **EMC:** EN50081-4-2 ESD

#### **Power**

**Input Voltage:** 3.3 to 5.5 VDC

Power Consumption:< 0.25 W @ 3.3 VDC (no antenna)</td>Current Consumption:< 70 mA @ 3.3 VDC (no antenna)</td>

**Antenna Voltage:** 5 VDC applied externally

#### Mechanical

**Dimensions:** 7.6 L x 5.1 W x 1.4 H (cm)

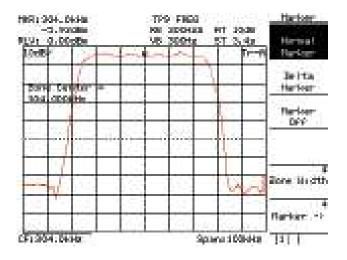
 $3.0 L \times 2.0 W \times 0.54 H$  (in)

**Weight:** 30 g (1.1 oz)

Connector (J1): 1x 4 pin header, 0.1" spacing 2x 12 pin header, 0.1" spacing

#### **Patented Front-End Filter Response**

The front-end filter in the SBX-4 passes beacon frequencies at a consistent strength while blocking out-of band signals. The result is low-noise, high performance beacon reception. The following figure illustrates the frequency response of this filter.



#### **Proprietary Commands**

- Select operating mode
- Query receiver performance and operating status
- Specify communication baud rate up to 57600 bps
- Reset receiver from operation to simulate a cold start
- Tabulate and output results of frequency scan

#### Pin-Out

J200 Connector:

Pin(s): Signal
1, 3: Analog ground
2: Antenna input

4: Antenna power output

J300 Connector:

Pin(s): Signal

1, 2: Antenna power input3, 4: Power supply input14: TXD0, output

**15:** TXD1, output

**16:** Lock indicator (active high)

**17:** RXD0, input **18:** RXD1, input

19: External reset input (active low)

**21, 22, 23, 24:** Digital ground



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# Vector<sup>™</sup> V102 GPS Smart Antenna

# GENERAL NAVIGATION HEADING AND POSITIONING COMPASS





Experience superior navigation from the accurate heading and positioning performance available with the Vector™ V102 GPS compass. The Vector V102 uses SBAS for differential GPS positioning allowing Hemisphere GNSS to provide a highly effective heading and position based smart antenna that out rank any fluxgate compasses.

The rugged low profile enclosure combined with Hemisphere GNSS' Crescent® Vector OEM technology gives portability and simple installation. The compass - measuring less than half-meter length - mounts easily to a flat surface or pole. The stability and maintenance- free design of the Vector V102 provides simple integration into autopilots, chart plotters, and AIS systems.

- Provides heading, positioning, heave, roll, and pitch
- Excellent in-band and out-of-band interference rejection
- 0.75 degree heading accuracy in an amazingly small form factor
- Differential positioning accuracy of 1.0 m, 95% of the time
- Integrated gyro and tilt sensors help deliver fast start-up times and provide heading updates during temporary loss of satellites
- Accurate heading up to 3 minutes during GNSS outages

Receiver Type: Vector GPS L1 Compass

Signals Received: GPS

Channels: Two 12-channel, parallel tracking

(Two 10-channel when tracking SBAS)

**GPS Sensitivity:** -142 dBm

**SBAS Tracking:** 2-channel, parallel tracking Update Rate: 10 Hz standard, 20 Hz optional

Rate of Turn: 90°/s maximum

Compass Safe

Distance: 30 cm 4

**Cold Start:** 60 s (no almanac or RTC) Warm Start: 30 s typical (almanac and RTC)

10 s typical (almanac, RTC and position) **Hot Start:** 

10 s typical (valid position) **Heading Fix:** 

Maximum Speed: 1,850 mph (999 kts)

Maximum

Altitude: 18,288 m (60,000 ft)

Differential

**Options: SBAS** 

Accuracy

RMS (67%) Position:

Autonomous,

no SA: 1 1.2 m SBAS: 2  $0.5 \, \mathrm{m}$ Heading (RMS): 0.75° 1.5° Pitch/Roll (RMS): Heave (RMS): 30 cm <sup>3</sup>

**Communications** 

Ports: 2 full-duplex RS232 **Baud Rates:** 4800 - 115200

Correction I/O

Protocol: RTCM SC-104

Data I/O Protocol: NMEA 0183, NMEA 2000, Hemisphere

Crescent binary 5

**Power** 

6 to 36 VDC Input Voltage:

3.0 W nominal (GPS L1) **Power Consumption: Current Consumption:** 0.25 A nominal (GPS L1) Isolated to enclosure Power Isolation:

**Reverse Polarity** 

**Protection:** Yes

**Environmental** 

Operating

 $-30^{\circ}$ C to + 70°C (-22°F to + 158°F) Temperature: **Storage Temperature:**  $-40^{\circ}$ C to + 85°C (-40°F to + 185°F)

**Humidity:** 

95% non-condensing **Mechanical Shock:** EP455 Section 5.14.1

Vibration: EMC:

EP455 Section 5.15.1 Random CE (IEC 60945 Emissions and

Immunity) FCC Part 15, Subpart B,

CISPR22

Mechanical

**Dimensions:** 41.7 L x 15.8 W x 6.9 H (cm) 16.4 L x 6.2 W x 2.7 H (in)

Weight: 1.5 kg (3.3 lbs.)

**Status Indications** 

(LED): Power, GNSS Lock, Heading

Power/Data

Connector: 12-pin, Female, IP67

**Aiding Devices** 

Gyro: Provides smooth heading, fast

> heading reacquisition and reliable 1° per minute heading for periods up to 3 minutes when loss of GPS

has occurred

**Tilt Sensors:** Provide pitch and roll data and

assist in fast start-up and

reacquisition of heading solution

Hemisphere GNSS proprietary



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Depends on multipath environment, number of satellites in view, satellite geometry, no SA, and ionospheric activity

Depends on multipath environment, number of satellites in view, WAAS coverage and satellite geometry

Based on a 40 second time constant

This is the minimum safe distance measured when the product is placed in the vicinity of the steering magnetic compass. The ISO 694 defines "vicinity" relative to the compass as within 5 m (16.4 ft) separation



# Vector<sup>™</sup> V104 GPS Smart Antenna







Vector™ V104 GPS Smart Antenna offers superior navigation including accurate positioning and heading performance. V104 uses SBAS (WAAS, EGNOS, MSAS, etc.) for differential GPS position allowing Hemisphere GNSS to provide a low cost and highly effective positioning and heading based smart antenna.

The rugged and low-profile enclosure combines Hemisphere GNSS' Crescent® Vector technology and two multi-path resistant antennas for accuracy, portability and simple installation. The smart antenna, measuring approximately 25 cm in length, mounts easily to a flat surface or pole. The stability and maintenance-free design of V104 provides traditional GPS position and heading at a low cost, replacing the combination of low-accuracy GPS and fluxgate compass.

- Provides position, heading, pitch, roll, and heave
- Excellent in-band and out-of-band interference rejection
- 2° (RMS) heading accuracy in an amazingly small form factor
- Integrated gyro and tilt sensors deliver fast start up times and provide heading updates during temporary loss of GPS and satellites
- Differential position accuracy of 1m, 95% of the time
- Accurate heading for up to 3 minutes during GNSS outages
- Offered as a Serial or NMEA 2000 version

Vector GPS L1 Compass Receiver Type:

Signals Received: GPS Channels:

-142 dBm **GPS Sensitivity:** 

2-channel, parallel tracking **SBAS Tracking:** Update Rate: 10 Hz standard, 20 Hz optional

Rate of Turn: 90°/s maximum

Compass Safe

Distance: 30 cm <sup>4</sup>

Cold Start: 60 s (no almanac or RTC) Warm Start: 30 s typical (almanac and RTC)

**Hot Start:** 10 s typical (almanac, RTC and position)

10 s typical (valid position) **Heading Fix:** 

Maximum Speed: 1,850 mph (999 kts)

Maximum

Altitude: 18,288 m (60,000 ft)

Accuracy

RMS (67%) Position:

Autonomous,

no SA: 1 1.5 m SBAS: 2  $0.5 \, \text{m}$ Heading (RMS):  $2^{\circ}$ 2° Pitch/Roll (RMS): Heave (RMS): 30 cm <sup>3</sup>

**Communications** 

2 full-duplex RS232 6 or 1 NMEA 2000  $^{7}$ Ports:

**Baud Rates:** 4800 - 115200

Correction I/O

RTCM SC-104 Protocol:

Data I/O Protocol: NMEA 0183 <sup>6</sup>, NMEA 2000 <sup>7</sup>, Hemisphere

Crescent binary 5

**Power** 

Input Voltage: 8-36 VDC

**Power** 

Consumption: ~ 2.0 W nominal

Current

Consumption: 0.16 A @ 12 VDC Power Isolation: Isolated to enclosure

**Reverse Polarity** 

**Protection:** Yes **Environmental** 

Operating

Temperature:  $-30^{\circ}$ C to + 70°C (-22°F to + 158°F)  $-40^{\circ}$ C to + 85°C (-40°F to + 185°F) Storage Temperature:

**Humidity:** 100% non-condensing

**Mechanical Shock:** IEC 60945 Vibration: IEC 60945

EMC: CE (IEC 60945 Emissions and

Immunity), FCC Part 15 Subpart B,

CISPR22

IP Rating: **IP69** 

**Enclosure:** UV resistant, white plastic, Geloy

CR7520 (ASA)

Mechanical

**Dimensions:** 

Not including mount:  $25.9 L \times 12.9 W \times 4.5 H (cm) 10.2 L \times 12.9 W \times 4.5 H (cm) 10.2 L \times 12.9 W \times 4.5 H (cm) 10.2 L \times 12.9 W \times 4.5 H (cm) 10.2 L \times 12.9 W \times 4.5 H (cm) 10.2 L \times 12.9 W \times 4.5 H (cm) 10.2 L \times 12.9 W \times 4.5 H (cm) 10.2 L \times 12.9 W \times 4.5 H (cm) 10.2 L \times 12.9 W \times 4.5 H (cm) 10.2 L \times 12.9 W \times 4.5 H (cm) 10.2 L \times 12.9 W \times 4.5 H (cm) 10.2 L \times 12.9 W \times 4.5 H (cm) 10.2 L \times 12.9 W \times 4.5 H (cm) 10.2 L \times 12.9 W \times 4.5 H (cm) 10.2 L \times 12.9 W \times 4.5 H (cm) 10.2 L \times 12.9 W \times 4.5 H (cm) 10.2 L \times 12.9 W \times 4.5 H (cm) 10.2 L \times 12.9 W \times 4.5 H (cm) 10.2 L \times 12.9 W \times 4.5 H (cm) 10.2 L \times 12.9 W \times 4.5 H (cm) 10.2 L \times 12.9 W \times 4.5 H (cm) 10.2 L \times 12.9 W (cm) 10.2 L$ 

5.1 W x 1.8 H (in)

Including mount: 25.9 L x 12.9 W x 12.8 H (cm) 10.2 L x

5.1 W x 5.0 H (in)

Weight:

Not including mount: 0.4 kg (0.9 lb) Including mount: 0.5 kg (1.1 lb)

Power/Data

Connector: 8-pin Male for Serial or 5 Pin Male

NMEA 2000 Micro connector

**Aiding Devices** 

Gyro: Provides smooth heading, fast

> heading reacquisition and reliable 2° per minute heading for periods up to 3 minutes when loss of GPS

has occurred

**Tilt Sensors:** Provide pitch and roll data, assist in

fast start-up and reacquisition of

heading solution

Depends on multipath environment, number of satellites in view, satellite geometry, no SA, and ionospheric activity

Depends on multipath environment, number of satellites in view, SBAS coverage and satellite geometry

Based on a 40-second time constant

This is the minimum safe distance measured when the product is placed in the vicinity of the steering magnetic compass. The ISO 694 defines "vicinity" relative to the compass as within 5 m (16.4 ft) separation

Hemisphere GNSS proprietary

Serial model only

NMEA 2000 model only



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# Vector<sup>™</sup> V123 & V133 GNSS Smart Antennas







The Vector™ V123/133 is Hemisphere GNSS' all-in-one single-frequency, multi-GNSS smart antenna which provides Atlas decimeter-level position and precise heading. This rugged design is sealed for the harshest environments and is a great solution for professional marine and other challenging applications.

The all-in-one V123/133 combines simple installation with consistent and precise heading accuracy and decimeter positioning.

- Simple all-in-one single-frequency, multi-GNSS heading solution
- Single-frequency GPS/GLONASS/ BeiDou/Galileo QZSS
- Atlas® L-band and beacon (V133) capable
- Integrated gyroscope provides smooth, fast heading reacquisition
- Reliable < 1° per minute heading for periods up to 3 minutes when loss of GNSS has occurred
- Fully rugged solution for the harshest environments

**Receiver Type:** Vector GNSS Receiver

Signals Received: GPS, GLONASS, BeiDou, Galileo, QZSS 7,

and Atlas 6

Channels: 424 GPS Sensitivity: -142 dBm

SBAS Tracking: 2-channel, parallel tracking
Update Rate: 20 Hz standard, 50 Hz optional

Timing (1 PPS)

Accuracy: 20 ns

Rate of Turn: 100°/s maximum

Compass Safe

**Distance:** 50 cm <sup>4</sup>

Cold Start: 60 s (no almanac or RTC)
Warm Start: 30 s typical (almanac and RTC)

Hot Start: 10 s typical (almanac, RTC and position)

**Heading Fix:** 10 s typical (valid position)

Antenna Input

Impedance:  $50 \Omega$ 

Maximum Speed: 1,850 mph (999 kts)

Maximum

Altitude: 18,288 m (60,000 ft)

Differential
Options: SBAS, Atlas (L-band)

Accuracy

Position: RMS (67%)

Autonomous,

no SA: 1 1.2 m SBAS: 2 0.3 m Atlas (L-Band): 6 0.3 m Heading (RMS): 0.3° Pitch/Roll (RMS): 1°

**Heave (RMS):** 30 cm (DGPS) <sup>3</sup>,10 cm (Atlas) <sup>6</sup>

**Beacon Receiver Specifications** 

**Channels:** 2-channel, parallel tracking 8

Frequency Range: 283.5 to 325 kHz 8

**Operating Modes:** Manual, Automatic, and Database <sup>8</sup> **Compliance:** IEC 61108-4 beacon standard <sup>8</sup>

**L-Band Receiver Specifications** 

Receiver Type: Single Channel
Channels: 1525 to 1560 MHz
Sensitivity: -130 dBm

Sensitivity: -130 dl Channel Spacing: 5 kHz

Satellite Selection: Manual or Automatic

Reacquisition

**Time:** 15 sec (typical)

- Depends on multipath environment, number of satellites in view, satellite geometry, no SA, and ionospheric activity
- Depends on multipath environment, number of satellites in view, WAAS coverage and satellite geometry
- Based on a 40-second time constant
- 4. This is the minimum safe distance measured when the product is placed in the vicinity of the steering magnetic compass. The ISO 694 defines "vicinity" relative to the compass as within 5 m (16.4 ft) separation
- 5. Hemisphere GNSS proprietary
- 6. Requires a Hemisphere GNSS subscription
- With future firmware upgrade and activation
- 8. V133 only



**Communications** 

Ports: 1x RS232, 1x RS422, 1x half-duplex

RS422(TX), NMEA2000

Baud Rates: Correction I/O

**Protocol:** Atlas, Hemisphere GNSS proprietary,

4800 - 115200

RTCM v2.3 (DGPS)

**Data I/O Protocol:** NMEA 0183, NMEA 2000, Hemisphere GNSS binary

**Timing Output:** 1 PPS (active high, rising edge sync,  $10 \text{ k}\Omega$ , 10 pF load)

**Event Marker Input:** Active low, falling edge sync,  $10 \text{ k}\Omega$ , 10 pF load

**Heading Warning I/O:** Open relay system indicates invalid

heading

**Power** 

**Input Voltage:** 9 - 36 VDC with reverse polarity

operation

**Power Consumption:** (multi-GNSS, typical continuous

draw @ 12V)

V123 3.9 W - 4.3 W V133 - 4.2 W 4.36 W Current Consumption: (multi-GNSS, typical continuous

draw @ 12V)

 SBAS
 Beacon
 Atlas

 V123
 0.33 A
 0.36 A

 V133
 0.35 A
 0.38 A

Reverse Polarity Protection:

Yes

**Environmental** 

Operating Temperature:

Storage Temperature:

Humidity:
Vibration:

Vibration: IEC60945 Section 8.7
EMC: IEC60945 FCC part 15 Subpart B,

CISPR32

IMO Wheelmark

Certification: MED/4.41 Transmitting Heading Device THD (GNSS Method)

Enclosure: IP66/IP69

Mechanical

**Dimensions:** 66.5 L x 20.8 W x 14.6 H (cm) 26.2 L x 8.2 W x 5.8 H (in)

Weight:

**V123** 2.1 kg (4.6 lb) **V133** 2.4 kg (5.4 lb)

**Status Indications** 

(LED):

Power/Data

**Connector:** 18-pin environmentally sealed

Power

**Aiding Devices** 

Gyro:

Integrated gyroscope provides smooth heading, fast heading reacquisition and reliable < 1° per minute heading for periods up to 3 minutes when loss of GNSS has

 $-40^{\circ}$ C to + 70°C (-40°F to + 158°F) -40°C to + 85°C (-40°F to + 185°F)

95% non-condensing

occurred

**Tilt Sensors:** Provide pitch, roll data and assist in

fast start-up and reacquisition of

heading solution

**Hemisphere GNSS** 

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# GENERAL NAVIGATION HEADING AND POSITIONING COMPASS







Experience superior navigation from the accurate heading and positioning performance available with the Vector™ V200 GNSS compass. The multi-GNSS Vector V200 supports GPS, GLONASS, BeiDou, Galileo, and QZSS and offers an amazing world-wide 30 cm (RMS) accuracy via Hemisphere's Atlas GNSS global correction service.

The Vector V200 offers an incredible combination of simple installation, small form factor, and amazing performance. The compass - measuring only 35 cm in length - mounts easily to a flat surface or pole. The stability and maintenance-free design of the Vector V200 provides simple integration into autopilots, chart plotters, and AIS systems.

- L1 GPS, GLONASS, Galileo, BeiDou, QZSS
- 30 cm RMS world-wide positioning accuracy with Atlas corrections
- 0.75 degree heading accuracy in an amazingly small form factor
- Excellent in-band and out-of-band interference rejection
- Integrated gyro and tilt sensors help deliver fast start-up times and provide heading updates during temporary loss of satellites
- Provides heading, positioning, heave, roll, and pitch

**GNSS Sensor Specifications** 

**Receiver Type:** Vector GNSS L1 Receiver

Signals Received: GPS, GLONASS, BeiDou, Galileo, QZSS 7,

and Atlas

Channels: 424 GPS Sensitivity: -142 dBm

SBAS Tracking: 2-channel, parallel tracking
Update Rate: 10 Hz standard, 20 Hz optional

Timing (1 PPS)

Accuracy: 20 ns <sup>6</sup>

Rate of Turn: 100°/s maximum

Compass Safe

**Distance:** 50 cm <sup>4</sup>

Cold Start: 60 s (no almanac or RTC)
Warm Start: 30 s typical (almanac and RTC)

**Hot Start:** 10 s typical (almanac, RTC and position)

**Heading Fix:** 10 s typical (valid position)

Maximum Speed: 1,850 mph (999 kts) Maximum Altitude: 18,288 m (60,000 ft) Differential Options: SBAS, Atlas (L-band)

Accuracy

Positioning: RMS (67%) 2DRMS (95%)

Autonomous,

**no SA:** <sup>1</sup> 1.2 m SBAS: <sup>2</sup> 0.3 m

**Atlas: 6** - 0.3 m **Heading (RMS):** 1.5° 0.75°

Pitch/Roll (RMS): 1°

**Heave (RMS):** 30 cm (DGPS) <sup>3</sup> 30 cm (Atlas)

**L-Band Receiver Specifications** 

**Receiver Type:** Single Channel Channels: 1525 to 1560 MHz

**Sensitivity:** -130 dBm **Channel Spacing:** 5 kHz

Satellite Selection: Manual or Automatic Reacquisition Time: 15 sec (typical)

**Communications** 

Ports:

**5-pin:** NMEA2000

**12-pin:** RS-232 (2 Tx, 2 Rx), RS-422 (1 Tx), 1 PPS or

RS-422 (2 Tx, 1 Rx), 1 PPS

**Baud Rates:** 4800 - 115200

Correction I/O

Protocol: RTCM SC-104

Data I/O Protocol:

**5-pin:** NMEA 2000

**12-pin:** NMEA 0183, Crescent binary <sup>5</sup> Timing Output: 1 PPS (CMOS, rising edge sync <sup>6</sup>)

**O**Hemisphere®

**Power** 

**Input Voltage:** 6 to 36 VDC

**Power Consumption:** (multi-GNSS, typical continuous

draw @ 12V)

**SBAS:** 3.2 W **Atlas:** 3.6 W

**Power Isolation:** Isolated to enclosure

**Reverse Polarity** 

**Protection:** Yes

**Environmental** 

Operating

Temperature:  $-40^{\circ}\text{C}$  to  $+70^{\circ}\text{C}$  ( $-40^{\circ}\text{F}$  to  $+158^{\circ}\text{F}$ ) Storage Temperature:  $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$  ( $-40^{\circ}\text{F}$  to  $+185^{\circ}\text{F}$ )

**Humidity:** 95% non-condensing

Enclosure: ISO 60529:2013 for IPx6/IPx7/IPx9
Vibration: IEC 60945:2002 Section 8.7 Vibration

**EMC:** IEC60945:2002

EN 301 489-1 V2.1.1 EN 301 489-5 V2.1.1 EN 301 489-19 V2.1.0 EN 303 413 V1.1.1

Mechanical

**Dimensions: No Mount:**34.8 L x 15.8 W x 7.5

 No Mount:
 34.8 L x 15.8 W x 7.5 H (cm)

 LP Flat Mount:
 34.8 L x 15.8 W x 7.6 H (cm)

 HP Flat Mount:
 34.8 L x 15.8 W x 10.7 H (cm)

 Pole Mount:
 34.8 L x 15.8 W x 16.8 H (cm)

Weight:

Not including Mount: 0.75 kg (1.7 lb) Including Mount: 0.94 kg (2.1 lb)

Power/Data

**Connector:** 5-pin or 12-pin

**Aiding Devices** 

**Gyro:** Provides smooth heading, fast

heading reacquisition and reliable 1° per minute heading for periods up to 3 minutes when loss of GPS

has occurred 4

**Tilt Sensors:** Provide pitch and roll data and

assist in fast start-up and

reacquisition of heading solution

 Depends on multipath environment, number of satellites in view, satellite geometry, no SA, and ionospheric activity

 Depends on multipath environment, number of satellites in view, WAAS coverage and satellite geometry

Based on a 40 second time constant

4. This is the minimum safe distance measured when the product is placed in the vicinity of the steering magnetic compass. The ISO 694 defines "vicinity" relative to the compass as within 5 m (16.4 ft) separation

5. Hemisphere GNSS proprietary

6. V200s only

7. With future firmware upgrade and activation

**Hemisphere GNSS** 

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# Vector™ V320 GNSS Smart Antenna







Vector™ V320 is the first all-in-one multi-frequency, multi-constellation GNSS smart antenna, which provides RTK level position and precise heading. Using Hemisphere's patented Eclipse™ Vector GNSS technology, V320 is a strong addition to our V family. The rugged IP69 design housing is sealed for the harshest environments. It incorporates fixed and pole mounting capability for both marine and land applications. The Vector V320 is series are suitable for both dynamic positioning and professional marine survey. The V320 provides a great solution for machine control and other challenging applications.

The all-in-one V320 smart antenna can be installed in various environments. With a set separation, the V320 provides consistent and reliable position and heading accuracy. The Vector V320 can use Atlas L-band and SBAS (WAAS, EGNOS, MSAS, etc.) for differential GNSS position.

- Simple all-in-one RTK-capable heading solution
- Athena<sup>™</sup> and Atlas<sup>®</sup> capable
- Multi frequency GPS/GLONASS/BeiDou RTK capable
- Maintain position and heading lock when more of the sky is blocked
- Accurate heading with a precise baseline
- Integrated gyro and tilt sensors deliver fast start up times and provide heading updates during temporary loss of satellites

Vector GNSS RTK Receiver Receiver Type:

Signals Received: GPS, GLONASS, BeiDou, and Atlas

Channels: **GPS Sensitivity:** -142 dBm

**SBAS Tracking:** 3-channel, parallel tracking Update Rate: 10 Hz standard, 20 Hz optional

Timing (1 PPS)

Accuracy:  $20 \, \mathrm{ns}$ 

Rate of Turn: 100°/s maximum

Compass Safe

Distance: 30 cm (with enclosure) **Cold Start:** 60 s (no almanac or RTC) 30 s typical (almanac and RTC) Warm Start:

**Hot Start:** 10 s typical (almanac, RTC and position)

10 s typical (valid position) **Heading Fix:** 

**Antenna Input** 

Impedance:

Maximum Speed: 1,850 mph (999 kts)

Maximum

Altitude: 18,288 m (60,000 ft)

Accuracy

Position: RMS (67%) 2DRMS (95%)

Single Point: 1 1.2 m 2.5 m SBAS: 2  $0.3 \, \text{m}$ 0.6 m **Atlas (L-Band): 6** 0.08 m 0.16 m

**RTK:** 1, 3 10 mm + 1 ppm 20 mm + 2 ppm

Heading (RMS): 0.2° Pitch/Roll (RMS):

Heave (RMS): 30 cm (DGPS) 5,10 cm (RTK) 2,4

**L-Band Receiver Specifications** 

Receiver Type: Single Channel Channels: 1530 to 1560 MHz

Sensitivity: -130 dBm Channel Spacing: 5 kHz

Satellite Selection: Manual or Automatic

Reacquisition

Time: 15 sec (typical)

Communications

Ports: 1 full-duplex RS-232; 1 full-duplex RS-422

and 1 half-duplex RS-422 (Tx only)

**Baud Rates:** 4800 - 115200

Correction I/O

Protocol: Hemisphere GNSS proprietary ROX

format, RTCM v2.3, RTCM v3.2, CMR7,

CMR+7

Data I/O Protocol: NMEA 0183, NMEA 2000, Crescent binary <sup>5</sup>

**Timing Output:** 1 PPS (active high, rising edge sync, 10

 $k\Omega$ , 10 pF load)

**Heading Warning** 

Open relay system indicates invalid 1/0:

heading

**Power** 

8 - 36 VDC Input Voltage:

6.10 W nominal (GPS L1/L2) **Power Consumption:** 

7.25 W nominal (GPS L1/L2 +

GLONASS L1/L2)

8.50 W nominal (GPS L1/L2 +GLONASS L1/L2 + BeiDou B1/B2) 9.50 W nominal (GPS L1/L2 + GLONASS L1/L2 + BeiDou B1/B2 +

L-band)

Power Isolation: Yes

**Reverse Polarity** 

**Protection:** Yes

**Environmental** 

Operating

 $-30^{\circ}$ C to + 70°C (-22°F to + 158°F) Temperature: Storage Temperature:  $-40^{\circ}$ C to + 85°C (-40°F to + 185°F)

**Humidity:** 95% non-condensing **Mechanical Shock:** EP455 Section 5.14.1

Vibration: EP455 Section 5.15.1 Random EMC: CE (IEC 60945 Emissions and

Immunity) FCC Part 15, Subpart B

CISPR22

**Enclosure: IP69** 

Mechanical

**Dimensions:** 66.3 L x 20.9 W x 14.6 H (cm)

26.1 L x 8.3 W x 5.8 H (in)

Weight: 2.1 kg (4.6 lb)

**Status Indications** 

(LED): Power Power/Data

Connector: 18-pin environmentally sealed

**Aiding Devices** 

Provides heading smoothing with Gyro:

> GNSS. Drift rate is 1° per minute in heading for periods up to 3 minute when loss of GNSS has occurred <sup>3</sup> Provide pitch and roll data and

**Tilt Sensors:** 

assist in fast start-up and

reacquisition of heading solution

Depends on multipath environment, number of satellites in view, satellite geometry, no SA, and ionospheric activity.

Depends on multipath environment, number of satellites in view, WAAS coverage and satellite geometry

Depends on multipath environment, number of satellites in view, satellite geometry, baseline length (for differential services), and ionospheric activity.

Based on a 40 second time constant

Hemisphere GNSS proprietary

Requires a Hemisphere GNSS subscription

CMR and CMR+ do not cover proprietary messages outside of the typical standard



**Hemisphere GNSS** 

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# Vector<sup>™</sup> V500 GNSS Smart Antenna









The Vector V500 is Hemisphere GNSS' all-in-one multi-frequency, multi-GNSS smart antenna which provides RTK-level position and precise heading. This rugged design is sealed for the harshest environments and is a great solution for professional marine and other challenging applications.

The all-in-one V500 combines simple installation with consistent and precise heading accuracy and RTK positioning.

- Simple all-in-one RTK-capable
- Multi-frequency GPS/GLONASS/BeiDou/Galileo/ QZSS/IRNSS
- Athena™ RTK and Atlas® L-band capable
- Supports Ethernet, CAN, Serial, Bluetooth, and Wi-Fi
- Powerful WebUI accessed via Wi-Fi
- Fully rugged solution for the harshest environments

**Receiver Type:** Vector GNSS RTK Receiver

Signals Received: GPS, GLONASS, BeiDou, Galileo, QZSS 7,

IRNSS 7, and Atlas

Channels: 1059
GPS Sensitivity: -142 dBm

SBAS Tracking: 2-channel, parallel tracking
Update Rate: 10 Hz standard, 20 Hz optional

Timing (1 PPS)

Accuracy: 20 ns

**Rate of Turn:** 100°/s maximum

Cold Start: 60 s (no almanac or RTC)
Warm Start: 30 s typical (almanac and RTC)

Hot Start: 10 s typical (almanac, RTC and position)

**Heading Fix:** 10 s typical (valid position)

**Antenna Input** 

Impedance:  $50 \Omega$ 

Maximum Speed: 1,850 mph (999 kts)

Maximum

**Altitude:** 18,288 m (60,000 ft)

**Differential** 

**Options:** SBAS, Atlas (L-band), RTK

Accuracy

Position: RMS (67%) 2DRMS (95%)

 Single Point: 1
 2.4 m

 SBAS: 2
 0.6 m

 Atlas H10: 6
 0.08 m
 0.16 m

 Atlas H30: 6
 0.3 m

 Atlas Basic: 6
 0.5 m

**RTK:** 1,3 8 mm + 1 ppm 15 mm + 2 ppm

Heading (RMS): 0.27° Pitch/Roll (RMS): 1°

**Heave (RMS):** 30 cm (DGPS) <sup>1</sup>,10 cm (Atlas) <sup>1,6</sup>,

5 cm (RTK) 1,6

**L-Band Receiver Specifications** 

Channels: 1525 to 1560 MHz

Sensitivity: -130 dBm Channel Spacing: 5 kHz

Satellite Selection: Manual or Automatic

Reacquisition

Time: 15 sec (typical)

**Communications** 

**Ports:** 1x full-duplex RS-232/RS-422, 1x RS232, 2x

CAN, 1x Ethernet

**Baud Rates:** 4800 - 115200

Radio Interfaces: Bluetooth 2.0 (Class 2), Wi-Fi 2.4 GHz

Correction I/O

**Protocol:** Hemisphere GNSS proprietary ROX

format, RTCM v2.3, RTCM v3.2, CMR8,

CMR+8

Data I/O Protocol: NMEA 0183, Hemisphere GNSS binary

Timing Output:

1 PPS (CMOS, rising edge sync)

**Event Marker** 

**Input:** Open drain, falling edge sync,  $10 \text{ k}\Omega$ , 10

pF load

**Power** 

Input Voltage: 9 - 32 VDC
Power Consumption: 7.5 W maximum
1.8 A maximum

No

Power Isolation: Reverse Polarity

Protection: Yes

**Environmental** 

Operating

Temperature:  $-40^{\circ}\text{C}$  to  $+70^{\circ}\text{C}$  ( $-40^{\circ}\text{F}$  to  $+158^{\circ}\text{F}$ ) Storage Temperature:  $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$  ( $-40^{\circ}\text{F}$  to  $+185^{\circ}\text{F}$ )

**Humidity:** 95% non-condensing

Enclosure: ISO 60529:2013 for IPx6/IPx7/IPx9
Vibration: IEC 60945:2002 Section 8.7 Vibration

**EMC:** IEC60945:2002

EN 301 489-1 V2.1.1 EN 301 489-5 V2.1.1 EN 301 489-19 V2.1.0 EN 303 413 V1.1.1

Mechanical

**Dimensions:** 68.6 L x 22.0 W x 12.3 H (cm) 27.0 L x 8.7 W x 4.8 H (in)

**Weight:** 3.7 kg (8.2 lb)

**Status Indications** 

(LED): Power, GNSS Lock, Heading

Power/Data

**Connector:** 22-pin environmentally sealed

**Aiding Devices** 

**Gyro:** Provides smooth heading, fast

heading reacquisition and reliable < 1° per min heading for periods up to 3 min. when loss of GPS has

occurred 4

**Tilt Sensors:** Provide pitch, roll data and assist in

fast start-up and reacquisition of

heading solution

Depends on multipath environment, number of satellites in view, satellite geometry, no SA,
 and inspersh aris pativity.

and ionospheric activity

 Depends on multipath environment, number of satellites in view, WAAS coverage and satellite geometry

 Depends on multipath environment, number of satellites in view, satellite geometry, baseline length (for differential services), and ionospheric activity

length (for differential services), and ionosphe

Based on a 40 second time constant

5. Hemisphere GNSS proprietary

6. Requires a Hemisphere GNSS subscription

7. With future firmware upgrade and activation

8. CMR and CMR+ do not cover proprietary messages outside of the typical standard



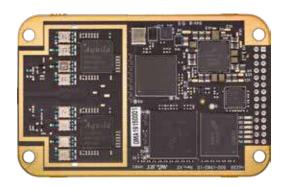
#### **Hemisphere GNSS**

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Develop sophisticated machine control and navigation solutions in a complex world full of dynamic environments. The Vega 28 is one of our most advanced GNSS heading and positioning boards.

The Vega 28 uses dual antenna ports to create a series of additional capabilities including fast, high-accuracy heading over short baselines, RTK positioning, onboard Atlas L-band, RTK-enabled heave, low-power consumption, and precise timing.

#### **Scalable Solutions**

With the Vega 28, positioning is scalable and field upgradeable with all Hemisphere software and service options. Utilize the same centimeter-level accuracy in either single frequency mode, or employ the full performance and fast RTK initialization times over long distances with multi-frequency multi-constellation GNSS signals. High-accuracy L-band positioning from meter to sub-decimeter levels available via Atlas correction service.

#### **Ease of Migration**

Leverage the industry standard form factor for easy upgradeability from other manufacturers' modules.

- Extremely accurate heading with long baselines
- Multi-frequency position, dual-frequency heading supporting GPS, GLONASS, BeiDou, Galileo, QZSS, IRNSS, and L-band
- Atlas® L-band capable to 4 cm RMS
- Athena™ GNSS engine providing best-in-class RTK performance
- Excellent coasting performance
- 5 cm RMS RTK-enabled heave accuracy
- Strong multipath mitigation and interference rejection
- New multi-axis gyro and tilt sensor for reliable coverage during short GNSS outages

Receiver Type: Multi-Frequency GPS, GLONASS,

BeiDou, Galileo, QZSS, and Atlas GPS L1CA/L1P/L1C/L2P/L2C/L5 Signals Received:

GLONASS G1/G2/G3, P1/P2 BeiDou B1i/B2i/B3i/B10C/B2A/B2B/

**ACEBOC** 

GALILEO E1BC/E5a/E5b/E6BC/

**ALTBOC** 

QZSS L1CA/L2C/L5/L1C/LEX

**IRNSS L5** Atlas 1,100+

Channels: **GPS Sensitivity:** -142 dBm

**SBAS Tracking:** 3-channel, parallel tracking **Update Rate:** 10 Hz standard, 1 Hz or 20 Hz optional (with activation)

Timing (1 PPS)

Accuracy: 20 ns

Rate of Turn: 100°/s maximum

Cold Start: 60 s typical (no almanac or RTC) Warm Start: 30 s typical (almanac and RTC) **Hot Start:** 10 s typical (almanac, RTC and

position)

**Heading Fix:** 10 s typical (Hot Start)

Antenna Input

50 Ω Impedance:

Maximum Speed: 1,850 mph (999 kts) 18,288 m (60,000 ft) Maximum Altitude:

Accuracy

2DRMS (95%) Positioning: RMS (67%) Autonomous, no SA: 1 1.2 m  $2.5 \, \mathrm{m}$ 0.3 m SBAS: 0.6 m Atlas H10: 1,3 0.04 m  $0.08 \, \text{m}$ Atlas H30: 1, 3  $0.15 \, \text{m}$  $0.3 \, \mathrm{m}$ Atlas Basic: 1,3 1.0 m 0.50 m

RTK: 1 8 mm + 1 ppm 15 mm + 2 ppm

Heading (RMS): 0.16° rms @ 0.5 m antenna

separation

0.08° rms @ 1.0 m antenna

separation

0.04° rms @ 2.0 m antenna

separation

0.02° rms @ 5.0 m antenna

separation

Pitch/Roll (RMS): 0.5°

Heave (RMS): 1 30 cm rms (DGNSS), 5 cm rms (RTK)

L-Band Receiver Specifications

Receiver Type: Single Channel Channels: 1525 to 1560 MHz

Sensitivity: -130 dBm Channel Spacing: 5.0 kHz

Satellite Selection: Manual and Automatic **Reacquisition Time:** 15 seconds (typical)

Depends on multipath environment, number of satellites in view, satellite geometry, and ionospheric activity

- Depends on multipath environment, number of satellites in view, SBAS coverage satellite geometry, and ionospheric activity
- Hemisphere GNSS proprietary
- With future firmware upgrade and activation
- CMR and CMR+ do not cover proprietary messages outside of the typical

**Communications** 

Ports: 2 x full-duplex

(1 x 3.3V CMOS, 1 x 3.3V CMOS with

flow control)

1 x USB Host/Device 1 x Ethernet 10/100Mbps 2 x CAN (NMEA2000, ISO 11783)

Interface Level: 3.3V CMOS 4800 - 115200 **Baud Rates:** 

Correction I/O Protocol: Hemisphere GNSS proprietary ROX

format, RTCM v2.3, RTCM v3.2,

CMR<sup>5</sup>, CMR+<sup>5</sup> NMEA 0183, Crescent binary Data I/O Protocol: 1 PPS, CMOS, active high, rising **Timing Output:** edge sync,  $10 \text{ k}\Omega$ , 10 pF load CMOS, active low, falling edge **Event Marker Input:** 

sync,  $10 \text{ k}\Omega$ , 10 pF load

Power

Input Voltage: 3.3 VDC +/- 5%

< 2.5 W all signals + L-band Power Consumption: 757 mA all signals + L-band **Current Consumption:** Antenna Voltage: 5 VDC maximum

Antenna Short Circuit **Protection:** 

**Antenna Gain Input** 

Range:

10 to 40 dB

**Environmental** 

Operating Temperature: Storage Temperature:

**Humidity**:

-40°C to +85°C (-40°F to +185°F) -40°C to +85°C (-40°F to +185°F) 95% non-condensing (when in an

enclosure)

**Mechanical Shock:** EP455 Section 5.14.1

Operational (when mounted in an enclosure with screw mounting

holes utilized)

Vibration: EP455 Section 5.15.1 Random EMC: CE (IEC 60945 Emissions and

Immunity)

FCC Part 15, Subpart B

CISPR 22

Mechanical

71 L x 45 W x 10 H (mm) 2.8 L x 1.8 W x 0.4 (in) **Dimensions:** 

24 g (0.85 oz) Weight:

Status Indications (LED): Power, Primary and Secondary

GNSS lock, Differential lock, DGNSS

position, Heading

Power/Data Connector:

2 x 14-pin male header **Antenna Connectors:** MMCX, female, straight

**Aiding Devices** 

Gyro:

Provides smooth and fast heading reacquisition. During loss of GNSS signals heading stability is degraded by < 1° per minute for up to 3

minutes.

**Tilt Sensors:** Provide pitch, roll data and assist in

fast start-up and reacquisition of

heading solution



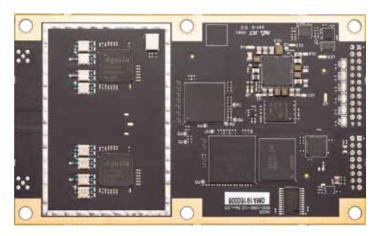
#### **Hemisphere GNSS**

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# **V**atlas

Develop sophisticated machine control and navigation solutions in a world full of complex dynamic environments. The Vega 40 is one of our most advanced GNSS heading and positioning boards.

The Vega 40 uses dual antenna ports to create a series of additional capabilities; including fast, high-accuracy heading over short baselines, RTK positioning, onboard Atlas L-band, RTK-enabled heave, low-power consumption, and precise timing.

#### **Scalable Solutions**

With the Vega 40, positioning is scalable and field upgradeable with all Hemisphere software and service options. Use the same centimeter-level accuracy in either single frequency mode, or employ the full performance and fast RTK initialization times over long distances with multi-frequency multi-constellation GNSS signals. High-accuracy L-band positioning from meter to sub-decimeter levels available via Atlas correction service.

#### **Ease of Migration**

Leverage the industry standard form factor for easy upgradeability from other manufacturers' modules.

- Extremely accurate heading with long baselines
- Multi-frequency position, dual-frequency heading supporting GPS, GLONASS, BeiDou, Galileo, QZSS, IRNSS, and L-band
- Atlas® L-band capable to 4 cm RMS
- Athena™ GNSS engine providing best-in-class RTK performance
- Excellent coasting performance
- 5 cm RMS RTK-enabled heave accuracy
- Strong multipath mitigation and interference rejection
- New multi-axis gyro and tilt sensor for reliable coverage during short GNSS outages

Receiver Type: Multi-Frequency GPS, GLONASS,

BeiDou, Galileo, QZSS, IRNSS and

**Atlas** 

Signals Received: GPS L1CA/L1P/L1C/L2P/L2C/L5

GLONASS G1/G2/G3, P1/P2 BeiDou B1i/B2i/B3i/B10C/B2A/B2B/

**ACEBOC** 

GALILEO E1BC/E5a/E5b/E6BC/

**ALTBOC** 

QZSS L1CA/L2C/L5/L1C/LEX

IRNSS L5 Atlas 1,100+-142 dBm

**GPS Sensitivity: SBAS Tracking:** 3-channel, parallel tracking **Update Rate:** 10 Hz standard, 1 Hz or 20 Hz optional (with activation)

Timing (1 PPS)

Channels:

Accuracy: 20 ns

Rate of Turn: 100°/s maximum

Cold Start: 60 s typical (no almanac or RTC) Warm Start: 30 s typical (almanac and RTC) **Hot Start:** 10 s typical (almanac, RTC and

position)

**Heading Fix:** 10 s typical (Hot Start)

Antenna Input

Atlas Basic: 1,3

Impedance:

1,850 mph (999 kts) Maximum Speed: Maximum Altitude: 18,288 m (60,000 ft)

Accuracy

Positioning: RMS (67%) 2DRMS (95%) Autonomous, no SA: 1 1.2 m 2.5 m SBAS: 1 0.3 m 0.6 m Atlas H10: 1,3 0.04 m  $0.08 \, \text{m}$ Atlas H30: 1,3  $0.15 \, \text{m}$  $0.3 \, \mathrm{m}$ 

 $0.50 \, \text{m}$ RTK: 1 8 mm + 1 ppm 15 mm + 2 ppm

Heading (RMS): 0.16° rms @ 0.5 m antenna

separation

0.08° rms @ 1.0 m antenna

1.0 m

separation

0.04° rms @ 2.0 m antenna

separation

0.02° rms @ 5.0 m antenna

separation

Pitch/Roll (RMS): 0.5°

Heave (RMS): 1 30 cm rms (DGNSS), 5 cm rms (RTK)

**L-Band Receiver Specifications** 

Receiver Type: Single Channel 1525 to 1560 MHz Channels:

Sensitivity: -130 dBm **Channel Spacing:** 5.0 kHz

Satellite Selection: Manual and Automatic Reacquisition Time: 15 seconds (typical)

Depends on multipath environment, number of satellites in view, satellite geometry, and ionospheric activity

Depends on multipath environment, number of satellites in view, SBAS coverage. satellite geometry, and ionospheric activity

Hemisphere GNSS proprietary

With future firmware upgrade and activation

CMR and CMR+ do not cover proprietary messages outside of the typical standard

**Communications** 

Ports: 3 x full-duplex

(1 x 3.3V CMOS, 1 x 3.3V CMOS with flow control, 1 x RS-232 with flow

control)

1 x USB Host/Device 1 x Ethernet 10/100Mbps

2 x CAN (NMEA2000, ISO 11783)

1 x SPI 3.3V CMOS Interface Level: 4800 - 115200 **Baud Rates:** 

Correction I/O Protocol: Hemisphere GNSS proprietary ROX

format, RTCM v2.3, RTCM v3.2, CMR<sup>5</sup>, CMR+<sup>5</sup>

Data I/O Protocol: **Timing Output:** 

**Event Marker Input:** 

NMEA 0183, Crescent binary 1 PPS, CMOS, active high, rising edge sync, 10  $k\Omega,$  10 pF load CMOS, active low, falling edge

sync,  $10 \text{ k}\Omega$ , 10 pF load

**Power** 

Input Voltage: 3.3 VDC +/- 5% < 2.5 W all signals + L-band **Power Consumption:** 757 mA all signals + L-band **Current Consumption:** Antenna Voltage: 5 VDC maximum

Antenna Short Circuit **Protection:** 

Antenna Gain Input

Range:

10 to 40 dB

**Environmental** 

Operating Temperature:

-40°C to +85°C (-40°F to +185°F) -40°C to +85°C (-40°F to +185°F) Storage Temperature: **Humidity**: 95% non-condensing (when in an

Yes

**Mechanical Shock:** 

enclosure) EP455 Section 5.14.1

Operational (when mounted in an enclosure with screw mounting

holes utilized)

Vibration: EMC:

EP455 Section 5.15.1 Random CE (IEC 60945 Emissions and

Immunity) FCC Part 15, Subpart B

CISPR 22

Mechanical

100 L x 60 W x 10 H (mm) **Dimensions:**  $3.9 L \times 2.4 W \times 0.4$  (in)

Weight: 44 g (1.56 oz)
Status Indications (LED): Power, Primary and Secondary

GNSS lock, Differential lock, DGNSS

position, Heading

Power/Data Connector:

24-pin male header 2 mm pitch 16-pin male header 2 mm pitch

**Antenna Connectors:** 

MMCX, female, straight

**Aiding Devices** 

Gyro:

Provides smooth and fast heading reacquisition. During loss of GNSS signals heading stability is degraded by < 1° per minute for up to 3

**Tilt Sensors:** Provide pitch, roll data and assist in fast start-up and reacquisition of

heading solution



### **Hemisphere GNSS**

8515 E. Anderson Drive Scottsdale, AZ 85255, USA Phone: +1 (480) 348-6380 Toll-Free: +1 (855) 203-1770 Fax: +1 (480) 270-5070











The Vector VS1000 is Hemisphere GNSS' premiere multi-GNSS, multi-frequency receiver designed specifically for the professional marine market. Providing precise heading, Athena RTK positioning, and full Atlas capability, its rugged design is compliant to 60529:2013 IP67 and IEC 60945:2002 8.7 standards.

The VS1000 supports antenna separations up to 10 meters, offering heading accuracy to 0.01 degrees RMS in addition to RTK position accuracy and full support for Hemisphere GNSS' Atlas worldwide L-band corrections.

- Athena™ RTK and Atlas® L-band capable
- Extremely accurate heading (to 0.01° RMS)
- Multi-frequency GPS/GLONASS/BeiDou/Galileo
- Purpose-built for the most challenging environments
- Supports Ethernet, CAN, Serial, USB, Bluetooth, and Wi-Fi
- Powerful WebUI accessed via Wi-Fi plus a 128x64 display and 10 multi-color LEDs

Vector GNSS RTK Receiver **Receiver Type:** 

Signals Received: GPS, GLONASS, BeiDou, Galileo, & Atlas 3

Channels: 1059 **GPS Sensitivity:** -142 dBm

**SBAS Tracking:** 2-channel, parallel tracking **Update Rate:** 10 Hz standard, 20 Hz optional

Timing (1PPS)

Accuracy: 20 ns

Rate of Turn: 100°/s maximum

Cold Start: 60 s (no almanac or RTC) Warm Start: 30 s typical (almanac and RTC)

**Hot Start:** 10 s typical (almanac, RTC and position)

10 s typical (valid position) **Heading Fix:** 

**Antenna Input** 

Impedance: 50 Ω

Maximum Speed: 1,850 mph (999 kts)

Maximum

Altitude: 18,288 m (60,000 ft)

**Differential** 

**Options:** SBAS, Atlas (L-band), RTK

Accuracy

Positioning: RMS (67%) 2DRMS (95%)

Single Point: 1 2.4 m SBAS: 2 0.6 m

Atlas H10: 6 0.08 m 0.16 m

Atlas H30: 6 0.3 m Atlas Basic: 6  $0.5 \, \mathrm{m}$ 

**RTK:** 1, 3 8 mm + 1 ppm 15 mm + 2 ppm Heading (RMS): 0.2° @ 0.5 m antenna separation 0.1° @ 1.0 m antenna separation

0.05° @ 2.0 m antenna separation 0.02° @ 5.0 m antenna separation 0.01° @ 10.0 m antenna separation

Pitch/Roll (RMS):

Heave (RMS): 30 cm (DGPS) 1,10 cm (Atlas) 1,6,

5 cm (RTK) 1,6

**L-Band Receiver Specifications** 

Channels: 1525 to 1560 MHz

Sensitivity: -130 dBm Channel Spacing: 5 kHz

Satellite Selection: Manual or Automatic

Reacquisition

Time: 15 sec (typical)

Depends on multipath environment, number of satellites in view, satellite geometry, no SA, and ionospheric activity
Depends on multipath environment, number of satellites in view, WAAS coverage and satellite geometry
Depends on multipath environment, number of satellites in view, satellite geometry, baseline length (for differential services), and ionospheric activity
Based on a 40 second time constant
Hemisphere GNSS proprietary
Requires a Hemisphere GNSS subscription
CMR and CMR+ do not cover proprietary messages outside of the typical standard

3.

**Communications** 

1x CAN, 1x Ethernet, 1x USB, 1x 12-pin

multi-purpose (RS232, RS422, CAN, 1PPS,

Event Marker)

4800 - 115200 **Baud Rates:** 

Radio Interfaces: Bluetooth 2.0 (Class 2), Wi-Fi 2.4 GHz

Correction I/O

Protocol: Hemisphere GNSS proprietary ROX

format, RTCM v2.3, RTCM v3.2, CMR7,

CMR+7

Data I/O Protocol: NMEA 0183, Hemisphere GNSS binary

**Timing Output: Event Marker** 

1PPS (CMOS, rising edge sync)

Open drain, falling edge sync,  $10 \text{ k}\Omega$ , 10

pF load

**Environmental** 

Operating

Input:

Temperature: -40°C to +70°C (-40°F to +158°F)

Storage

Temperature:  $-40^{\circ}$ C to + 85°C (-40°F to + 185°F)

**Humidity:** 95% non-condensing ISO 60529:2013 for IPx6/IPx7 **Enclosure:** 

Vibration: IEC 60945:2002 Section 8.7 Vibration EMC: IEC 60945:2002, EN 301 489-1 V2.1.1,

EN 301 489-5 V2.1.1, EN 301 489-19 V2.1.0,

EN 303 413 V1.1.1

Mechanical

**Dimensions:** 

No Plate: 23.2 L x 16.5 W x 7.9 H (cm)

9.1 L x 6.5 W x 3.1 H (in)

With Plate: 23.2 L x 21.4 W x 8.3 H (cm)

9.1 L x 8.4 W x 3.3 H (in)

Display: 128 x 64 Resolution Weight: 1.7 kg (3.8 lb)

**Status Indications** 

(LED): Power, Primary Antenna, Secondary

Antenna, Heading, Quality, Atlas, Bluetooth, Wi-Fi, CAN, Ethernet

Power/Data

Connector: M12 CAN/Power, 12-pin multi-purpose,

RJ45, USB

**Antenna** 

BT/Wi-Fi Connectors:

**Aiding Devices** 

Gyro:

Provides fast reacquisition and reliable heading for short periods when loss

of GNSS has occurred

**Tilt Sensors:** Provide pitch, roll data and assist in fast

start-up and reacquisition of heading

solution



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Experience the Vector™ VS330 with our powerful Athena GNSS core engine technology. The Vector VS330 supports precise marine, dynamic positioning, and land applications that require RTK positioning and precise heading performance.

The Vector V\$330 use all of the innovations in Hemisphere GNSS' Eclipse™ Vector technology. Our optimized Eclipse Vector technology brings a series of new features to the Vector V\$330 including heave, pitch, and roll output, and more robust positioning and heading performance.

The Vector VS330 receiver, with its display and user interface, can be conveniently installed near the operator. The two antennas are mounted separately with a user-determined separation to meet the desired heading accuracy. The fully-subscribed Vector VS330 uses Atlas L-band, Beacon, and SBAS for differential positioning. Our firmware allows the VS330 to transition smoothly between DGNSS systems.

- Athena™ RTK, Atlas® L-band, Beacon and SBAS capable
- Extremely accurate heading with baselines up 50 m
- Multi-frequency GPS/GLONASS/BeiDou RTK capable
- Automatic antenna baseline survey
- Maintain heading and position lock when more of the sky is blocked
- Runs Athena core GNSS engine offering improved initialization times, robustness in difficult environments, performance over long baselines and under scintillation
- Integrated gyro and tilt sensors help deliver fast start-up times and provide heading updates during temporary loss of satellites

Vector GNSS L1/L2 RTK Receiver Receiver Type: Signals Received: GPS, GLONASS, BeiDou, and Atlas

Channels: 502 **GPS Sensitivity:** -142 dBm

**SBAS Tracking:** 3-channel, parallel tracking Update Rate: 10 Hz standard, 20 Hz optional

Timing (1 PPS)

Accuracy:

Rate of Turn: 100°/s maximum

Compass Safe

Distance: 30 cm (with enclosure) 5 **Cold Start:** 60 s (no almanac or RTC) Warm Start: 30 s typical (almanac and RTC)

10 s typical (almanac, RTC and position) **Hot Start:** 

**Heading Fix:** 10 s typical (valid position)

**Antenna Input** 

Impedance: 50 O

Maximum Speed: 1,850 mph (999 kts)

Maximum

Altitude: 18,288 m (60,000 ft)

Differential

**Options:** SBAS, Beacon, External RTCM, Atlas

L-band and Athena RTK

Accuracy

RMS (67%) 2DRMS (95%) Positioning:

Single Point: 1 2.4 m SBAS: 2  $0.6 \, \mathrm{m}$ 

Atlas H10: 6 0.08 m 0.16 m

Atlas H30: 6 0.3 m Atlas Basic: 6  $0.5 \, \mathrm{m}$ 

RTK: 1, 3 10 mm + 1 ppm 20 mm + 2 ppm Heading (RMS): 0.2° @ 0.5 m antenna separation 0.1° @ 1.0 m antenna separation 0.05° @ 2.0 m antenna separation

0.02° @ 5.0 m antenna separation 0.01° @ 10.0 m antenna separation

Pitch/Roll (RMS):

30 cm (DGPS) 5,10 cm (RTK) 1,3 Heave (RMS):

**Beacon Receiver Specifications** 

Channels: 2-channel, parallel tracking

Frequency Range: 283.5 to 325 kHz

Operating Modes: Manual, Automatic, and Database

Compliance:

**L-Band Receiver Specifications** 

Receiver Type: Single Channel 1530 to 1560 MHz Channels:

Sensitivity: -130 dBm Channel Spacing: 5 kHz

Satellite Selection: Manual or Automatic

Reacquisition

Time: 15 sec (typical)

Communications

Ports: 2 full-duplex RS232, 1 half-duplex RS422

> port 1 USB-A

**Baud Rates:** 4800 - 115200

Correction I/O

Protocol: Hemisphere GNSS proprietary ROX format,

RTCM v2.3, RTCM v3.2, CMR<sup>7</sup>, CMR+<sup>7</sup>

Data I/O Protocol: NMEA 0183, Hemisphere GNSS binary 6 **Timing Output:** 1 PPS (active high, rising edge sync, 10

 $k\Omega$ , 10 pF load)

**Power** 

Input Voltage: 8-36 VDC Power

Consumption: 5.3 W nominal (GPS L1/L2 + GLONASS L1/

7 W nominal (GPS L1/L2 + GLONASS L1/L2

+ BeiDou B1/B2 + L-band)

Current Consumption: 0.44 A nominal (GPS L1/L2 + GLONASS L1/

0.51 A nominal (GPS L1/L2 + GLONASS L1/

L2 + BeiDou B1/B2 + L-band)

**Power** Isolation: 500 V **Reverse Polarity Protection:** Yes

Antenna

Voltage: 5 VDC maximum 60mA

Antenna Short Circuit Protection: Yes Antenna Gain

Input Range: 10 to 40 dB

**Environmental** 

Operating Temperature:  $-30^{\circ}$ C to + 70°C (-22°F to + 158°F)

Storage

 $-40^{\circ}$ C to + 85°C (-40°F to + 185°F) Temperature: 95% non-condensing

**Humidity:** Mechanical Shock:

EP455 Section 5.14.1

Operational (when mounted in an enclosure with screw mounting holes

utilized) EP455

Vibration: Section 5.15.1 Random

CE (IEC 60945 Emissions and Immunity) FCC Part 15, Subpart B EMC:

CISPR22

**Enclosure:** IP66 (IEC 60529)

Mechanical

**Dimensions:** 20.2 L x 12.0 W x 7.5 H (cm) 8.0 L x 4.7 W x3.0 H (in)

1.1 kg (2.5 lbs.) Weight: Status Indications

(LED):

Power, Primary and Secondary GPS lock,

Differential lock, DGPS position, Heading, RTK lock, L-band DGNSS lock

Front panel soft switch

**Power Switch:** Power/Data

Power Connector: 9-pin ODU metal circular Power Connector: 2-pin ODU metal circular

**Data Connector:** DB9 (sealed)

**Antenna** 

**Aiding Devices** 

Connectors:

Gyro:

Provides heading smoothing with GNSS. Drift rate is 1° per minute in heading for periods up to 3 minute when loss of GNSS has occurred 4

2 TNC (female)

**Tilt Sensors:** Provide pitch, roll data, assist in fast start-

up and heading reacquisition

2. 3.

Depends on multipath environment, number of satellites in view, satellite geometry, no SA, and ionospheric activity.

Requires a subscription
Depends on multipath environment, number of satellites in view, satellite geometry, baseline length (for differential services), and ionospheric activity.

Based on a 40 second time constant
This is the minimum safe distance measured when the product is placed in the vicinity of the steering magnetic compass. The ISO 694 defines "vicinity" relative to the compass as within 5 m (16.4 ft)

Hemisphere GNSS proprietary CMR and CMR+ do not cover proprietary messages outside of the typical standard

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